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Towards all-order Laurent expansion of generalized hypergeometric functions around rational values of parameters

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Abstract

We prove the following theorems: 1) The Laurent expansions in ε of the Gauss hypergeometric functions ${}_2F_1(I_1 + a\varepsilon, I_2 + b\varepsilon; I_3 + \frac{p}{q} + c\varepsilon; z)$, ${}_2F_1(I_1 + \frac{p}{q} + a\varepsilon, I_2 + \frac{p}{q} + b\varepsilon; I_3 + \frac{p}{q} + c\varepsilon; z)$ and ${}_2F_1(I_1 + \frac{p}{q} + a\varepsilon, I_2 + b\varepsilon; I_3 + \frac{p}{q} + c\varepsilon; z)$, where I_1, I_2, I_3, p, q are arbitrary integers, a, b, c are arbitrary numbers and ε is an infinitesimal parameter, are expressible in terms of multiple polylogarithms of q -roots of unity with coefficients that are ratios of polynomials; 2) The Laurent expansion of the Gauss hypergeometric function ${}_2F_1(I_1 + \frac{p}{q} + a\varepsilon, I_2 + b\varepsilon; I_3 + c\varepsilon; z)$ is expressible in terms of multiple polylogarithms of q -roots of unity times powers of logarithm with coefficients that are ratios of polynomials; 3) The multiple inverse rational sums $\sum_{j=1}^{\infty} \frac{\Gamma(j)}{\Gamma(1+j-\frac{p}{q})} \frac{z^j}{j^c} S_{a_1}(j-1) \cdots S_{a_p}(j-1)$ and the multiple rational sums $\sum_{j=1}^{\infty} \frac{\Gamma(j+\frac{p}{q})}{\Gamma(1+j)} \frac{z^j}{j^c} S_{a_1}(j-1) \cdots S_{a_p}(j-1)$, where $S_a(j) = \sum_{k=1}^j \frac{1}{k^a}$ is a harmonic series and c is an arbitrary integer, are expressible in terms of multiple polylogarithms; 4) The generalized hypergeometric functions ${}_pF_{p-1}(\vec{A} + \vec{a}\varepsilon; \vec{B} + \vec{b}\varepsilon, \frac{p}{q} + B_{p-1}; z)$ and ${}_pF_{p-1}(\vec{A} + \vec{a}\varepsilon, \frac{p}{q} + A_p; \vec{B} + \vec{b}\varepsilon; z)$ are expressible in terms of multiple polylogarithms with coefficients that are ratios of polynomials.

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1 Introduction: Feynman diagrams and special functions

High-precision theoretical predictions for physics at the LHC and the ILC demand the inclusion of higher-order radiative corrections. The results of perturbative calculation are expressible in terms of Feynman integrals [1]. However, in order to obtain physical results, it is necessary to construct the Laurent expansions of Feynman diagrams about the integer value of the space-time dimension [2] (typically $d = 4 - 2\epsilon$). For the parametrization of the coefficients of such ϵ expansions, a lot of new functions have been introduced by physicists during the last few years [3,4,5,6]. Some of these new functions are also generated in a different branch of mathematics [7,8,9,10]. At present, it is unclear if there is some limitation on the types of functions generated by Feynman diagrams or if the “zoo” of new functions is an artifact of the techniques used. In particular, the statement that the results of such calculations can be written in terms of a restricted set of special functions will allow one to use a restricted set of programs for the numerical evaluation of physical results. Another application is related to the evaluation of so-called single-scale diagrams, where an explicit prediction of possible transcendental constants can be done [11].

The strategy of such a kind of analysis is well known in the theory of special functions and the analytical theory of differential equations [12]. As is well known, any Feynman diagram satisfies a system of linear differential or difference equations with polynomial coefficients [13,14,15,16,17]. In modern mathematical language, such a system can be associated with the Gelfand-Karpanov-Zelevinskii functions or D -modules [18]. So, any question regarding the zoo of special functions generated by the ϵ expansion of Feynman diagrams could be reduced to the problem of constructing Laurent expansions of D -modules (hypergeometric functions [19]) about certain values of their parameters. Unfortunately, a unique hypergeometric representation of Feynman diagrams besides the so-called α representation [1] does not exist. Using the latter representation, it has been shown recently that, for single-scale diagrams, i.e. diagrams where all kinematic variables are proportional to each other so that one of them can be factored out, all coefficients of the ϵ expansion can be understood, up to some normalisation factor, as periods in the Kontsevich-Zagier formulation [20]. Another useful representation, which is closely related to the corresponding property of generalized hypergeometric functions, is the Mellin-Barnes representation of Feynman diagrams [21]. Using the Mellin-Barnes representation, it is possible to write the result in each order of ϵ in terms of multiple sums, which sometimes can be expressed in terms of special functions [22]. Since the power of a propagator is integer in covariant gauge and any (irreducible) numerator is expressible in terms of an integral of the same topology with a shifted power, which is again integer [14,15], it is enough to only consider hypergeometric functions of several variables with integer values of parameters. (In general, the number of variables is equal to the number of kinematic invariants minus one.) Fortunately, when some of the kinematic invariants are proportional (or equal) to each other, the number of variables in the proper hypergeometric series can be reduced. But the price of this reduction is the appearance of rational values of parameters. All known exactly solvable cases [23,24,25,26,27] have

confirmed this observation. Typically, only integer and half-integer values of parameters are generated, and only recently inverse cubic values have been discovered [27].

Recently, there has been essential progress in understanding what type of functions are generated by the ε expansion of hypergeometric functions. Besides the pioneering construction of the ε expansions of hypergeometric functions [28] using harmonic series [29] or so-called multiple (inverse) binomial sums [30,31,32], there are now a few independent techniques for the construction of analytical coefficients in the ε expansions of hypergeometric functions about integer and half-integer values of parameters and the summing of multiple series [32,33,34,35,36,37,38,39,40,41]. However, the extension of these results to the case of rational values of parameters is still a mystery. There is just one publication [36] devoted to the analysis of ε expansions of hypergeometric functions about a special configuration of rational parameters, the so-called, “zero-balance” case. Specifically, two types of sums have been analyzed in Ref. [36], namely in Eqs. (51) and (62). To our knowledge, they correspond to the sums covered by our Theorems A and B below, respectively, in the case $c \geq 1$.

The aim of the present paper is to derive an algorithm for the construction of all-order ε expansions of generalized hypergeometric functions ${}_pF_{p-1}$ and multiple (inverse) rational sums. The present consideration is based on appropriate extensions of the generating-function approach [32,42,39] and the differential-equation technique [37,38,40] to the case of rational values of parameters.

In particular, we will prove the following theorems:

- **Theorem I:**

The all-order ε expansions of the Gauss hypergeometric functions

$${}_2F_1(I_1 + a\varepsilon, I_2 + b\varepsilon; I_3 + \frac{p}{q} + c\varepsilon; z), \quad (1a)$$

$${}_2F_1(I_1 + \frac{p}{q} + a\varepsilon, I_2 + b\varepsilon; I_3 + c\varepsilon; z), \quad (1b)$$

$${}_2F_1(I_1 + \frac{p}{q} + a\varepsilon, I_2 + b\varepsilon; I_3 + \frac{p}{q} + c\varepsilon; z), \quad (1c)$$

$${}_2F_1(I_1 + \frac{p}{q} + a\varepsilon, I_2 + \frac{p}{q} + b\varepsilon; I_3 + \frac{p}{q} + c\varepsilon; z), \quad (1d)$$

where $\{I_k\}$ are integers, a, b, c are arbitrary numbers, and ε is an arbitrarily small parameter, are expressible in terms of multiple polylogarithms (or multiple polylogarithms times powers of logarithm) with coefficients that are ratios of polynomials with complex coefficients.

- **Theorem A**

The multiple inverse rational sums

$$\sum_{j=1}^{\infty} \frac{\Gamma(j)\Gamma\left(1 - \frac{p}{q}\right)}{\Gamma\left(1 + j - \frac{p}{q}\right)} \frac{z^j}{j^c} S_{a_1}(j-1) \cdots S_{a_p}(j-1), \quad (2)$$

where $S_a(j)$ is a harmonic series, defined as $S_a(j) = \sum_{k=1}^j \frac{1}{k^a}$, and c is any integer, are expressible in terms of multiple polylogarithms with (i) complex coefficients if $c \geq$

1; and (ii) with coefficients that are ratios of polynomials with complex coefficients if $c \leq 0$.

- **Theorem B**

The multiple rational sums

$$\sum_{j=1}^{\infty} \frac{\Gamma\left(j + \frac{p}{q}\right)}{\Gamma(1+j)\Gamma\left(1 + \frac{p}{q}\right)} \frac{z^j}{j^c} S_{a_1}(j-1) \cdots S_{a_p}(j-1), \quad (3)$$

where $S_a(j)$ is a harmonic series, defined as $S_a(j) = \sum_{k=1}^j \frac{1}{k^a}$, and c is any integer, are expressible in terms of multiple polylogarithms times powers of logarithm with (i) complex coefficients if $c \geq 1$; and (ii) with coefficients that are ratios of polynomials with complex coefficients if $c \leq 0$.

- **Theorem C**

The all-order ε expansion of the generalized hypergeometric functions

$${}_pF_{p-1} \left(\vec{A} + \vec{a}\varepsilon, \frac{p}{q} + I_2; \vec{B} + \vec{b}\varepsilon; z \right), \quad (4a)$$

$${}_pF_{p-1} \left(\vec{A} + \vec{a}\varepsilon; \vec{B} + \vec{b}\varepsilon, \frac{p}{q} + I_1; z \right), \quad (4b)$$

where \vec{A}, \vec{B} are lists of integers and I_1, I_2 are integers, are expressible in terms of multiple polylogarithms (or multiple polylogarithms times powers of logarithms) with coefficients that are ratios of polynomials with complex coefficients.

This paper is organized as follows. In Section 2, we will prove **Theorem I**. In Section 3, we will present an analysis of multiple (inverse) rational sums and prove **Theorem A** and **Theorem B**. In Section 4, the results of **Theorem A** and **Theorem B** will be applied to hypergeometric functions to prove **Theorem C**. In Section 5, we will demonstrate that, for physically interesting kinematics, the two-loop sunset diagrams are expressible in terms of generalized hypergeometric functions with quarter values of parameters. Appendices A and B contain some basic information about multiple polylogarithms, which are a particular class of hyperlogarithms, and the iterative solution of systems of differential equations.

2 Gauss hypergeometric function: notations

The Gauss hypergeometric function [43] $\omega(z) \equiv {}_2F_1(a, b; c; z)$ can be defined as the solution of a second-order differential equation of Fuchsian class [12] with three regular singular points at $z = 0, 1, \infty$, as

$$\frac{d}{dz} \left(z \frac{d}{dz} + c - 1 \right) \omega(z) = \left(z \frac{d}{dz} + a \right) \left(z \frac{d}{dz} + b \right) \omega(z), \quad (5)$$

and admits the series representation about $z = 0$,

$${}_2F_1(a, b; c; z) = \sum_{k=0}^{\infty} \frac{(a)_k (b)_k}{(c)_k} \frac{z^k}{k!}, \quad (6)$$

where $(a)_k = \Gamma(a + k)/\Gamma(a)$ is the Pochhammer symbol. It is the only solution analytic at $z = 0$ and with value 1 there.

It is well known that, between any three Gauss hypergeometric functions with the same argument z and parameters a, b, c differing by integers, there is an algebraic relation with polynomial coefficients [44], namely

$$\begin{aligned} &P_1(a, b, c, z) {}_2F_1(a + m_1, b + n_1; c + k_1; z) + P_2(a, b, c, z) {}_2F_1(a + m_2, b + n_2; c + k_2; z) \\ &+ P_3(a, b, c, z) {}_2F_1(a + m_3, b + n_3; c + k_3; z) = 0, \end{aligned} \quad (7)$$

where $m_j, n_j, k_j \in \mathbb{Z}$ ($j = 1, 2, 3$). Taking $m_3 = n_3 = k_3 = 0$ and $m_2 = n_2 = k_2 = 1$, we obtain, for example, by using the algorithm described in Ref. [45],

$$P(a, b, c, z) {}_2F_1(a + m_1, b + n_1; c + k_1; z) = \left[Q_1(a, b, c, z) \frac{d}{dz} + Q_2(a, b, c, z) \right] {}_2F_1(a, b; c; z), \quad (8)$$

where a, b, c , are any fixed numbers and P, Q_1, Q_2 are polynomial in the parameters a, b, c and the argument z . We call the functions of r.h.s. of Eq. (8) basis functions and their first derivatives. Consequently, in order to prove **Theorem A**, all-order ε expansions have to be constructed for basis hypergeometric functions.

2.1 Differential equation approach for construction of ε expansion

2.1.1 Gauss hypergeometric functions

Let us consider as the basis the Gauss hypergeometric function with the following set of parameters: $\omega(z) = {}_2F_1(\frac{p_1}{q_1} + a_1\varepsilon, \frac{p_2}{q_2} + a_2\varepsilon; 1 - \frac{p_3}{q_3} + c\varepsilon; z)$. It is the solution of the differential equation

$$\left(z \frac{d}{dz} + \frac{p_1}{q_1} + a_1\varepsilon \right) \left(z \frac{d}{dz} + \frac{p_2}{q_2} + a_2\varepsilon \right) \omega(z) = \frac{d}{dz} \left(z \frac{d}{dz} - \frac{p_3}{q_3} + c\varepsilon \right) \omega(z), \quad (9)$$

with boundary conditions $\omega(0) = 1$ and $z \frac{d}{dz} \omega(z) \Big|_{z=0} = 0$. Due to the analyticity of the Gauss hypergeometric function with respect to its parameters, Eq. (9) is valid in each order of ε , i.e. it holds for every coefficient function $\omega_k(z)$ in the expansion

$$\omega(z) = \sum_{k=0}^{\infty} \omega_k(z) \varepsilon^k. \quad (10)$$

The boundary conditions for the coefficient functions are

$$\omega_k(z) = 0 \quad (k < 0), \quad (11a)$$

$$\omega_k(0) = 0 \quad (k \geq 1), \quad (11b)$$

$$z \frac{d}{dz} \omega_k(z) \Big|_{z=0} = 0 \& \quad (k \geq 0). \quad (11c)$$

Equation (9) can be rewritten in terms of the coefficients functions ω_k as

$$\begin{aligned} & \left[(1-z) \frac{d}{dz} - \left(\frac{p_1}{q_1} + \frac{p_2}{q_2} \right) - \frac{1}{z} \frac{p_3}{q_3} \right] z \frac{d}{dz} \omega_k - \frac{p_1 p_2}{q_1 q_2} \omega_k \\ &= \left(a_1 + a_2 - \frac{c}{z} \right) z \frac{d}{dz} \omega_{k-1} + \left(a_1 \frac{p_2}{q_2} + a_2 \frac{p_1}{q_1} \right) \omega_{k-1} + a_1 a_2 \omega_{k-2}. \end{aligned} \quad (12)$$

The main idea of the approach developed in Refs. [38,40] is to find a new parametrization, through change of variable $z \rightarrow \xi(z)$, and to define new functions $\rho_k(\xi)$, related to the first derivative of the original functions $\omega_k(\xi)$, as

$$\rho_k(\xi) = \sum_j \Gamma_{kj}(\xi) \frac{d}{d\xi} \omega_j(\xi),$$

so that Eq. (12) can be rewritten as a system of linear differential equations of first order with rational coefficients, as

$$\frac{d}{d\xi} \omega_k(\xi) = \rho_k(\xi) \sum_j \frac{A_j}{\xi - \alpha_j}, \quad (13a)$$

$$\frac{d}{d\xi} \rho_k(\xi) = \rho_{k-1}(\xi) \sum_j \frac{B_j}{\xi - \beta_j} + \omega_{k-1}(\xi) \sum_j \frac{C_j}{\xi - \gamma_j} + \omega_{k-2}(\xi) \sum_j \frac{D_j}{\xi - \sigma_j}, \quad (13b)$$

where $A_j, B_j, C_j, D_j, \alpha_j, \beta_j, \gamma_j, \sigma_j \in \mathbb{C}$ ($j = 1, 2, \dots$). Then, the iterative solution of this system can be constructed as explained in Appendix B. Under the condition $\omega_0(z) = 1$ ($\rho_0(z) = 0$) this solution is expressible in terms of hyperlogarithms (see Appendix A) depending on the parameters $\alpha_j, \beta_j, \gamma_j, \sigma_j$, possibly times powers of logarithm. For example, the first iteration of Eq. (13b) produces

$$\rho_1(\xi) = \sum_j C_j [G_1(\gamma_j; \xi(z)) - G_1(\gamma_j; \xi(0))] \quad (\gamma_j \neq 0), \quad (14a)$$

$$\begin{aligned} \omega_1(\xi) = & \sum_{k,j} A_j C_k \{ [G_{1,1}(\alpha_j, \gamma_k; \xi(z)) - G_{1,1}(\alpha_j, \gamma_k; \xi(0))] \\ & - [G_1(\alpha_j; \xi(z)) G_1(\gamma_k; \xi(0)) - G_1(\alpha_j; \xi(0)) G_1(\gamma_k; \xi(0))] \} \quad (\gamma_k, \alpha_j \neq 0). \end{aligned} \quad (14b)$$

The main problem is to find a general algorithm for constructing this parametrization. We are not able to proof that we found a solution of this problem for all possible values of the parameters. But for some special set of parameters, the solution is found.

This algorithm can be applied to construct the all-order ε expansion of an arbitrary system of differential equations of the first order, in particular to the generalized hypergeometric function, as was done in Ref. [40].

2.1.2 One lower parameter is a rational number

Let us consider the particular case that the basis function is of the form

$$\omega(z) = {}_2F_1\left(a_1\varepsilon, a_2\varepsilon; 1 - \frac{p}{q} + c\varepsilon; z\right), \quad (15)$$

where we assume that $p, q > 0$ and $p < q$. The differential equation (9) takes the form

$$\left[(1-z)\frac{d}{dz} - \frac{1}{z}\frac{p}{q}\right]z\frac{d}{dz}\omega_k(z) = \left(a_1 + a_2 - \frac{c}{z}\right)z\frac{d}{dz}\omega_{k-1}(z) + a_1a_2\omega_{k-2}(z), \quad (16)$$

with the boundary condition

$$\omega_0(z) = 1. \quad (17)$$

Let us introduce a new variable ξ ,¹

$$\xi = \left(\frac{z}{z-1}\right)^{1/q}, \quad (18)$$

so that

$$\begin{aligned} z &= -\frac{\xi^q}{1-\xi^q}, & 1-z &= \frac{1}{1-\xi^q}, & \frac{1-z}{z} &= -\frac{1}{\xi^q}, \\ z\frac{d}{dz} &= \frac{1}{q}(1-\xi^q)\xi\frac{d}{d\xi}, & (1-z)\frac{d}{dz} - \frac{p}{q}z &= -\frac{1}{q}\left(\frac{1-\xi^q}{\xi^q}\right)\left(\xi\frac{d}{d\xi} - p\right). \end{aligned} \quad (19)$$

We introduce new functions $\rho_k(\xi)$ via the differential equation

$$z\frac{d}{dz}\omega_k(z)\Big|_{z=-\xi^q/(1-\xi^q)} \equiv \frac{1}{q}(1-\xi^q)\xi\frac{d}{d\xi}\omega_k(\xi) = \xi^p\rho_k(\xi). \quad (20)$$

The boundary conditions for the new coefficient functions are

$$\rho_k(0) = 0 \quad (k \geq 0). \quad (21)$$

Equation (16) can be rewritten in terms of new coefficients functions $\omega_k(\xi)$ and $\rho_k(\xi)$ as a system of two first-order differential equations, as

$$\frac{1}{q}\frac{d}{d\xi}\omega_k(\xi) = \frac{\xi^{p-1}}{1-\xi^q}\rho_k(\xi), \quad (22a)$$

$$-\frac{1}{q}\frac{d}{d\xi}\rho_k(\xi) = \left[(a_1 + a_2)\frac{\xi^{q-1}}{1-\xi^q} + \frac{c}{\xi}\right]\rho_{k-1}(\xi) + a_1a_2\frac{\xi^{q-p-1}}{1-\xi^q}\omega_{k-2}(\xi). \quad (22b)$$

¹The proposition to use the variable ξ for the evaluation of multiple inverse rational sums was made in Ref. [36]. For the particular value $q = 2$, the variable ξ is equivalent to the variable $y = \frac{1-\xi}{1+\xi}$ considered in Ref. [32], due to the invariance of the Remiddi-Vermaseren functions [3] with respect to the transformation $z \rightarrow \frac{1-z}{1+z}$. For $q = 2$, the variable ξ was also applied to the parametrization of Remiddi-Vermaseren functions in Ref. [46].

Now, we are in a position to proof the following result.

Lemma I:

The all-order ε expansion of the Gauss hypergeometric function ${}_2F_1\left(a_1\varepsilon, a_2\varepsilon; 1 - \frac{p}{q} + c\varepsilon; z\right)$ is expressible in terms of multiple polylogarithms with arguments that are powers of q -roots of unity and the variable ξ defined by Eq. (18).

This may be written symbolically as

$$\begin{aligned} {}_2F_1\left(a_1\varepsilon, a_2\varepsilon; 1 - \frac{p}{q} + c\varepsilon; z\right) = \\ 1 + a_1 a_2 \sum_{j=2}^{\infty} \varepsilon^j \sum_{\vec{J}, \vec{s}} v_{\vec{J}, \vec{s}} \text{Li}_{\vec{s}}\left(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} \xi\right) . \\ \begin{array}{c} 1 \leq \{j_m\} \leq q \\ \sum_{i=1}^r s_i = j \end{array} \end{aligned} \quad (23)$$

where $\vec{s} = \{s_1, \dots, s_m\}$ is a multi-index and $v_{\vec{J}, \vec{s}}$ are numerical coefficients ($v_{\vec{J}, \vec{s}} \in \mathbb{C}$). In particular, the following statement is valid:

Corollary I:

The analytical coefficient of ε^k in the expansion of ${}_2F_1\left(a_1\varepsilon, a_2\varepsilon; 1 - \frac{p}{q} + c\varepsilon; z\right)$ includes only multiple polylogarithms of weight k with numerical coefficients.

Proof:

Firstly, it is necessary to show that the system of equations (22) can be rewritten in the form of Eq. (13b). This follows from the standard decomposition relation

$$1 - \xi^q = \prod_{j=1}^q (1 - \lambda_q^j \xi) , \quad (24)$$

where we have introduced the primitive q -root of unity,

$$\lambda_q = \exp\left(i \frac{2\pi}{q}\right) . \quad (25)$$

Using the decomposition²

$$q \frac{x^{q-r-1}}{1-x^q} = - \sum_{j=1}^q \frac{\lambda_q^{jr}}{x - \frac{1}{\lambda_q^j}} , \quad (26)$$

² For completeness, we present a few particular cases:

$$q \frac{x^{q-1}}{1-x^q} = - \sum_{j=1}^q \frac{1}{x - \frac{1}{\lambda_q^j}} , \quad q \frac{x^{p-1}}{1-x^q} = - \sum_{j=1}^q \frac{\lambda_q^{-jp}}{x - \frac{1}{\lambda_q^j}} , \quad q \frac{x^{q-p-1}}{1-x^q} = - \sum_{j=1}^q \frac{\lambda_q^{jp}}{x - \frac{1}{\lambda_q^j}} .$$

where $0 \leq r \leq q - 1$, the system of equations (22) can be rewritten for an arbitrary value of p ($0 \leq p \leq q - 1$) in the desired form (13b), as

$$\frac{d}{d\xi} \omega_k(\xi) = - \sum_{j=1}^q \frac{\lambda_q^{-jp}}{\xi - \frac{1}{\lambda_q^j}} \rho_k(\xi) , \quad (27a)$$

$$\frac{d}{d\xi} \rho_k(\xi) = \left[(a_1 + a_2) \sum_{j=1}^q \frac{1}{\xi - \frac{1}{\lambda_q^j}} - \frac{cq}{\xi} \right] \rho_{k-1}(\xi) + a_1 a_2 \sum_{j=1}^q \frac{\lambda_q^{jp}}{\xi - \frac{1}{\lambda_q^j}} \omega_{k-2}(\xi) . \quad (27b)$$

The solution of system (27) has the form

$$\omega_k(\xi) = - \sum_{j=1}^q \lambda_q^{-jp} \int_0^\xi \frac{dt}{t - \frac{1}{\lambda_q^j}} \rho_k(t) , \quad (28a)$$

$$\rho_k(\xi) = \left[(a_1 + a_2) \sum_{j=1}^q \int_0^\xi \frac{dt}{t - \frac{1}{\lambda_q^j}} - cq \int_0^\xi \frac{dt}{t} \right] \rho_{k-1}(t) + a_1 a_2 \sum_{j=1}^q \lambda_q^{jp} \int_0^\xi \frac{dt}{t - \frac{1}{\lambda_q^j}} \omega_{k-2}(t) . \quad (28b)$$

The first coefficients of the ε expansion are zero,

$$\omega_1(\xi) = \rho_1(\xi) = 0 . \quad (29)$$

The first nontrivial terms correspond to $k = 2$,³

$$\frac{\rho_2(\xi)}{a_1 a_2} = - \sum_{j_1=1}^q \lambda_q^{j_1 p} \ln(1 - \lambda_q^{j_1} \xi) = - \sum_{j_1=1}^q \lambda_q^{j_1 p} \text{Li}_1(\lambda_q^{j_1} \xi) , \quad (30a)$$

$$\frac{\omega_2(\xi)}{a_1 a_2} = - \sum_{j_1, i_1=1}^q \lambda_q^{(j_1 - i_1)p} \text{Li}_{1,1}(\lambda_q^{j_1 - i_1}, \lambda_q^{i_1} \xi) . \quad (30b)$$

³This is equivalent to the following representation for the hypergeometric function:

$$\frac{z}{q-p} {}_2F_1\left(1, 1; 2 - \frac{p}{q}; z\right) = \left(\frac{z}{z-1}\right)^{\frac{p}{q}} \int_0^{\left(\frac{z}{z-1}\right)^{\frac{1}{q}}} \frac{t^{q-p-1}}{t^q - 1} dt ,$$

where $z \neq 1$.

Higher-order terms can be generated by iteration:

$$\frac{\rho_3(\xi)}{a_1 a_2} = (a_1 + a_2) \sum_{j_1, j_2=1}^q \lambda_q^{j_1 p} \text{Li}_{1,1} (\lambda_q^{j_1 - j_2}, \lambda_q^{j_2} \xi) + c q \sum_{j_1=1}^q \lambda_q^{j_1 p} \text{Li}_2 (\lambda_q^{j_1} \xi) , \quad (31\text{a})$$

$$\begin{aligned} \frac{\omega_3(\xi)}{a_1 a_2} &= (a_1 + a_2) \sum_{j_1, j_2, i_1=1}^q \lambda_q^{(j_1 - i_1)p} \text{Li}_{1,1,1} (\lambda_q^{j_1 - j_2}, \lambda_q^{j_2 - i_1}, \lambda_q^{i_1} \xi) \\ &\quad + c q \sum_{j_1, i_1=1}^q \lambda_q^{(j_1 - i_1)p} \text{Li}_{1,2} (\lambda_q^{j_1 - i_1}, \lambda_q^{i_1} \xi) , \end{aligned} \quad (31\text{b})$$

$$\begin{aligned} \frac{\rho_4(\xi)}{a_1 a_2} &= - \sum_{j_1, j_2, j_3=1}^q \lambda_q^{j_1 p} \left[(a_1 + a_2)^2 \text{Li}_{1,1,1} (\lambda_q^{j_1 - j_2}, \lambda_q^{j_2 - j_3}, \lambda_q^{j_3} \xi) + c^2 q^2 \text{Li}_3 (\lambda_q^{j_1} \xi) \right] \\ &\quad - c q (a_1 + a_2) \sum_{j_1, j_2=1}^q \lambda_q^{j_1 p} \left\{ \text{Li}_{1,2} (\lambda_q^{j_1 - j_2}, \lambda_q^{j_2} \xi) + \text{Li}_{2,1} (\lambda_q^{j_1 - j_2}, \lambda_q^{j_2} \xi) \right\} \\ &\quad + a_1 a_2 \sum_{j_1, j_2, i_1=1}^q \lambda_q^{(j_1 + j_2 - i_1)p} \text{Li}_{1,1,1} (\lambda_q^{j_1 - i_1}, \lambda_q^{i_1 - j_2}, \lambda_q^{j_2} \xi) . \end{aligned} \quad (31\text{c})$$

Let us apply the mathematical induction. Let us assume that **Lemma I** is valid up to order j , so that

$$\omega_j(\xi) = \sum_{\vec{J}, \vec{s}} v_{\vec{J}, \vec{s}} \text{Li}_{\vec{s}} (\lambda_q^{j_1 - j_2}, \lambda_q^{j_2 - j_3}, \dots, \lambda_q^{j_{r-1} - j_r}, \lambda_q^{j_r} \xi) , \quad (32\text{a})$$

$$\begin{aligned} 1 \leq \{j_m\} &\leq q \\ \sum_{i=1}^r s_i &= j \end{aligned}$$

$$\rho_j(\xi) = \sum_{\vec{k}, \vec{l}} u_{\vec{l}, \vec{k}} \text{Li}_{\vec{k}} (\lambda_q^{l_1 - l_2}, \lambda_q^{l_2 - l_3}, \dots, \lambda_q^{l_{m-1} - l_m}, \lambda_q^{l_m} \xi) . \quad (32\text{b})$$

$$\begin{aligned} 1 \leq \{l_a\} &\leq q \\ \sum_{i=1}^m k_i &= j - 1 \end{aligned}$$

Substituting these expressions in Eq. (28b), we obtain

$$\begin{aligned}
\rho_{j+1}(\xi) &= -(a_1 + a_2) \sum_{a=1}^q \sum_{\substack{\vec{l}, \vec{k} \\ 1 \leq \{l_a\} \leq q \\ \sum_{i=1}^m k_i = j-1}} u_{\vec{l}, \vec{k}} \text{Li}_{1, \vec{k}} (\lambda_q^{l_1-l_2}, \dots, \lambda_q^{l_{m-1}-l_m}, \lambda_q^{j_m-j_a}, \lambda_q^{j_a} \xi) \\
&\quad - cq \sum_{\substack{\vec{l}, \vec{k} \\ 1 \leq \{l_a\} \leq q \\ \sum_{i=1}^m k_i = j-1}} u_{\vec{l}, \vec{k}} \text{Li}_{1+k_1, k_2, \dots} (\lambda_q^{l_1-l_2}, \dots, \lambda_q^{l_{m-1}-l_m}, \lambda_q^{j_m} \xi) \\
&\quad - a_1 a_2 \sum_{a=1}^q \lambda_q^{ap} \sum_{\substack{\vec{J}, \vec{s} \\ 1 \leq \{j_m\} \leq q \\ \sum_{i=1}^r s_i = j-1}} v_{\vec{J}, \vec{s}} \text{Li}_{1, \vec{s}} (\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r-j_a}, \lambda_q^{j_a} \xi) \\
&\equiv \sum_{\substack{\vec{J}, \vec{k} \\ 1 \leq \{l_a\} \leq q \\ \sum_{i=1}^m k_i = j}} \tilde{v}_{\vec{J}, \vec{k}} \text{Li}_{\vec{k}} (\lambda_q^{l_1-l_2}, \lambda_q^{l_2-l_3}, \dots, \lambda_q^{l_{m-1}-l_m}, \lambda_q^{j_m} \xi) , \tag{33}
\end{aligned}$$

and the next iteration produces

$$\begin{aligned}
\omega_{j+1}(\xi) &= - \sum_{a=1}^q \lambda_q^{-ap} \sum_{\substack{\vec{J}, \vec{s} \\ 1 \leq \{j_m\} \leq q \\ \sum_{i=1}^r k_i = j}} \tilde{v}_{\vec{J}, \vec{k}} \text{Li}_{1, \vec{k}} (\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r-j_a}, \lambda_q^{j_a} \xi) \\
&= \sum_{\substack{\vec{J}, \vec{s} \\ 1 \leq \{j_m\} \leq q \\ \sum_{i=1}^r s_i = j+1}} u_{\vec{J}, \vec{s}} \text{Li}_{1, \vec{s}} (\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r-j_{r+1}}, \lambda_q^{j_{r+1}} \xi) . \tag{34}
\end{aligned}$$

In this way, **Lemma I** is seen to be valid also at order $j+1$. Consequently, **Lemma I** is valid at arbitrary order.

Remark I:

There is another possible parametrization of Eq. (22). It is possible to consider the variable $\tilde{\xi} = 1/\xi$ instead of the variable ξ , so that

$$z = \frac{1}{1 - \tilde{\xi}^q} . \tag{35}$$

In terms of the new variable, Eq. (22) takes the form

$$\frac{1}{q} \frac{d}{d\tilde{\xi}} \tilde{\omega}_k(\tilde{\xi}) = \frac{\tilde{\xi}^{q-p-1}}{1 - \tilde{\xi}^q} \tilde{\rho}_k(\tilde{\xi}), \quad (36a)$$

$$-\frac{1}{q} \frac{d}{d\tilde{\xi}} \tilde{\rho}_k(\tilde{\xi}) = \left[(a_1 + a_2) \frac{\tilde{\xi}^{q-1}}{1 - \tilde{\xi}^q} + \frac{a_1 + a_2 - c}{\tilde{\xi}} \right] \tilde{\rho}_{k-1}(\tilde{\xi}) + a_1 a_2 \frac{\tilde{\xi}^{p-1}}{1 - \tilde{\xi}^q} \tilde{\omega}_{k-2}(\tilde{\xi}). \quad (36b)$$

The result of **Lemma I** does not change under such a reparametrization.

Remark II:

In the region $0 < z < 1$, the variable ξ is purely imaginary. It is then possible to introduce a new variable, $y = (1 - \xi)/(1 + \xi)$, which parameterizes the complex unit circle, so that $y = \exp(i\theta)$. The trigonometric parametrization can be derived by putting $z = \tan^q(\theta/2)/[1 + \tan^q(\theta/2)]$, and, for $q = 2$, it coincides with the parametrization of Ref. [32]. In this region, the multiple polylogarithms can be split into real and imaginary parts as in the case of the classical polylogarithms [47]. A few particular values of multiple polylogarithms, for $q = 2, 6$ and $z = 1/4$ ($\theta = \pi/3$), were evaluated in Refs. [32,34,48,49].

2.1.3 One upper parameter is a rational number

Let us analyze a Gauss hypergeometric function where one of the upper parameters is a rational number,

$$\omega(z) = {}_2F_1\left(\frac{p}{q} + a_1\varepsilon, a_2\varepsilon; 1 + c\varepsilon; z\right). \quad (37)$$

Using the algebraic relation between Gauss hypergeometric functions of arguments z and $1 - 1/z$,

$$\begin{aligned} {}_2F_1\left(\begin{array}{c} a, b \\ c \end{array} \middle| z\right) &= \frac{1}{z^a} \frac{\Gamma(c)\Gamma(c-a-b)}{\Gamma(c-a)\Gamma(c-b)} {}_2F_1\left(\begin{array}{c} a, 1+a-c \\ 1+a+b-c \end{array} \middle| 1-\frac{1}{z}\right) \\ &+ z^{a-c}(1-z)^{c-a-b} \frac{\Gamma(c)\Gamma(a+b-c)}{\Gamma(a)\Gamma(b)} {}_2F_1\left(\begin{array}{c} c-a, 1-a \\ 1+c-a-b \end{array} \middle| 1-\frac{1}{z}\right), \end{aligned} \quad (38)$$

and putting

$$a = a_2\varepsilon, \quad b = \frac{p}{q} + a_1\varepsilon, \quad c = 1 + c\varepsilon,$$

we obtain

$$\begin{aligned}
& {}_2F_1 \left(\begin{matrix} \frac{p}{q} + a_1\varepsilon, a_2\varepsilon \\ 1+c\varepsilon \end{matrix} \middle| z \right) = \\
& \frac{1}{z^{a_2\varepsilon}} \frac{\Gamma(1+c\varepsilon)\Gamma\left(1-\frac{p}{q}+(c-a_1-a_2)\varepsilon\right)}{\Gamma(1+(c-a_2)\varepsilon)\Gamma\left(1-\frac{p}{q}+(c-a_1)\varepsilon\right)} {}_2F_1 \left(\begin{matrix} (a_2-c)\varepsilon, a_2\varepsilon \\ \frac{p}{q}+(a_1+a_2-c)\varepsilon \end{matrix} \middle| 1-\frac{1}{z} \right) \\
& + \frac{(1-z)^{1-p/q+(c-a_1-a_2)\varepsilon} z^{(a_2-c)\varepsilon}}{(c-a_2)\varepsilon} \frac{\Gamma(1+c\varepsilon)\Gamma\left(\frac{p}{q}+(a_1+a_2-c)\varepsilon\right)}{\Gamma(1+a_2\varepsilon)\Gamma\left(\frac{p}{q}+a_1\varepsilon\right)} \\
& \times z \frac{d}{dz} {}_2F_1 \left(\begin{matrix} (c-a_2)\varepsilon, -a_2\varepsilon \\ 1-\frac{p}{q}+(c-a_1-a_2)\varepsilon \end{matrix} \middle| 1-\frac{1}{z} \right). \tag{39}
\end{aligned}$$

According to **Lemma I**, the Gauss hypergeometric functions on the r.h.s. of Eq. (39) are expressible in terms of multiple polylogarithms with arguments being powers of q -roots of unity and the variable τ defined as

$$\tau = \xi|_{z \rightarrow 1-\frac{1}{z}} = (1-z)^{\frac{1}{q}}. \tag{40}$$

In terms of this variable, we have

$$z^{a\varepsilon} = \prod_{j=1}^q (1 - \lambda_q^j \tau)^{a\varepsilon}, \quad (1-z)^{b\varepsilon} = \tau^{bq\varepsilon}. \tag{41}$$

The ε expansion of the first factor only produces powers of the logarithms $\ln(1 - \lambda_q^j \tau)$, whereas the ε expansion of the second factor generates powers of $\ln \tau$. In this way, we obtain

Lemma II:

The all-order ε expansion of the Gauss hypergeometric function ${}_2F_1 \left(\begin{matrix} \frac{p}{q} + a_1\varepsilon, a_2\varepsilon \\ 1+c\varepsilon \end{matrix} \middle| z \right)$ is expressible in terms of multiple polylogarithms times powers of $\ln \tau$, where the variable τ is defined by Eq. (40), whereby the arguments of the multiple polylogarithms are powers of q -roots of unity times τ .

Remark III

For $a_1 = 0$, all powers of logarithms are factorized, so that the result is expressible just in terms of multiple polylogarithms.

2.1.4 One upper and one lower parameter are equal rational numbers (zero-balance case)

In a similar manner, we can study the so-called zero-balance case [36]. Using the transformation $z \rightarrow -z/(1-z)$,

$${}_2F_1 \left(\begin{matrix} a, b \\ c \end{matrix} \middle| z \right) = \frac{1}{(1-z)^a} {}_2F_1 \left(\begin{matrix} a, c-b \\ c \end{matrix} \middle| -\frac{z}{1-z} \right), \tag{42}$$

and putting

$$a = a_1 \varepsilon, \quad b = 1 - \frac{p}{q} + a_2 \varepsilon, \quad c = 1 - \frac{p}{q} + c \varepsilon,$$

we obtain

$${}_2F_1 \left(\begin{matrix} 1 - \frac{p}{q} + a_2 \varepsilon, a_1 \varepsilon \\ 1 - \frac{p}{q} + c \varepsilon \end{matrix} \middle| z \right) = (1 - z)^{-a_1 \varepsilon} {}_2F_1 \left(\begin{matrix} a_1 \varepsilon, (c - a_2) \varepsilon \\ 1 - \frac{p}{q} + c \varepsilon \end{matrix} \middle| -\frac{z}{1 - z} \right). \quad (43)$$

According to **Lemma I**, the Gauss hypergeometric function on the r.h.s. of Eq. (43) is expressible in terms of multiple polylogarithms with arguments being powers of q -roots of unity and the variable η defined as

$$\eta = \xi|_{z \rightarrow -\frac{z}{1-z}} = z^{\frac{1}{q}}, \quad (44)$$

in agreement with Ref. [36]. In terms of this variable, we have

$$(1 - z)^{b\varepsilon} \rightarrow \prod_{j=1}^q (1 - \lambda_q^j \eta)^{b\varepsilon}.$$

In this way, we obtain

Lemma III:

The all-order ε expansion of the Gauss hypergeometric function ${}_2F_1 \left(1 - \frac{p}{q} + a_1 \varepsilon, a_2 \varepsilon; 1 - \frac{p}{q} + c \varepsilon; z \right)$ is expressible in terms of multiple polylogarithms with arguments being powers of q -roots of unity times the variable η defined by Eq. (44).

2.1.5 All three parameters are equal and non-integer

In order to derive the ε expansion for a Gauss hypergeometric function with three rational numbers, the following relation can be applied:

$${}_2F_1 \left(\begin{matrix} a, b \\ c \end{matrix} \middle| z \right) = (1 - z)^{c-a-b} {}_2F_1 \left(\begin{matrix} c - a, c - b \\ c \end{matrix} \middle| z \right). \quad (45)$$

Putting

$$a = 1 - \frac{p}{q} + a \varepsilon, \quad b = 1 - \frac{p}{q} + b \varepsilon, \quad c = 1 - \frac{p}{q} + c \varepsilon,$$

we obtain

$${}_2F_1 \left(\begin{matrix} 1 - \frac{p}{q} + a \varepsilon, 1 - \frac{p}{q} + b \varepsilon \\ 1 - \frac{p}{q} + c \varepsilon \end{matrix} \middle| z \right) = \frac{1}{(1 - z)^{1-p/q-(c-a-b)\varepsilon}} {}_2F_1 \left(\begin{matrix} (c - a) \varepsilon, (c - b) \varepsilon \\ 1 - \frac{p}{q} + c \varepsilon \end{matrix} \middle| z \right). \quad (46)$$

The r.h.s. of Eq. (46) is expressible just in terms of multiple polylogarithms. In this way, we obtain

Lemma IV:

The all-order ε expansion of the Gauss hypergeometric function ${}_2F_1 \left(1 - \frac{p}{q} + a_1 \varepsilon, 1 - \frac{p}{q} + a_2 \varepsilon; 1 - \frac{p}{q} + c \varepsilon; z \right)$ is expressible in terms of multiple polylogarithms with arguments being powers of q -roots of unity times the variable ξ defined by Eq. (18).

2.2 The Laurent ε expansion of Gauss hypergeometric functions with rational values of parameters around $z = 1$

Let us construct the iterative solution of the differential equation (5) in the neighbourhood of the point $z = 1$. In accordance with the standard procedure [12,19], we introduce a new variable, $Z = 1 - z$, so that the the differential equation becomes

$$Z(1-Z)\frac{d^2\omega(Z)}{dZ^2} - [c - (a+b+1)(1-Z)]\frac{d\omega(Z)}{dZ} - ab\omega(Z) = 0 \quad (47)$$

and one of its solution is $\omega(Z) = {}_2F_1(a; b; 1+a+b-c; Z)$. Setting

$$a = a_1\varepsilon, \quad b = a_2\varepsilon, \quad c = 1 - \frac{p}{q} + c\varepsilon,$$

we rewrite Eq. (47) as

$$\frac{d}{dZ}\left(Z\frac{d}{dZ} - \left(1 - \frac{p}{q}\right) + (a_1 + a_2 - c)\varepsilon\right)\omega(Z) = \left(Z\frac{d}{dZ} + a_1\varepsilon\right)\left(Z\frac{d}{dZ} + a_2\varepsilon\right)\omega(Z). \quad (48)$$

Since the difference $1 - p/q$ can be written symbolically as r/q , where $r \leq q - 1$, Eq. (48) is equivalent to Eq. (16) with appropriate changes of variable and parameters,

$$(z, c, p) \longleftrightarrow (Z, a_1 + a_2 - c, q - p), \quad (49)$$

so that we can use the results of Section 2.1.2 with appropriate change of notations.

In particular, the solutions of the differential equations for the functions $\rho_i(Q)$ and $\omega_i(Q)$ can be written as

$$\omega_k(Q) = q \int_0^Q \frac{t^{q-p-1}}{1-t^q} \rho_k(t), \quad (50a)$$

$$\rho_k(Q) = -q \int_0^Q \left[(a_1 + a_2) \frac{t^{q-1}}{1-t^q} + \frac{a_1 + a_2 - c}{t} \right] \rho_{k-1}(t) - qa_1 a_2 \int_0^Q \frac{t^{p-1}}{1-t^q} \omega_{k-2}(t), \quad (50b)$$

where the new variable Q is defined as

$$Q = \left(\frac{Z}{Z-1}\right)^{\frac{1}{q}} \equiv \frac{1}{\xi}, \quad (51)$$

and ξ is defined by Eq. (18).

There is an explicit relation between the solution of the differential equation (5) in the neighbourhoods of the points $z = 0$ and $z = 1$ [19], which we write in the following form

$$\begin{aligned} {}_2F_1\left(\begin{matrix} a, b \\ c \end{matrix} \middle| z\right) &= \frac{\Gamma(c)\Gamma(c-a-b)}{\Gamma(c-a)\Gamma(c-b)} {}_2F_1\left(\begin{matrix} a, b \\ a+b-c+1 \end{matrix} \middle| 1-z\right) \\ &+ (1-z)^{c-a-b} z^{1-c} \frac{\Gamma(c)\Gamma(a+b-c)}{\Gamma(a)\Gamma(b)} {}_2F_1\left(\begin{matrix} 1-a, 1-b \\ c-a-b+1 \end{matrix} \middle| 1-z\right). \end{aligned} \quad (52)$$

For

$$a = a_1 \varepsilon, \quad b = a_2 \varepsilon, \quad c = 1 - \frac{p}{q} + c \varepsilon, \quad z = 1 - z,$$

we have

$$\begin{aligned} & {}_2F_1 \left(\begin{matrix} a_1 \varepsilon, a_2 \varepsilon \\ 1 - \frac{p}{q} + c \varepsilon \end{matrix} \middle| 1 - z \right) \\ &= \frac{\Gamma \left(1 - \frac{p}{q} + c \varepsilon \right) \Gamma \left(1 - \frac{p}{q} + (c - a_1 - a_2) \varepsilon \right)}{\Gamma \left(1 - \frac{p}{q} + (c - a_1) \varepsilon \right) \Gamma \left(1 - \frac{p}{q} + (c - a_2) \varepsilon \right)} {}_2F_1 \left(\begin{matrix} a_1 \varepsilon, a_2 \varepsilon \\ \frac{p}{q} + (a_1 + a_2 - c) \varepsilon \end{matrix} \middle| z \right) \\ &\quad - (1 - z)^{\frac{p}{q} - c \varepsilon} z^{-\frac{p}{q} + (c - a_1 - a_2) \varepsilon} \frac{\Gamma \left(1 - \frac{p}{q} + c \varepsilon \right) \Gamma \left(\frac{p}{q} + (a_1 + a_2 - c) \varepsilon \right)}{\Gamma(1 + a_1 \varepsilon) \Gamma(1 + a_2 \varepsilon)} \\ &\quad \times \left(z \frac{d}{dz} \right) {}_2F_1 \left(\begin{matrix} -a_1 \varepsilon, -a_2 \varepsilon \\ 1 - \frac{p}{q} + (c - a_1 - a_2) \varepsilon \end{matrix} \middle| z \right). \end{aligned} \quad (53)$$

The all-order ε expansion for the hypergeometric functions entering the r.h.s. of this relation is constructed in Section 2.1.2, the l.h.s. is done in this section. Consequently, both sides of relation (53) are expressible in terms of multiple polylogarithms depending on powers of q -roots of unity and the arguments ξ (r.h.s.) and $\frac{1}{\xi}$ (l.h.s.). The equality of the l.h.s. and r.h.s. of Eq. (53) in each order of ε generates algebraic relations between multiple polylogarithms.

A similar approach was applied in Refs. [37,50] to the connection problem of the formal Knizhnik-Zamolodchikov equation in order to derive linear relations between special values of multiple polylogarithms.

In the region $0 < z < 1$, the variable ξ is purely imaginary. It can then be rewritten in terms of the new variable $y = (1 - \xi)/(1 + \xi)$, where $y = \exp(i\theta)$. In such a parametrization, relation (53) is equivalent to algebraic relations between colour zeta values. The algebraic relations between particular values of multiple polylogarithms of lower depth and weight and particular values of q , specifying the root of unity, were analysed for $q = 2$ and $z = 1/4$ in Refs. [32,34,49] and for $q = 6$ and $z = 1/4$ in Ref. [48].

3 Multiple (inverse) rational sums

It is well known that there are three different ways to describe hypergeometric functions:

- (i) as an integral of the Euler or Mellin-Barnes type,
- (ii) by a series whose coefficients satisfy certain recurrence relations,
- (iii) as a solution of a system of differential or difference equations (holonomic approach).

For functions of a single variable, all of these representations are equivalent, but some properties of the function may be more evident in one representation than in another.

In Section 2.1, the third approach, the iterative solution of differential equations, was used to construct the all-order ε expansion of a Gauss hypergeometric function. Now, we wish to analyze the series generated by the ε expansion of a generalized hypergeometric function with one rational parameter. This was properly analyzed for the zero-balance case in Ref. [36] and for $q = 2$ in Ref. [39].

3.1 Gauss hypergeometric function as generating function of multiple (inverse) rational sums

The starting point of our consideration is the Taylor expansion of the Γ function. The proper expression may be extracted from Refs. [19,36] and reads

$$\begin{aligned} \ln \frac{\Gamma(k+1+\frac{p}{q}+j+z)}{\Gamma(k+1+\frac{p}{q}+j)} &= z\Psi\left(k+1+j+\frac{p}{q}\right) + \sum_{m=2}^{\infty} \frac{(-z)^m}{m} \sum_{r=0}^{\infty} \frac{1}{\left(r+k+1+\frac{p}{q}+j\right)^m} \\ &= \ln \frac{\Gamma(k+1+\frac{p}{q}+z)}{\Gamma(k+1+\frac{p}{q})} - \sum_{m=1}^{\infty} \frac{(-z)^m}{m} \sum_{r=1}^j \frac{1}{\left(r+k+\frac{p}{q}\right)^m} \end{aligned} \quad (54a)$$

$$= \ln \frac{\Gamma\left(1+\frac{p}{q}+z\right)}{\Gamma\left(1+\frac{p}{q}\right)} - \sum_{m=1}^{\infty} \frac{(-z)^m}{m} \sum_{r=1}^{j+k} \frac{1}{\left(r+\frac{p}{q}\right)^m}, \quad (54b)$$

where Ψ is the psi-function, $\Psi(z) = \frac{d}{dz} \ln \Gamma(z)$, k is an arbitrary non-negative integer, $k \geq 0$, and we have used the two auxiliary expressions

$$\begin{aligned} \Psi^{(m)}(z) &\equiv \left(\frac{d}{dz}\right)^m \Psi(z) = (-1)^{m+1} \Gamma(m+1) \sum_{p=0}^{\infty} \frac{1}{(z+p)^{m+1}}, \\ \Psi(1+z+n) - \Psi(1+z) &= \sum_{k=1}^n \frac{1}{k+z}. \end{aligned}$$

In particular, for $p = 0$, we have

$$\ln \frac{\Gamma(1+j+z)}{\Gamma(1+z)} = \ln \Gamma(1+j) - \sum_{m=1}^{\infty} \frac{(-z)^m}{m} S_m(j), \quad (55)$$

where $S_a(j)$ is the harmonic sum defined as $S_a(j) = \sum_{k=1}^j \frac{1}{k^a}$. Based on previous experience [32,34,45], we choose $\omega(z) = {}_2F_1(1+a_1\varepsilon, 1+a_2\varepsilon; 2-\frac{p}{q}+c\varepsilon; z)$ as the basis function, appearing on the r.h.s. of Eq.(8). Using representation (6) and expression (54) for each Γ function, we write the ε expansion of our basis function as a multiple series, as⁴

$${}_2F_1\left(\begin{matrix} 1+a_1\varepsilon, 1+a_2\varepsilon \\ 2-\frac{p}{q}+c\varepsilon \end{matrix} \middle| z\right) = \frac{1}{z} \left(1-\frac{p}{q}+c\varepsilon\right) \sum_{j=1}^{\infty} z^j \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1-\frac{p}{q}+j\right)} \Delta, \quad (56)$$

⁴The expansions of Γ functions about rational values of their parameters may be rewritten in terms of multiple Z and S sums (for details, see Ref. [36]).

where

$$\Delta = \exp \left[\sum_{k=1}^{\infty} \frac{(-\varepsilon)^k}{k} \left(-A_k S_k(j-1) + c^k S_k^{[q-p,q]}(j-1) \right) \right], \quad (57)$$

with $A_k = a_1^k + a_2^k$. Here,

$$S_k^{[p,q]}(j) = \sum_{r=1}^j \frac{1}{\left(r + \frac{p}{q}\right)^k}, \quad (58)$$

denotes the generalized multiple harmonic sum, which satisfies

$$S_k^{[p,q]}(j+1) = S_k^{[p,q]}(j) + \frac{1}{\left(1 + j + \frac{p}{q}\right)^k}. \quad (59)$$

The harmonic sum $S_a(j)$ is a special case of $S_k^{[p,q]}(j)$, for $p = 0$,

$$S_k(j) \equiv S_k^{[0,q]}(j).$$

In particular, the first few coefficients of the ε expansion read:

$$\begin{aligned} & \sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1+j-\frac{p}{q}\right)} \exp \left[\sum_{k=1}^{\infty} \frac{(-\varepsilon)^k}{k} \left(-A_k S_k(j-1) + c^k S_k^{[q-p,q]}(j-1) \right) \right] \\ &= \sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1+j-\frac{p}{q}\right)} \left\{ 1 + \varepsilon \left[A_1 S_1(j-1) - c S_1^{[q-p,q]}(j-1) \right] \right. \\ & \quad + \frac{1}{2} \varepsilon^2 \left[A_1^2 S_1^2(j-1) - A_2 S_2(j-1) - 2c A_1 S_1(j-1) S_1^{[q-p,q]}(j-1) \right. \\ & \quad \left. \left. + c^2 \left(\left[S_1^{[q-p,q]}(j-1) \right]^2 + S_2^{[q-p,q]}(j-1) \right) \right] + O(\varepsilon^3) \right\}. \end{aligned} \quad (60)$$

From the relation

$$\frac{d}{dz} {}_2F_1(a, b; c; z) = \frac{ab}{c} {}_2F_1(a+1, b+1; c+1; z), \quad (61)$$

it follows that

$$\begin{aligned} & \sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1-\frac{p}{q}+j\right)} \exp \left[\sum_{k=1}^{\infty} \frac{(-\varepsilon)^k}{k} \left(-A_k S_k(j-1) + c^k S_k^{[q-p,q]}(j-1) \right) \right] \Big|_{z=-\frac{\xi^q}{1-\xi^q}} \\ &= \xi^p \sum_{k=0}^{\infty} \left[\frac{\rho_{k+2}(\xi)}{a_1 a_2} \right] \varepsilon^k, \end{aligned} \quad (62)$$

where ξ and $\rho_k(\xi)$ are defined by Eqs. (18) and (20), respectively. The algorithms for the analytical evaluation of $\rho_k(\xi)$ were presented in Section 2.1.2. The equality of the l.h.s. and r.h.s. of Eq. (62) in each order of ε allows one to express the combination of generalized multiple rational sums in terms of multiple polylogarithms. Using Eq. (31), we obtain

$$\sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1-\frac{p}{q}+j\right)} = -\xi^p \sum_{j_1=1}^q \lambda_q^{j_1 p} \text{Li}_1\left(\lambda_q^{j_1} \xi\right) , \quad (63a)$$

$$\sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_1(j-1) = \xi^p \sum_{j_1, j_2=1}^q \lambda_q^{j_1 p} \text{Li}_{1,1}\left(\lambda_q^{j_1-j_2}, \lambda_q^{j_2} \xi\right) , \quad (63b)$$

$$\sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_1^{[q-p,q]}(j-1) = -\xi^p q \sum_{j_1=1}^q \lambda_q^{j_1 p} \text{Li}_2\left(\lambda_q^{j_1} \xi\right) , \quad (63c)$$

$$\begin{aligned} \sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1+j-\frac{p}{q}\right)} & \left(\left[S_1^{[q-p,q]}(j-1) \right]^2 + S_2^{[q-p,q]}(j-1) \right) = \\ & -2q^2 \xi^p \sum_{j_1=1}^q \lambda_q^{j_1 p} \text{Li}_3\left(\lambda_q^{j_1} \xi\right) , \end{aligned} \quad (63d)$$

$$\begin{aligned} \sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_1(j-1) S_1^{[q-p,q]}(j-1) = \\ q \xi^p \sum_{j_1, j_2=1}^q \lambda_q^{j_1 p} \left\{ \text{Li}_{1,2}\left(\lambda_q^{j_1-j_2}, \xi \lambda_q^{j_2}\right) + \text{Li}_{2,1}\left(\lambda_q^{j_1-j_2}, \xi \lambda_q^{j_2}\right) \right\} , \end{aligned} \quad (63e)$$

$$\begin{aligned} \sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_1^2(j-1) = \\ -\xi^p \sum_{j_1, j_2, i_1=1}^q \lambda_q^{j_1 p} \left\{ 2 \text{Li}_{1,1,1}\left(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \xi \lambda_q^{j_3}\right) - \lambda_q^{(j_2-i_1)p} \text{Li}_{1,1,1}\left(\lambda_q^{j_1-i_1}, \lambda_q^{i_1-j_2}, \xi \lambda_q^{j_2}\right) \right\} , \end{aligned} \quad (63f)$$

$$\sum_{j=1}^{\infty} z^j \frac{\Gamma\left(1-\frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_2(j-1) = \xi^p \sum_{j_1, j_2, j_3=1}^q \lambda_q^{(j_1+j_2-j_3)p} \text{Li}_{1,1,1}\left(\lambda_q^{j_1-j_3}, \lambda_q^{j_3-j_2}, \xi \lambda_q^{j_2}\right) , \quad (63g)$$

where ξ is defined by Eq. (18). Symbolically, Eq. (62) may be written as

$$\begin{aligned} & \sum_{\vec{a}} v_{\vec{a}} \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma\left(1 - \frac{p}{q}\right) \Gamma(j)}{\Gamma\left(1 - \frac{p}{q} + j\right)} S_{a_1}^{[p,q]}(j) S_{a_2}^{[p,q]}(j) \dots S_{a_p}^{[p,q]}(j) \Big|_{z=z(\xi)} \\ &= \sum_{\substack{\vec{J}, \vec{k} \\ 1 \leq \{j_m\} \leq q \\ \sum_{i=1}^r k_i = 1+c+a_1+a_2+\dots+a_p}} u_{\vec{J}, \vec{k}} \text{Li}_{\vec{k}}\left(\lambda_q^{j_1-j_2}, \dots, \xi \lambda_q^{j_r}\right), \end{aligned} \quad (64)$$

where \vec{k} is a multi-index, $\vec{k} = \{k_1, \dots, k_r\}$, $v_{\vec{k}}$ are rational numbers and $u_{\vec{k}}$ are complex numbers ($u_{\vec{k}} \in \mathbb{C}$). Unfortunately, we cannot treat all multiple inverse rational sums using the all-order ε expansion of Gauss hypergeometric functions, but just certain linear combinations (see the discussion in Ref. [32]). However, for the evaluation of the others another technique can be used.

3.2 Multiple inverse rational sums of arbitrary depth and weight

There is an important subclass of *multiple inverse rational sums*, which are defined as

$$\Sigma_{a_1, \dots, a_k; -; c; -}^{[p,q]}(z) \equiv \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j) \Gamma\left(1 - \frac{p}{q}\right)}{\Gamma\left(1 - \frac{p}{q} + j\right)} S_{a_1}(j-1) S_{a_2}(j-1) \dots S_{a_k}(j-1), \quad (65)$$

where a_1, \dots, a_k, c are arbitrary positive integers. The number $w = c + 1 + a_1 + \dots + a_k$ is called the *weight* and $d = k$ the *depth* of the sums. For the analysis of these sums, the generating function approach [32,39,42,51] can be applied.

Let us rewrite the multiple sum (65) in the form $\Sigma_{\vec{a}; -; c; -}^{[p,q]}(z) = \sum_{j=1}^{\infty} z^j \eta_{\vec{a}; -; c; -}(j)$, where $\vec{a} \equiv (a_1, \dots, a_p)$ denotes the collective list of indices and $\eta_{\vec{a}; -; c; -}(j)$ is the coefficient of z^j . In order to find the differential equation for generating functions of multiple sums, it is necessary to find a recurrence relation for the coefficients $\eta_{\vec{a}; -; c; -}^{[p,q]}(j)$ with respect to the summation index j . Using the explicit form of $\eta_{\vec{a}; -; c; -}^{[p,q]}(j)$, the recurrence relation for the coefficients can be written in the form

$$\left[j + 1 - \frac{p}{q}\right] (j+1)^c \eta_{\vec{a}; -; c; -}^{[p,q]}(j+1) = j^{c+1} \eta_{\vec{a}; -; c; -}^{[p,q]}(j) + r_{\vec{a}; -}^{[p,q]}(j), \quad (66)$$

where the “remainder” $r_{\vec{a}; -}(j)$ is given by

$$\frac{\Gamma\left(1 + j - \frac{p}{q}\right)}{\Gamma(j) \Gamma\left(1 - \frac{p}{q}\right)} r_{\vec{a}; -}^{[p,q]}(j) = j \times \left\{ \prod_{r=1}^k \left[S_{a_r}(j-1) + \frac{1}{j^{a_r}} \right] - \prod_{r=1}^k S_{a_r}(j-1) \right\}. \quad (67)$$

Multiplying both sides of Eq. (66) by z^j , summing over $j = 1, 2, 3, \dots$, and using the fact that any extra power of j corresponds to the derivative $z(d/dz)$ leads to the following differential equation for the generating functions $\Sigma_{\vec{a};-;c;-}^{[p,q]}(z)$:

$$\left[\left(\frac{1}{z} - 1 \right) z \frac{d}{dz} - \frac{1}{z} \frac{p}{q} \right] \left(z \frac{d}{dz} \right)^c \Sigma_{\vec{a};-;c;-}^{[p,q]}(z) = \delta_{\vec{a},0} + R_{\vec{a};-}^{[p,q]}(z), \quad (68)$$

where the non-homogeneous term $R_{\vec{a};-}^{[p,q]}(z) \equiv \sum_{j=1}^{\infty} z^j r_{\vec{a};-}^{[p,q]}(j)$ is again expressible in terms of sums of the same type, $\Sigma_{b_1, \dots, b_p; -; m; -}^{[p,q]}(z)$, but with smaller depth, and $\delta_{a,b}$ is the Kronecker δ symbol. The boundary conditions for any of these sums and their derivatives are

$$\left(z \frac{d}{dz} \right)^j \Sigma_{\vec{a};\vec{b};c_1;c_2}(0) = 0 \quad (j = 0, 1, 2, \dots). \quad (69)$$

Let us consider the differential equation (68) in terms of the variable ξ defined by Eq.(18). The notation $\Sigma_{\vec{a};\vec{b};c;-}^{[p,q]}(\xi)$ will be used for a sum defined by Eq. (65), where the variable z is rewritten in terms of the variable ξ :

$$\Sigma_{\vec{a};\vec{b};c_1;c_2}^{[p,q]}(\xi) \equiv \Sigma_{\vec{a};\vec{b};c_1;c_2}^{[p,q]}(z(\xi)) \equiv \left. \Sigma_{\vec{a};\vec{b};c_1;c_2}^{[p,q]}(z) \right|_{z=z(\xi)}. \quad (70)$$

In terms of the variable ξ , Eq. (68) may be split into the sum of two equations,

$$\left(\frac{1}{q} (1 - \xi^q) \xi \frac{d}{d\xi} \right)^c \Sigma_{\vec{a};-;c;-}^{[p,q]}(\xi) = \xi^p \sigma_{\vec{a};-}^{[p,q]}(\xi), \quad (71a)$$

$$-\frac{1}{q} \frac{1 - \xi^q}{\xi^{q-p-1}} \frac{d}{d\xi} \sigma_{\vec{a};-}^{[p,q]}(\xi) = \delta_{\vec{a},0} + R_{\vec{a};-}^{[p,q]}(\xi). \quad (71b)$$

From Eq. (71a), it is easy to obtain

$$\left(\frac{1}{q} (1 - \xi^q) \xi \frac{d}{d\xi} \right)^{c-j} \Sigma_{\vec{a};-;c;-}^{[p,q]}(\xi) = \Sigma_{\vec{a};-;j}^{[p,q]}(\xi), \quad (72)$$

or in equivalent form,

$$\left(\frac{1}{q} (1 - \xi^q) \xi \frac{d}{d\xi} \right)^{c-j-1} \Sigma_{\vec{a};-;c;-}^{[p,q]}(\xi) = q \int_0^\xi \frac{dt}{(1-t^q)t} \Sigma_{\vec{a};-;j}^{[p,q]}(t), \quad j \geq 1. \quad (73)$$

From this representation, we immediately obtain the following lemma, which is a generalisation of a statement given in Ref. [45]:

Lemma A

If, for some integer j , the series $\Sigma_{\vec{a};-;j}^{[p,q]}(\xi)$ is expressible in terms of hyperlogarithms with complex coefficients, then this also holds for the sums $\Sigma_{\vec{a};-;j+i}^{[p,q]}(\xi)$ with positive integers i .

In order to prove **Theorem A** for multiple inverse rational sums, we prove an auxiliary proposition:

Proposition A

For $c = 0$, the inverse rational sums are expressible in terms of multiple polylogarithms of arguments being powers of q -roots of unity and the variable ξ , defined by Eq. (18), with complex coefficients $c_{r,\vec{s}}$ times a factor ξ^p , as

$$\Sigma_{a_1, \dots, a_p; -; 0; -}^{[p,q]}(z) \Big|_{z=z(\xi)} = \xi^p \sum_{\substack{\vec{J}, \vec{s} \\ 1 \leq \{j_m\} \leq q}} c_{\vec{J}, \vec{s}} \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} \xi) , \quad (74)$$

where the weights of the l.h.s. and the r.h.s. are equal, i.e. $s_1 + \dots + s_r = 1 + a_1 + \dots + a_p$.

Substituting expression (74) in the r.h.s. of Eq. (72), setting $c = 1$, and performing a trivial splitting of the denominator, we obtain

$$\begin{aligned} & \Sigma_{\vec{a}; -; 1; -}^{[p,q]}(z) \Big|_{z=z(\xi)} \\ &= \sum_{\substack{\vec{J}, \vec{s} \\ 1 \leq \{j_m\} \leq q}} \sum_{j=1}^q \lambda_q^{-jp} \int_0^\xi \frac{1}{t - \frac{1}{\lambda_q^j}} \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} t) \\ &= \sum_{\substack{\vec{J}, \vec{s} \\ 1 \leq \{j_m\} \leq q}} \lambda_q^{-jp} c_{\vec{J}, \vec{s}} \text{Li}_{1, \vec{s}}(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r-j_{r+1}}, \lambda_q^{j_{r+1}} \xi) . \end{aligned} \quad (75)$$

In accordance with **Lemma A**, we have

Corollary A:

For $c \geq 1$, the inverse rational sums are expressible in terms of multiple polylogarithms of arguments being powers of q -roots of unity and the variable ξ , defined by Eq. (18), with complex coefficients $d_{\vec{J}, \vec{s}}$, as

$$\Sigma_{a_1, \dots, a_p; -; c; -}^{[p,q]}(z) \Big|_{z=z(\xi)} = \sum_{\substack{\vec{J}, \vec{s} \\ 1 \leq \{j_m\} \leq q}} d_{\vec{J}, \vec{s}} \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} \xi) \quad (c \geq 1) , \quad (76)$$

where the weights of the l.h.s. and the r.h.s. are equal, i.e. $s_1 + \dots + s_r = 1 + c + a_1 + \dots + a_p$. The strategy of the proof of these results is similar to the one adopted in Ref. [39]. We reproduce it here for completeness with appropriate modifications. In Eq. (68), it is necessary to distinguish two cases: (i) $R_{\vec{a}}^{[p,q]}(z) = 0, \delta_{\vec{a},0} = 1$, the so-called depth-0 sums, and (ii) $R_{\vec{a}}^{[p,q]}(z) \neq 0, \delta_{\vec{a},0} = 0$.

Let us first consider the multiple inverse rational sums of depth 0,

$$\Sigma_{-;-;c;-}^{[p,q]}(\xi) = \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1+j-\frac{p}{q}\right)}. \quad (77)$$

In this case, the system of equations (71) has the form

$$\left(\frac{1}{q}(1-\xi^q)\xi \frac{d}{d\xi}\right)^c \Sigma_{-;-;c;-}^{[p,q]}(\xi) = \xi^p \sigma_{-;-}^{[p,q]}(\xi), \quad (78a)$$

$$\frac{d}{d\xi} \sigma_{-;-}^{[p,q]}(\xi) = \sum_{j=1}^q \lambda_q^{jp} \frac{1}{\xi - \frac{1}{\lambda_q^j}}. \quad (78b)$$

We immediately obtain

$$\sigma_{-;-}^{[p,q]}(\xi) = - \sum_{j=1}^q \lambda_q^{jp} \text{Li}_1(\lambda_q^j \xi), \quad (79)$$

and

$$\Sigma_{-;-;0;-}^{[p,q]}(\xi) = -\xi^p \sum_{j=1}^q \lambda_q^{jp} \text{Li}_1(\lambda_q^j \xi), \quad (80)$$

which agrees with **Proposition A**, and also with Eq. (63a). Iteration of the last equation produces

$$\Sigma_{-;-;1;-}^{[p,q]}(\xi) = - \sum_{k,j_1=1}^q \lambda_j^{(k-j_1)p} \text{Li}_{1,1}(\lambda_q^{k-j_1}, \lambda_q^{j_1} \xi). \quad (81)$$

In accordance with **Lemma A**, all the next iterations produce results in terms of multiple polylogarithms with complex coefficients. For example,

$$\begin{aligned} \Sigma_{-;-;2;-}^{[p,q]}(\xi) &= -q \sum_{k,j_1=1}^q \lambda_q^{(k-j_1)p} \text{Li}_{2,1}(\lambda_q^{k-j_1}, \lambda_q^{j_1} \xi) \\ &\quad - \sum_{k,j_1,j_2=1}^q \lambda_q^{(k-j_1)p} \text{Li}_{1,1,1}(\lambda_q^{k-j_1}, \lambda_q^{j_1-j_2}, \lambda_q^{j_2} \xi). \end{aligned} \quad (82)$$

Let us analyze the sums of depth 1,

$$\Sigma_{a_1;-;c;-}^{[p,q]}(\xi) = \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_{a_1}(j-1) \equiv \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(j-\frac{p}{q}\right)} \sum_{i=1}^{j-1} \frac{1}{i^{a_1}}.$$

The coefficients of the non-homogeneous part are expressible in terms of multiple inverse rational sum of depth 0, and Eq. (71) takes the form

$$\left(\xi \frac{d}{d\xi}\right)^c \Sigma_{a_1; -; c; -}^{[p, q]}(\xi) = \xi^p \sigma_{a_1; -}^{[p, q]}(\xi), \quad (83a)$$

$$\frac{d}{d\xi} \sigma_{a_1; -}^{[p, q]}(\xi) = -q \frac{\xi^{q-p-1}}{1-\xi^q} \Sigma_{-; -; a_1-1; -}^{[p, q]}(\xi). \quad (83b)$$

For $c = 0$, the system of equations (83) takes the simplest form,

$$\Sigma_{a_1; -; 0; -}^{[p, q]}(\xi) = \xi^p \sigma_{a_1; -}^{[p, q]}(\xi), \quad (84a)$$

$$\frac{d}{d\xi} \sigma_{a_1; -}^{[p, q]}(\xi) = -q \frac{\xi^{q-p-1}}{1-\xi^q} \Sigma_{-; -; a_1-1; -}^{[p, q]}(\xi). \quad (84b)$$

Let us first consider the case $a_1 = 1$. Using Eq. (80), we obtain

$$\sigma_{1; 0}(\xi) = \sum_{j_1, j_2=1}^q \lambda_q^{j_1 p} \text{Li}_{1, 1}(\lambda_q^{j_1-j_2}, \lambda_q^{j_2} \xi), \quad (85)$$

and the result for $\Sigma_{1; -; 0; -}^{[p, q]}(\xi)$ agrees with **Proposition A** and reproduces the result of Eq. (63b). For $a_1 \geq 2$, the r.h.s. of Eq. (84b) is expressible in terms of multiple polylogarithms with complex coefficients, so that $\sigma_{a_1; -}^{[p, q]}(\xi)$ is also expressible in terms of multiple polylogarithms with complex coefficients.⁵ Substituting these results in Eq. (84a), we obtain results in accordance with **Corollary A**. For $c \geq 1$, the desired results follows from **Lemma A**.

Let us apply mathematical induction. Let us assume that **Proposition A** is valid for multiple inverse rational sums of depth k ,

$$\begin{aligned} \Sigma_{a_1, \dots, a_k; -; 0; -}^{[p, q]}(z) &\equiv \sum_{j=1}^{\infty} z^j \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_{a_1}(j-1) \cdots S_{a_k}(j-1) \Big|_{z=z(\xi)} \\ &= \xi^p \sum_{\vec{s}, 1 \leq \{j_m\} \leq q} c_{\vec{j}, \vec{s}} \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} \xi), \end{aligned} \quad (86)$$

where $\vec{s} = \{s_1, \dots, s_r\}$, and $s_1 + \cdots + s_r = 1 + a_1 + \cdots + a_k$. Then for $c \geq 1$, **Corollary A** also holds for multiple inverse rational sums of depth k ,

$$\begin{aligned} \Sigma_{a_1, \dots, a_k; -; c; -}^{[p, q]}(z) &\equiv \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_{a_1}(j-1) \cdots S_{a_k}(j-1) \Big|_{z=z(\xi)} \\ &= \sum_{\vec{s}, 1 \leq \{j_m\} \leq q} d_{\vec{j}, \vec{s}} \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} \xi). \end{aligned} \quad (87)$$

⁵In particular, Eq. (63g) may be reproduced easily.

For the sum of depth $k+1$, the coefficients of the non-homogeneous part may be expressed as linear combinations of sums of depth j ($j = 0, \dots, k$) with integer coefficients and all possible symmetric distributions of the original indices over the terms of the new sums, as

$$\left[\frac{1}{q} (1 - \xi^q) \xi \frac{d}{d\xi} \right]^c \Sigma_{a_1, \dots, a_{k+1}; -; c; -}^{[p, q]}(\xi) = \xi^p \sigma_{a_1, \dots, a_{k+1}; -}^{[p, q]}(\xi), \quad (88a)$$

$$\begin{aligned} \frac{d}{d\xi} \sigma_{a_1, \dots, a_{k+1}; -}^{[p, q]}(\xi) &= -q \frac{\xi^{q-p-1}}{1 - \xi^q} \sum_{j=1}^{\infty} z^j \frac{\Gamma(1+j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1+j-\frac{p}{q}\right)} \\ &\times \sum_{p=0}^k \sum_{(i_1, \dots, i_{k+1})} \frac{1}{p!(k+1-p)!} \frac{S_{i_1}(j-1) \cdots S_{i_p}(j-1)}{j^{i_{p+1}+\dots+i_{k+1}}}, \end{aligned} \quad (88b)$$

where the sum over the indices (i_1, \dots, i_{k+1}) is to be taken over all permutations of the list (a_1, \dots, a_{k+1}) . If $i_{p+1} + \dots + i_{k+1} \geq 2$, the r.h.s. of Eq. (88b) is expressible in terms of multiple polylogarithms of weight k with complex coefficients; see Eq. (87). As a result of integrating this equation, $\sigma_{a_1, \dots, a_{k+1}; -}^{(1)}(\xi)$ is also expressible in terms of harmonic polylogarithms of weight $k+1$ with complex coefficients.

If $i_{p+1} + \dots + i_{k+1} = 1$, the r.h.s. of Eq. (88b) is expressible in terms of multiple polylogarithms of weight k with a common factor ξ^p ; see Eq. (86). The result of integrating this equation is again expressible in terms of multiple polylogarithms of weight $k+1$ with complex coefficients, as

$$\sigma_{a_1, \dots, a_{k+1}; -}^{(1)}(\xi) = \sum_{\vec{s}, 1 \leq \{j_m\} \leq q} \sum_{j=1}^q \int_0^\xi dt \frac{1}{t - \frac{1}{\lambda_q^j}} d_{\vec{J}, \vec{s}} \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} \xi). \quad (89)$$

For $c = 0$, direct substitution of the previous results into Eq. (88a) shows that **Proposition A** is valid for weight $k+1$. In this way, **Proposition A** is proven for all weights. Then, for $c \geq 2$, **Corollary A** is also true for multiple inverse rational sums of depth $k+1$.

Applying the differential operator $z \frac{d}{dz} \equiv -\frac{1}{q} (1 - \xi^q) \xi \frac{d}{d\xi}$ repeatedly l times to the sum $\Sigma_{a_1, \dots, a_p; -; c; -}^{[p, q]}(z)$, we can derive results for a similar sum with $c < 0$. Thus, **Theorem A** is proven for multiple inverse rational sums.

Remark IV

For the particular value $q = 2$ ($p = 1$), the multiple inverse rational sums (62) are reduced to multiple inverse binomial sums, which were studied in Refs. [30,32,39],

$$\begin{aligned} \Sigma_{a_1, \dots, a_p; -; c; -}^{[1, 2]}(z) &= \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma\left(\frac{1}{2}\right) \Gamma(j)}{\Gamma\left(j + \frac{1}{2}\right)} S_{a_1}(j-1) \cdots S_{a_p}(j-1) \\ &= \sum_{j=1}^{\infty} \frac{(4z)^j}{j^{c+1}} \frac{1}{\binom{2j}{j}} S_{a_1}(j-1) \cdots S_{a_p}(j-1). \end{aligned} \quad (90)$$

In order to convert the results of Eqs. (63) and **Theorem A** to the form presented in Refs. [32,39], respectively, is it necessary to consider the new variable

$$y = \frac{1 - \xi}{1 + \xi}.$$

In particular,

$$\Sigma_{-;-;0;-}^{[1,2]}(z) = \xi \ln \frac{1 - \xi}{1 + \xi}, \quad (91)$$

$$\Sigma_{-;-;1;-}^{[1,2]}(z) = -\text{Li}_{1,1}(1, \xi) - \text{Li}_{1,1}(1, -\xi) + \text{Li}_{1,1}(-1, \xi) + \text{Li}_{1,1}(-1, -\xi). \quad (92)$$

For practical applications, the following relations are useful:

$$\text{Li}_{1,1}(x, y) = - \int_0^y \frac{dt}{1 - z} \ln(1 - xt), \quad (93)$$

$$\text{Li}_{1,1}(1, z) = \frac{1}{2} \ln^2(1 - z), \quad (94)$$

$$\text{Li}_{1,1}(-1, z) = \ln(2) \ln(1 - z) - \text{Li}_2\left(\frac{1 - x}{2}\right) + \text{Li}_2\left(\frac{1}{2}\right). \quad (95)$$

Remark V

Let us modify the multiple inverse rational sums of Eq. (65) by introducing an additional parameter d , as

$$\Sigma_{a_1, \dots, a_k; -;c;-}^{[p,q]}(d, z) \equiv \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j)\Gamma(d - \frac{p}{q})}{\Gamma(d + j - \frac{p}{q})} S_{a_1}(j-1) S_{a_2}(j-1) \cdots S_{a_k}(j-1). \quad (96)$$

Equation (66) is changed to become

$$\left[j + d - \frac{p}{q}\right] (j+1)^c \eta_{\vec{a};-;c;-}^{[p,q]}(j+1) = j^{c+1} \eta_{\vec{a};-;c;-}^{[p,q]}(j) + r_{\vec{a};-}^{[p,q]}(j), \quad (97)$$

and we have

$$\left[\left(\frac{1}{z} - 1\right) z \frac{d}{dz} + \frac{1}{z} \left(d - 1 - \frac{p}{q}\right)\right] \left(z \frac{d}{dz}\right)^c \Sigma_{\vec{a};-;c;-}^{[p,q]}(d, z) = \delta_{\vec{a},0} + R_{\vec{a};-}^{[p,q]}(d, z). \quad (98)$$

In terms of the variable ξ , Eq. (98) is split into two pieces,

$$\left[\frac{1}{q}(1 - \xi^q) \xi \frac{d}{d\xi}\right]^c \Sigma_{-;\vec{a};-c;-}^{[p,q]}(d, \xi) = \xi^{p-q(d-1)} \sigma_{-;\vec{a}}^{[p,q]}(\xi), \quad (99a)$$

$$-\frac{1}{q} \frac{1 - \xi^q}{\xi^{qd-p-1}} \frac{d}{d\xi} \sigma_{-;\vec{a}}^{[p,q]}(\xi) = \delta_{\vec{a},0} + R_{-;\vec{a}}^{[p,q]}(\xi). \quad (99b)$$

For the analysis of this system, the previous technique can be applied directly after using the decomposition

$$q \frac{x^{qd-p-1}}{1 - x^q} = - \sum_{j=1}^q \frac{\lambda_q^{jp}}{x - \frac{1}{\lambda_q^j}},$$

where d is an integer and $qd \geq p + 1$.

3.3 Multiple rational sums of arbitrary depth and weight

Another important class of multiple sums are the so-called *multiple rational sums*, defined as

$$\Upsilon_{a_1, \dots, a_k; -; c; -}^{[p,q]}(z) \equiv \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j + \frac{p}{q})}{\Gamma(j+1)\Gamma(1+\frac{p}{q})} S_{a_1}(j-1) S_{a_2}(j-1) \cdots S_{a_k}(j-1) , \quad (100)$$

where a_1, \dots, a_k, c are arbitrary positive integers. The quantum numbers, depth and weight, are defined as in the case of multiple inverse rational sums, namely the *weight* as $w = c + 1 + a_1 + \cdots + a_k$ and the *depth* as $d = k$. In this case, the proper recurrence relation is

$$(j+1)^{c+1} \eta_{\vec{a}; -; c; -}^{[p,q]}(j+1) = \left(j + \frac{p}{q}\right) j^c \eta_{\vec{a}; -; c; -}^{[p,q]}(j) + \left(j + \frac{p}{q}\right) r_{\vec{a}; -}^{[p,q]}(j) , \quad (101)$$

where the “remainder” $r_{\vec{a}; -}(j)$ is given by

$$\frac{\Gamma(j+1)\Gamma(1+\frac{p}{q})}{\Gamma(j+\frac{p}{q})} r_{\vec{a}; -}^{[p,q]}(j) = \left\{ \prod_{r=1}^p \left[S_{a_r}(j-1) + \frac{1}{j^{a_r}} \right] - \prod_{r=1}^p S_{a_r}(j-1) \right\} . \quad (102)$$

The differential equations for the generating functions $\Upsilon_{\vec{a}; -; c; -}^{[p,q]}(z)$ is

$$\left[\left(\frac{1}{z} - 1 \right) z \frac{d}{dz} - \frac{p}{q} \right] \left(z \frac{d}{dz} \right)^c \Upsilon_{\vec{a}; -; c; -}^{[p,q]}(z) = \delta_{\vec{a},0} + \left(z \frac{d}{dz} + \frac{p}{q} \right) \sum_{\vec{s},j} d_{\vec{s},j} \Upsilon_{\vec{s}; -; j; -}^{[p,q]}(z) , \quad (103)$$

where the non-homogeneous term $\sum_{j=1}^{\infty} z^j r_{\vec{a}; -}^{[p,q]}(j)$ is again expressible in terms of sums of the same type, but with smaller depth. Symbolically, we write it as

$$\sum_{j=1}^{\infty} z^j r_{\vec{a}; -}^{[p,q]}(j) = \sum_{\vec{s},k} d_{\vec{s},k} \Upsilon_{\vec{s}; -; k; -}^{[p,q]}(\tau) , \quad (104)$$

where $d_{\vec{s},k}$ are complex coefficients and

$$\sum_j a_j = k + \sum_i s_i .$$

Introducing the variable τ defined in Eq. (40), so that

$$z = 1 - \tau^q , \quad z \frac{d}{dz} = -\frac{1}{q} \left(\frac{1 - \tau^q}{\tau^q} \right) \tau \frac{d}{d\tau} , \quad \left[(1 - z) \frac{d}{dz} - \frac{p}{q} \right] = -\frac{1}{q} \left(\tau \frac{d}{d\tau} + p \right) \quad (105)$$

we obtain

$$\left[-\frac{1}{q} \left(\frac{1 - \tau^q}{\tau^q} \right) \tau \frac{d}{d\tau} \right]^c \Upsilon_{\vec{a}; -; c; -}^{[p,q]}(\tau) = \tau^{-p} \sigma_{\vec{a}; -}^{[p,q]}(\tau) , \quad (106a)$$

$$-\frac{1}{q} \tau^{1-p} \frac{d}{d\tau} \sigma_{\vec{a}; -}^{[p,q]}(\tau) = \delta_{\vec{a},0} - \frac{1}{q} \left(\frac{1 - \tau^q}{\tau^q} \tau \frac{d}{d\tau} - p \right) \sum_{\vec{s},j} d_{\vec{s},j} \Upsilon_{\vec{s}; -; j; -}^{[p,q]}(\tau) . \quad (106b)$$

The point $z = 0$ transforms to the point $\tau = 1$, so that the boundary conditions for these sums are

$$\Upsilon_{\vec{a};-;c_1;-}(1) = 0 . \quad (107)$$

From Eq. (106a), it is easy to obtain

$$\left[-\frac{1}{q} \frac{(1-\tau^q)}{\tau^q} \tau \frac{d}{d\tau} \right]^{c-j} \Upsilon_{\vec{a};-;c;-}^{[p,q]}(\tau) = \Upsilon_{\vec{a};-;j;-}^{[p,q]}(\tau) , \quad (108)$$

or in equivalent form,

$$\left[-\frac{1}{q} \frac{(1-\tau^q)}{\tau^q} \tau \frac{d}{d\tau} \right]^{c-j-1} \Upsilon_{\vec{a};-;c;-}^{[p,q]}(\tau) = -q \int_1^\tau dt \frac{t^{q-1}}{1-t^q} \Upsilon_{\vec{a};-;j;-}^{[p,q]}(t) \quad (j \geq 1) . \quad (109)$$

We wish to point out that the point $\tau = 1$ is a regular point of multiple rational sums.

From representation (109), we immediately obtain the following lemma, which is a generalization of the statement given in Ref. [45]:

Lemma B

If for some integer j , the series $\Upsilon_{\vec{a};-;j}^{[p,q]}(\tau)$ is expressible in terms of hyperlogarithms with complex coefficients, then this also holds for the sums $\Upsilon_{\vec{a};-;j+i}^{[p,q]}(\tau)$ for positive integers i .

Let us return to Eq. (106b) and rewrite it in the form

$$-\frac{1}{q} \tau^{1-p} \frac{d}{d\tau} \sigma_{\vec{a};-}^{[p,q]}(\tau) = \delta_{\vec{a},0} + \sum_{\vec{s},j} d_{\vec{s};-;j} \left[\frac{p}{q} \Upsilon_{\vec{s};-;j}^{[p,q]}(\tau) + \Upsilon_{\vec{s};-;j-1}^{[p,q]}(\tau) \right] , \quad (110)$$

where $d_{\vec{s};-;j}$ is a set of constants. Integrating it by parts, we find

$$\sigma_{\vec{a};-}^{[p,q]}(\tau) = \frac{q}{p} \delta_{\vec{a},0} (1 - \tau^p) + \sum_{\vec{s},j} d_{\vec{s};-;j} \left[-\tau^p \Upsilon_{\vec{s};-;j}^{[p,q]}(\tau) - q \int_1^\tau dt \frac{t^{p-1}}{1-t^q} \Upsilon_{\vec{s};-;j-1}^{[p,q]}(t) \right] . \quad (111)$$

Substituting this expression in the r.h.s. of Eq. (106a), we obtain

$$\begin{aligned} \left[-\frac{1}{q} \frac{(1-\tau^q)}{\tau^q} \tau \frac{d}{d\tau} \right]^c \Upsilon_{\vec{a};-;c;-}^{[p,q]}(\tau) &= -\frac{q}{p} \delta_{\vec{a},0} (1 - \tau^{-p}) \\ &\quad - \sum_{\vec{s},j} d_{\vec{s};-;j} \left[\Upsilon_{\vec{s};-;j}^{[p,q]}(\tau) + q \tau^{-p} \int_1^\tau dt \frac{t^{p-1}}{1-t^q} \Upsilon_{\vec{s};-;j-1}^{[p,q]}(t) \right] . \end{aligned} \quad (112)$$

In order to prove **Theorem B** for rational sums, we first prove the following auxiliary proposition:

Proposition B

For $c = 0$, the inverse rational sums are expressible in terms of multiple polylogarithms of arguments being powers of q -roots of unity times the variable τ , defined by Eq. (40), with

complex coefficients $c_{r,\vec{s}}$ and $d_{r,\vec{s}}$ times a factor τ^{-p} , as

$$\begin{aligned} \Upsilon_{a_1, \dots, a_p; -; 0; -}^{[p,q]}(z) \Big|_{z=z(\tau)} &= \\ \sum_{\substack{\vec{J}, \vec{s} \\ 1 \leq \{j_m\} \leq q}} \left(c_{\vec{J}, \vec{s}, k} + d_{\vec{J}, \vec{s}, k} \tau^{-p} \right) \ln^k \tau &\left[\text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r} \tau) - \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r}) \right], \end{aligned} \quad (113)$$

where the weights of the l.h.s. and the r.h.s. are equal, i.e. $s_1 + \dots + s_r + k = a_1 + \dots + a_p$.

Substituting expression (113) in the r.h.s. of Eq. (109), setting $c = 1$, and performing a trivial splitting of the denominator, we obtain

$$\begin{aligned} \Upsilon_{\vec{a}; -; 1; -}^{[p,q]}(z) \Big|_{z=z(\tau)} &= \\ \sum_{\substack{\vec{J}, \vec{s}, k \\ 1 \leq \{j_m\} \leq q}} \sum_{j=1}^q \left(c_{\vec{J}, \vec{s}} + d_{\vec{J}, \vec{s}} \lambda_q^{jp} \right) \int_1^\tau \frac{dt}{t - \frac{1}{\lambda_q^j}} \ln^k t &\left[\text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r} t) - \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r}) \right] \\ &= - \sum_{\substack{\vec{J}, \vec{s}, k \\ 1 \leq \{j_m\} \leq q}} \tilde{d}_{\vec{J}, \vec{s}} \ln^k \tau &\left[\text{Li}_{1, \vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_{r+1}} \tau) - \text{Li}_{1, \vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_{r+1}}) \right]. \end{aligned} \quad (114)$$

In accordance with **Lemma B**, we have

Corollary B:

For $c \geq 1$, the multiple rational sums are expressible in terms of multiple polylogarithms of arguments being powers of q -roots of unity and the variable τ , defined by Eq. (40), with complex coefficients $d_{\vec{s}}$, as

$$\begin{aligned} \Upsilon_{a_1, \dots, a_p; -; c; -}^{[p,q]}(z) \Big|_{z=z(\xi)} &= \\ \sum_{\substack{\vec{J}, \vec{s}, k \\ 1 \leq \{j_m\} \leq q}} d_{\vec{J}, \vec{s}, k} \ln^k \tau &\left[\text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r} \tau) - \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r}) \right] \quad (c \geq 1), \end{aligned} \quad (115)$$

where the weights of the l.h.s. and the r.h.s. are equal, i.e. $s_1 + \dots + s_r + k = c + a_1 + \dots + a_p$.

In order to prove **Theorem B** for multiple inverse rational sums, it is sufficient to proof **Lemma B**. The strategy of proof of these results is similar to the one adopted in Ref. [39]. We reproduce it here for completeness with appropriate modifications.

In Eq. (106), it is necessary to distinguish two cases: (i) $R_{\vec{a}}^{[p,q]}(z) = 0, \delta_{\vec{a},0} = 1$, the so-called depth 0 sums, and (ii) $R_{\vec{a}}^{[p,q]}(z) \neq 0, \delta_{\vec{a},0} = 0$.

Let us consider the multiple inverse rational sums of depth 0,

$$\Upsilon_{-;-;c;-}^{[p,q]}(\tau) = \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j + \frac{p}{q})}{\Gamma(j+1)\Gamma(1+\frac{p}{q})} \Big|_{z=z(\tau)} . \quad (116)$$

In this case, the system of equations (106) has the form

$$\left(-\frac{1}{q} \frac{(1-\tau^q)}{\tau^q} \tau \frac{d}{d\tau} \right)^c \Upsilon_{-;-;c;-}^{[p,q]}(\tau) = \tau^{-p} \sigma_{-;-}^{[p,q]}(\tau) , \quad (117a)$$

$$\frac{d}{d\tau} \sigma_{-;-}^{[p,q]}(\tau) = -q\tau^{p-1} . \quad (117b)$$

We immediately obtain

$$\sigma_{-;-}^{[p,q]}(\tau) = \frac{q}{p} (1 - \tau^p) \quad (118)$$

and

$$\Upsilon_{-;-;0;-}^{[p,q]}(\tau) = -\frac{q}{p} (1 - \tau^{-p}) . \quad (119)$$

Iteration of the last equation produces⁶

$$\begin{aligned} \Upsilon_{-;-;1;-}^{[p,q]}(\tau) &= \frac{q}{p} \sum_{j=1}^{q-1} (1 - \lambda_q^{jp}) [\text{Li}_1(\lambda_q^j \tau) - \text{Li}_1(\lambda_q^j)] \\ &\equiv \frac{q}{p} \sum_{j=1}^q (1 - \lambda_q^{jp}) [\text{Li}_1(\lambda_q^j \tau) - \text{Li}_1(\lambda_q^j)] , \end{aligned} \quad (120)$$

where the last term of the sum, for $j = q$, is identically equal to zero.

The next iteration yields

$$\begin{aligned} \Upsilon_{-;-;2;-}^{[p,q]}(\tau) &= -\frac{q}{p} \sum_{j_1,j_2=1}^{q-1} (1 - \lambda_q^{j_1 p}) [\text{Li}_{1,1}(\lambda_q^{j_1-j_2}, \lambda_q^{j_2} \tau) - \text{Li}_{1,1}(\lambda_q^{j_1-j_2}, \lambda_q^{j_2})] \\ &\quad + \frac{q}{p} \sum_{j_1,j_2=1}^{q-1} (1 - \lambda_q^{j_1 p}) \text{Li}_1(\lambda_q^{j_1}) \left[\text{Li}_1(\lambda_q^{j_2} \tau) - \text{Li}_1(\lambda_q^{j_2}) \right] \\ &\quad + \frac{q}{p} \sum_{j_1=1}^{q-1} (1 - \lambda_q^{j_1 p}) [\text{Li}_{1,1}(\tau, \lambda_q^{j_1}) - \text{Li}_{1,1}(1, \lambda_q^{j_1}) + \text{Li}_2(\lambda_q^{j_1} \tau) - \text{Li}_2(\lambda_q^{j_1})] , \end{aligned} \quad (121)$$

⁶We wish to mention that

$$\sum_{j=1}^{q-1} \ln(1 - \lambda_q^j) = \ln q .$$

where we have used the identity [9]

$$\text{Li}_m(x)\text{Li}_n(y) = \text{Li}_{m,n}(x,y) + \text{Li}_{n,m}(y,x) + \text{Li}_{m+n}(xy) . \quad (122)$$

In accordance with **Lemma B**, all the following iterations produce results in terms of multiple polylogarithms with complex coefficients.

Let us now analyze the multiple inverse rational sums of depth 1,

$$\Upsilon_{a_1; -; c; -}^{[p,q]}(\tau) = \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j+\frac{p}{q})}{\Gamma(1+j)\Gamma(1+\frac{p}{q})} S_{a_1}(j-1) \equiv \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j+\frac{p}{q})}{\Gamma(1+j)\Gamma(1+\frac{p}{q})} \sum_{i=1}^{j-1} \frac{1}{i^{a_1}} .$$

The coefficients of the non-homogeneous part are expressible in terms of multiple rational sums of depth 0, and Eq. (106) takes the form

$$\left(-\frac{1}{q} \frac{(1-\tau^q)}{\tau^q} \tau \frac{d}{d\tau} \right)^c \Upsilon_{a_1; -; c; -}^{[p,q]}(\tau) = \tau^{-p} \sigma_{a_1; -}^{[p,q]}(\tau) , \quad (123a)$$

$$\sigma_{a_1; -}^{[p,q]}(\tau) = -\tau^p \Upsilon_{-; -; a_1; -}^{[p,q]}(\tau) - q \int_1^\tau dt \frac{t^{p-1}}{1-t^q} \Sigma_{-; -; a_1-1}^{[p,q]}(t) . \quad (123b)$$

For $c = 0$, the system of equations (123) read

$$\Upsilon_{a_1; -; 0; -}^{[p,q]}(\tau) = -\Upsilon_{-; -; a_1; -}^{[p,q]}(\tau) - q\tau^{-p} \int_1^\tau dt \frac{t^{p-1}}{1-t^q} \Sigma_{-; -; a_1-1}^{[p,q]}(t) . \quad (124)$$

Let us first consider the case $a_1 = 1$. Using Eqs. (119) and (120), we obtain

$$\Upsilon_{1; -; 0; -}^{[p,q]}(\tau) = -\frac{q}{p} \sum_{j=1}^{q-1} [(1-\lambda_q^{jp}) + \tau^{-p}(1-\lambda_q^{-jp})] [\text{Li}_1(\lambda_q^j \tau) - \text{Li}_1(\lambda_q^j)] - \frac{q^2}{p} \tau^{-p} \ln \tau , \quad (125)$$

in agreement with **Proposition B**. For $a_1 \geq 2$, the r.h.s. of Eq. (124) is expressible in terms of multiple polylogarithms with complex coefficients, so that this also holds for $\Upsilon_{a_1; -}^{[p,q]}(\tau)$, in agreement with **Corollary B**. For $c \geq 1$, the desired result follows from **Lemma B**.

Let us apply mathematical induction and assume that **Proposition B** is valid for multiple inverse rational sums of depth k ,

$$\begin{aligned} \Upsilon_{a_1, \dots, a_k; -; 0; -}^{[p,q]}(z) &\equiv \sum_{j=1}^{\infty} z^j \frac{\Gamma(j+\frac{p}{q})}{\Gamma(1+j)\Gamma(1+\frac{p}{q})} S_{a_1}(j-1) \cdots S_{a_k}(j-1) \Big|_{z=z(\tau)} \\ &= \sum_{\substack{\vec{J}, \vec{s}, k \\ 1 \leq \{j_m\} \leq q}} \left(c_{\vec{J}, \vec{s}, k} + d_{\vec{J}, \vec{s}, k} \tau^{-p} \right) \ln^k \tau \left[\text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r} \tau) - \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r}) \right] , \end{aligned} \quad (126)$$

where $\vec{s} = \{s_1, \dots, s_r\}$ and $s_1 + \dots + s_r + k = a_1 + \dots + a_k$. Then, for $c \geq 1$, **Corollary B** also holds for multiple rational sums of depth k ,

$$\begin{aligned} \Upsilon_{a_1, \dots, a_k; -; c; -}^{[p, q]}(z) &\equiv \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j + \frac{p}{q})}{\Gamma(1+j)\Gamma(1+\frac{p}{q})} S_{a_1}(j-1) \cdots S_{a_k}(j-1) \Big|_{z=z(\tau)} \\ &= \sum_{\substack{\vec{J}, \vec{s}, k \\ 1 \leq \{j_m\} \leq q}} \tilde{d}_{\vec{J}, \vec{s}, k} \ln^k \tau \left[\text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r} \tau) - \text{Li}_{\vec{s}}(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r}) \right]. \end{aligned} \quad (127)$$

For sums of depth $k+1$, the coefficients of the non-homogeneous part are expressed as linear combination of sums of depth j ($j = 0, \dots, k$), with complex coefficients and all possible distributions of the original indices over the terms of the new sums. Using relation (111), we obtain

$$\begin{aligned} \left[-\frac{1}{q} \frac{(1-\tau^q)}{\tau^q} \tau \frac{d}{d\tau} \right]^c \Upsilon_{a_1, \dots, a_{k+1}; -; c; -}^{[p, q]}(\tau) &= \\ \sum_{\vec{s}, J} \left[c_{\vec{s}; -; J} \Upsilon_{\vec{s}; -; J}^{[p, q]}(\tau) + q\tau^{-p} d_{\vec{s}; -; J} \int_1^\tau dt \frac{t^{p-1}}{1-t^q} \Upsilon_{\vec{s}; -; J-1}^{[p, q]}(t) \right] . \end{aligned} \quad (128)$$

Let us set $c = 0$ and consider the two cases: (i) $J = 1$ and (ii) $J \geq 2$. For $J = 1$, the first term on the r.h.s. of Eq. (128) is expressible in terms of multiple polylogarithms. The last term on the r.h.s. of Eq. (128) has the structure of Eq. (126), so that, upon integration, it will again be expressible in terms of multiple polylogarithms of weight $k+1$. Due to the common factor τ^{-p} , the result agrees with **Proposition B**. For $J \geq 2$, both terms on the r.h.s. of Eq. (128) are expressible in terms of harmonic polylogarithms of weight $k+1$, as

$$\begin{aligned} \left[-\frac{1}{q} \frac{(1-\tau^q)}{\tau^q} \tau \frac{d}{d\tau} \right]^{c-1} \Upsilon_{a_1, \dots, a_{k+1}; -; c; -}^{[p, q]}(\tau) &= \\ \sum_{\vec{s}, J} \sum_{j=1}^q \left[c_{\vec{s}; -; J} \int_1^\tau \frac{dt}{t - \frac{1}{\lambda_q^j}} \Upsilon_{\vec{s}; -; J}^{[p, q]}(t) + d_{\vec{s}; -; J} \int_1^\tau dt \frac{\lambda_q^{jp}}{t - \frac{1}{\lambda_q^j}} q \int_1^{t_1} dt_1 \frac{t_1^{p-1}}{1-t_1^q} \Upsilon_{\vec{s}; -; J-1}^{[p, q]}(t_1) \right] . \end{aligned} \quad (129)$$

In this way, **Proposition B** is found to be valid for weight $k+1$. Consequently, **Proposition B** is proven for all weights. Therefore, for $c \geq 1$, **Corollary B** is also valid for the multiple binomial sums of weight $k+1$.

Applying the differential operator $z \frac{d}{dz} \equiv -\frac{1}{q} \frac{1-\tau^q}{\tau^q} \frac{d}{d\tau}$ repeatedly l times to the sum $\Upsilon_{a_1, \dots, a_r; -; c}^{[p, q]}(z)$, we can derive results for a similar sum with $c < 0$. Thus, **Theorem B** is

proven for multiple rational sums.

Remark VI

For the particular value $q = 2$ ($p = 1$), the multiple rational sums are reduced to multiple binomial sums, which were studied in Refs. [31,32,39], as

$$\begin{aligned} \Upsilon_{a_1, \dots, a_p; -; c; -}^{[1,2]}(z) &= \sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j + \frac{1}{2})}{\Gamma(\frac{3}{2}) \Gamma(j+1)} S_{a_1}(j-1) \cdots S_{a_p}(j-1) \\ &= 2 \sum_{j=1}^{\infty} \binom{2j}{j} \left(\frac{z}{4}\right)^j \frac{1}{j^c} \frac{1}{\binom{2j}{j}} S_{a_1}(j-1) \cdots S_{a_p}(j-1). \end{aligned} \quad (130)$$

In order to convert the results of Eq. (63) and **Theorem A** to the form presented in Refs. [31,32,39], is it necessary to introduce the new variable χ as

$$\tau = \frac{1-\chi}{1+\chi}.$$

4 All-order Laurent expansion of generalized hypergeometric functions with one rational parameter

In this section, we turn our attention to the proof of **Theorem C**. It is well known that any function ${}_pF_{p-1}(\vec{a} + \vec{m}; \vec{b} + \vec{k}; z)$ is expressible in terms of p other functions of the same type, as [52,53]

$$R_{p+1}(\vec{a}, \vec{b}, z) {}_pF_{p-1}(\vec{a} + \vec{m}; \vec{b} + \vec{k}; z) = \sum_{k=1}^p R_k(\vec{a}, \vec{b}, z) {}_pF_{p-1}(\vec{a} + \vec{e}_k; \vec{b} + \vec{E}_k; z), \quad (131)$$

where \vec{m} , \vec{k} , \vec{e}_k , and \vec{E}_k are lists of integers and R_k are polynomials in the parameters \vec{a} , \vec{b} , and z . Systematic methods for solving this problem were elaborated in Refs. [52,53]. For generalized hypergeometric functions of **Theorem C**, let us choose as the basis functions, appearing on the r.h.s. of Eq. (131), arbitrary p functions from the following set:

- for Eq. (4b), r^2 functions of the type

$${}_rF_{r-1} \left(\begin{matrix} 1 + \frac{p}{q}, \{1 + a_i \varepsilon\}^{r-L-1}, \{2 + d_i \varepsilon\}^L \\ \{1 + e_i \varepsilon\}^{r-Q-1}, \{2 + c_i \varepsilon\}^Q \end{matrix} \middle| z \right),$$

- for Eq. (4a), $r^2 - 1$ functions of the type

$${}_rF_{r-1} \left(\begin{matrix} \{1 + a_i \varepsilon\}^{r-L}, \{2 + d_i \varepsilon\}^L \\ 2 - \frac{p}{q}, \{1 + e_i \varepsilon\}^{r-Q-2}, \{2 + c_i \varepsilon\}^Q \end{matrix} \middle| z \right).$$

In the framework of the approach developed in Refs. [30,31,32,34,42], the study of the ε expansion of basis hypergeometric functions was reduced to the study of multiple (inverse) rational sums. It is easy to obtain the following representations:

$${}_rF_{r-1} \left(\begin{matrix} \{1+a_i\varepsilon\}^K, \{2+d_i\varepsilon\}^L \\ 2-\frac{p}{q}+b\varepsilon, \{1+e_i\varepsilon\}^R, \{2+c_i\varepsilon\}^Q \end{matrix} \middle| z \right) = \frac{1}{z} \left(1 - \frac{p}{q} + b\varepsilon \right) \frac{\prod_{s=1}^Q (1+c_s\varepsilon)}{\prod_{i=1}^L (1+d_i\varepsilon)} \sum_{j=1}^{\infty} \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1+j-\frac{p}{q}\right)} \frac{z^j}{j^{K-R-2}} \Delta, \quad (132a)$$

$${}_rF_{r-1} \left(\begin{matrix} 1+\frac{p}{q}+f\varepsilon, \{1+a_i\varepsilon\}^K, \{2+d_i\varepsilon\}^L \\ \{1+e_i\varepsilon\}^R, \{2+c_i\varepsilon\}^Q \end{matrix} \middle| z \right) = \frac{1}{z} \frac{\prod_{s=1}^Q (1+c_s\varepsilon)}{\prod_{i=1}^L (1+d_i\varepsilon)} \sum_{j=1}^{\infty} \frac{\Gamma\left(j+\frac{p}{q}\right)}{\Gamma(1+j)\Gamma\left(1+\frac{p}{q}\right)} \frac{z^j}{j^{K-R-1}} \Delta, \quad (132b)$$

where the superscripts K, L, R, Q indicate the lengths of the parameter lists,

$$\Delta = \exp \left\{ \sum_{k=1}^{\infty} \frac{(-\varepsilon)^k}{k} \left[w_k j^{-k} + S_k(n-1)t_k + b^k S_k^{[p,q]}(j) - f^k S_k^{[p,q]}(j-1) \right] \right\}, \quad (133)$$

$S_a(n) = \sum_{j=1}^n 1/j^a$ is a harmonic sum, and the constants are defined as

$$A_k \equiv \sum a_i^k, \quad C_k \equiv \sum c_i^k, \quad D_k \equiv \sum d_i^k, \quad E_k \equiv \sum e_i^k, \\ t_k \equiv C_k + E_k - A_k - D_k, \quad w_k \equiv C_k - D_k,$$

where the summations extend over all possible values of the parameters in Eq. (132). In this way, for $b = f = 0$, the ε expansions of the basis functions in Eq. (132) are seen to be expressible in terms of multiple (inverse) rational sums, which were studied in Section 3. But all these are expressible in terms of multiple polylogarithms. In this way, **Theorem C** is proven.

5 Two-loop sunset with two equal masses M , a third mass m , and external momentum $q^2 = -m^2$

The aim of this section is to find a hypergeometric representation for the two-loop sunset-type diagrams with the special kinematic configuration considered in Ref. [54]. The integral under investigation is

$$J_{122}^{(-)}(\alpha, \sigma_1, \sigma_2, m^2, M^2) = \int \int \frac{d^n k_1 d^n k_2}{[k_1^2 - M^2]^{\sigma_1} [(k_1 - k_2 - q)^2 - M^2]^{\sigma_2} [k_2^2 - m^2]^{\alpha}} \Big|_{q^2 = -m^2} \quad (134)$$

It is well known that, for arbitrary values of masses and momentum and powers of propagators, this integral is expressible in terms of Lauricella functions [25]. The hypergeometric

representation of the master integral with three equal masses and an arbitrary value of momentum was derived by Tarasov [27] in terms of Gauss hypergeometric functions and Appell functions F_2 . We now demonstrate, that for $q^2 = -m^2$, the master integrals are expressible in terms of generalized hypergeometric functions with quarter values of parameters.

Using the Mellin-Barnes representation [21], we obtain

$$\begin{aligned} J_{122}^{(-)}(\alpha, \sigma_1, \sigma_2, m^2, M^2) &= \frac{(-1)^{\sigma_1+\sigma_2+\alpha+1} (M^2)^{n/2-\sigma_1-\sigma_2} (m^2)^{n/2-\alpha}}{\Gamma(\sigma_1)\Gamma(\sigma_2)\Gamma(\alpha)\Gamma\left(\frac{n}{2}\right)} \\ &\quad \frac{1}{2\pi i} \int_{-i\infty}^{+i\infty} du \left(\frac{m^2}{M^2} \right)^u \frac{\Gamma(\sigma_1+u)\Gamma(\sigma_2+u)\Gamma(\sigma_1+\sigma_2-\frac{n}{2}+u)\Gamma(\frac{n}{2}+u)}{\Gamma(\sigma_1+\sigma_2+2u)} \\ &\quad \Gamma(-u)\Gamma\left(\alpha-\frac{n}{2}-u\right) {}_2F_1\left(\alpha-\frac{n}{2}-u, -u \middle| \frac{n}{2} \right). \end{aligned} \quad (135)$$

The Gauss hypergeometric function in this expression is of the form

$${}_2F_1\left(\begin{matrix} a, b \\ a-b+\alpha \end{matrix} \middle| -1\right),$$

where, by definition, α is a positive integer. Using the contiguous relations for Gauss hypergeometric functions [44,45], it is possible to express this hypergeometric function in terms of a linear combination of any two functions with parameters different by integers from the original ones. For our analysis, it is sufficient that the proper set of master integrals are expressible in terms of integrals with $\alpha = 1$ [55]. Closing the contour of integration at infinity in the right half-plane and summing over the residues of $\Gamma(-u)$ and $\Gamma(1-n/2-u)$, we obtain the sum of two hypergeometric series. Using the Kummer relation [56,57],

$${}_2F_1\left(\begin{matrix} a, b \\ 1+a-b \end{matrix} \middle| -1\right) = \frac{\Gamma(1+a-b)\Gamma(1+\frac{a}{2})}{\Gamma(1+a)\Gamma(1+\frac{a}{2}-b)},$$

where the hypergeometric series on the l.h.s. is defined if $a-b$, which is $n/2-1$ in our case, is not a negative integer, and substituting it in our series, we obtain a one-fold series representation which contains only products of Γ functions. In contrast to the previously studied cases [21], these series contain gamma functions of the type $\Gamma(a+k/2)$, where k is the index of summation and a is some number. To convert a series of this type into series of the generalized-hypergeometric-function type, we split the summation in one over the even and one over the odd values of the index, so that

$$\sum_{k=0}^{\infty} f(k) h\left(\frac{k}{2}\right) z^k = \sum_{j=0}^{\infty} \left[f(2j) h(j) + z f(2j+1) h\left(j + \frac{1}{2}\right) \right] (z^2)^j, \quad (136)$$

where h and f are arbitrary functions.⁷ Returning to our series, we like to mention that, after splitting the summation into even and odd parts, the term $1/\Gamma(\frac{1-k}{2})$, which comes from the residues of $\Gamma(-u)$, only contributes to the even part. Finally, we obtain

$$\begin{aligned}
J_{122}^{(-)}(1, \sigma_1, \sigma_2, m^2, M^2) = & \frac{(-1)^{\sigma_1+\sigma_2} (M^2)^{n/2-\sigma_1-\sigma_2} (m^2)^{n/2-1}}{\Gamma(\sigma_1)\Gamma(\sigma_2)} \\
& \left[\frac{\Gamma(1-\frac{n}{2})\Gamma(\sigma_1)\Gamma(\sigma_2)\Gamma(\sigma_1+\sigma_2-\frac{n}{2})}{\Gamma(\sigma_1+\sigma_2)} \right. \\
& \left. - \frac{m^4}{4M^4} \right] \\
& {}_6F_5 \left(\begin{matrix} \frac{\sigma_1}{2}, \frac{\sigma_1+1}{2}, \frac{\sigma_2}{2}, \frac{\sigma_2+1}{2}, \frac{2\sigma_1+2\sigma_2-n}{4}, \frac{2\sigma_1+2\sigma_2+2-n}{4} \\ \frac{n}{2}, \frac{\sigma_1+\sigma_2}{4}, \frac{\sigma_1+\sigma_2+1}{4}, \frac{\sigma_1+\sigma_2+2}{4}, \frac{\sigma_1+\sigma_2+3}{4} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \\
& + \left(\frac{m^2}{M^2} \right)^{(2-n)/2} \frac{\Gamma(1+\sigma_1-\frac{n}{2})\Gamma(1+\sigma_2-\frac{n}{2})\Gamma(1+\sigma_1+\sigma_2-n)\Gamma(\frac{n}{2}-1)}{\Gamma(\frac{n}{2})\Gamma(\sigma_1+\sigma_2+2-n)} \\
& {}_7F_6 \left(\begin{matrix} 1, \frac{2+2\sigma_1-n}{4}, \frac{2+2\sigma_2-n}{4}, \frac{4+2\sigma_1-n}{4}, \frac{4+2\sigma_2-n}{4}, \frac{\sigma_1+\sigma_2+1-n}{4}, \frac{\sigma_1+\sigma_2+2-n}{4} \\ \frac{2+n}{4}, \frac{6-n}{4}, \frac{\sigma_1+\sigma_2+2-n}{4}, \frac{\sigma_1+\sigma_2+3-n}{4}, \frac{\sigma_1+\sigma_2+4-n}{4}, \frac{\sigma_1+\sigma_2+5-n}{4} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \\
& + \frac{8}{n(4-n)} \left(\frac{m^2}{M^2} \right)^{(4-n)/2} \frac{\Gamma(2+\sigma_1-\frac{n}{2})\Gamma(2+\sigma_2-\frac{n}{2})\Gamma(\sigma_1+\sigma_2+2-n)}{\Gamma(\sigma_1+\sigma_2+4-n)} \\
& \left. {}_7F_6 \left(\begin{matrix} 1, \frac{2\sigma_1+4-n}{4}, \frac{2\sigma_2+4-n}{4}, \frac{2\sigma_1+6-n}{4}, \frac{2\sigma_2+6-n}{4}, \frac{\sigma_1+\sigma_2+2-n}{4}, \frac{\sigma_1+\sigma_2+3-n}{4} \\ \frac{4+n}{4}, \frac{8-n}{4}, \frac{\sigma_1+\sigma_2+4-n}{4}, \frac{\sigma_1+\sigma_2+5-n}{4}, \frac{\sigma_1+\sigma_2+6-n}{4}, \frac{\sigma_1+\sigma_2+7-n}{4} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right]. \quad (138)
\end{aligned}$$

Closing the contour of integration at infinity in the left half-plane and summing over the residues of the Γ functions, we obtain hypergeometric series in terms of the variable M^2/m^2 . The same results can be derived from the general formula for the analytical continuation of the generalized hypergeometric function.

The first and the last hypergeometric functions in Eq. (138) may be reduced by the Takayama-Zeilberger [52,53] algorithm to the basis function

$${}_4F_3 \left(\begin{matrix} 1+a_1\varepsilon, 1+a_2\varepsilon, \frac{3}{2}+c_1\varepsilon, \frac{3}{2}+c_2\varepsilon \\ 2+d\varepsilon, 2-\frac{1}{4}+b_1\varepsilon, 2-\frac{3}{4}+b_2\varepsilon \end{matrix} \middle| z \right) \quad (139)$$

and its derivatives. The second hypergeometric function in Eq. (138) belongs to the class

$${}_4F_3 \left(\begin{matrix} 1+a_1\varepsilon, 1+a_2\varepsilon, 1+a_3\varepsilon, \frac{3}{2}+c\varepsilon \\ \frac{3}{2}+d\varepsilon, 2-\frac{1}{4}+b_1\varepsilon, 2-\frac{3}{4}+b_2\varepsilon \end{matrix} \middle| z \right). \quad (140)$$

⁷ In particular, for the hypergeometric function, we have [56,58]

$$\begin{aligned}
{}_pF_q \left(\begin{matrix} a_1, \dots, a_p \\ b_1, \dots, b_q \end{matrix} \middle| z \right) = & {}_{2p}F_{2q+1} \left(\begin{matrix} \frac{a_1}{2}, \frac{a_1+1}{2}, \dots, \frac{a_p}{2}, \frac{a_p+1}{2} \\ \frac{1}{2}, \frac{b_1}{2}, \frac{b_1+1}{2}, \dots, \frac{b_q}{2}, \frac{b_q+1}{2} \end{matrix} \middle| 4^{p-q-1}z^2 \right) \\
& + z \frac{\prod_{i=1}^p a_i}{\prod_{j=1}^q b_j} {}_{2p}F_{2q+1} \left(\begin{matrix} \frac{a_1+1}{2}, \frac{a_1+2}{2}, \dots, \frac{a_p+1}{2}, \frac{a_p+2}{2} \\ \frac{3}{2}, \frac{b_1+1}{2}, \frac{b_1+2}{2}, \dots, \frac{b_q+1}{2}, \frac{b_q+2}{2} \end{matrix} \middle| 4^{p-q-1}z^2 \right). \quad (137)
\end{aligned}$$

The ε expansions of the hypergeometric functions appearing in Eq. (138) are expressible in terms of elliptic integrals, which have been found in Ref. [54], and their generalizations, which are beyond our consideration (see the discussion in Ref. [45]). Three master-integrals in $n = 4 - 2\varepsilon$ dimensions, where ε is a parameter of dimension regularization [2], correspond to $\sigma_1 = \sigma_2 = 1$, $\sigma_1 = 1, \sigma_2$, $\sigma_1 = \sigma_2 = 2$. We obtain from Eq. (138)

$$J_{122}^{(-)}(1, 1, 1, m^2, M^2) = -(M^2)^{-\varepsilon}(m^2)^{1-\varepsilon} \frac{\Gamma^2(1+\varepsilon)}{\varepsilon^2(1-\varepsilon)} \left[{}_4F_3 \left(\begin{matrix} 1, \frac{1}{2}, \frac{\varepsilon}{2}, \frac{1}{2} + \frac{\varepsilon}{2} \\ 2 - \varepsilon, \frac{3}{4}, \frac{5}{4} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right. \\ \left. + \left(\frac{M^2}{m^2}\right)^{1-\varepsilon} \frac{1}{(1-2\varepsilon)} {}_4F_3 \left(\begin{matrix} 1, -\frac{1}{2} + \frac{\varepsilon}{2}, \frac{\varepsilon}{2}, \varepsilon \\ \frac{3}{2} - \frac{\varepsilon}{2}, \frac{1}{4} + \frac{\varepsilon}{2}, \frac{3}{4} + \frac{\varepsilon}{2} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right. \\ \left. - \left(\frac{M^2}{m^2}\right)^{-\varepsilon} \frac{(1-\varepsilon)}{(2-\varepsilon)(1+2\varepsilon)} {}_4F_3 \left(\begin{matrix} 1, \frac{1}{2} + \frac{\varepsilon}{2}, \frac{1}{2} + \varepsilon, \varepsilon \\ 2 - \frac{\varepsilon}{2}, \frac{3}{4} + \frac{\varepsilon}{2}, \frac{5}{4} + \frac{\varepsilon}{2} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right], \quad (141a)$$

$$J_{122}^{(-)}(1, 1, 2, m^2, M^2) = \frac{1}{2}(M^2)^{-1-\varepsilon}(m^2)^{1-\varepsilon} \frac{\Gamma^2(1+\varepsilon)}{\varepsilon(1-\varepsilon)} \left[{}_4F_3 \left(\begin{matrix} 1, \frac{1}{2}, 1 + \frac{\varepsilon}{2}, \frac{1}{2} + \frac{\varepsilon}{2} \\ 2 - \varepsilon, \frac{3}{4}, \frac{5}{4} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right. \\ \left. - \left(\frac{M^2}{m^2}\right)^{1-\varepsilon} \frac{1}{\varepsilon} {}_4F_3 \left(\begin{matrix} 1, \frac{1}{2} + \varepsilon, \frac{\varepsilon}{2}, \varepsilon \\ \frac{3}{2} - \frac{\varepsilon}{2}, \frac{1}{4} + \frac{\varepsilon}{2}, \frac{3}{4} + \frac{\varepsilon}{2} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right. \\ \left. - 2 \left(\frac{M^2}{m^2}\right)^{-\varepsilon} \frac{(1-\varepsilon)}{(2-\varepsilon)(1+2\varepsilon)} {}_4F_3 \left(\begin{matrix} 1, \frac{1}{2} + \frac{\varepsilon}{2}, \frac{1}{2} + \varepsilon, 1 + \varepsilon \\ 2 - \frac{\varepsilon}{2}, \frac{3}{4} + \frac{\varepsilon}{2}, \frac{5}{4} + \frac{\varepsilon}{2} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right], \quad (141b)$$

$$J_{122}^{(-)}(1, 2, 2, m^2, M^2) = -(M^2)^{-2-\varepsilon}(m^2)^{1-\varepsilon} \Gamma^2(1+\varepsilon) \frac{(1+\varepsilon)}{\varepsilon(1-\varepsilon)} \left[\frac{1}{6} {}_4F_3 \left(\begin{matrix} 1, \frac{3}{2}, 1 + \frac{\varepsilon}{2}, \frac{3}{2} + \frac{\varepsilon}{2} \\ 2 - \varepsilon, \frac{5}{4}, \frac{7}{4} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right. \\ \left. - \left(\frac{M^2}{m^2}\right)^{1-\varepsilon} \frac{\varepsilon}{(1+\varepsilon)(1+2\varepsilon)} {}_4F_3 \left(\begin{matrix} 1, \frac{1}{2} + \varepsilon, 1 + \frac{\varepsilon}{2}, 1 + \varepsilon \\ \frac{3}{2} - \frac{\varepsilon}{2}, \frac{3}{4} + \frac{\varepsilon}{2}, \frac{5}{4} + \frac{\varepsilon}{2} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right. \\ \left. - \left(\frac{M^2}{m^2}\right)^{-\varepsilon} \frac{(1-\varepsilon)}{(2-\varepsilon)(3+2\varepsilon)} {}_4F_3 \left(\begin{matrix} 1, \frac{3}{2} + \frac{\varepsilon}{2}, \frac{3}{2} + \varepsilon, 1 + \varepsilon \\ 2 - \frac{\varepsilon}{2}, \frac{5}{4} + \frac{\varepsilon}{2}, \frac{7}{4} + \frac{\varepsilon}{2} \end{matrix} \middle| -\frac{m^4}{4M^4} \right) \right]. \quad (141c)$$

To cross-check our results, we evaluate the first few coefficients of the expansion of the original diagram in the large-mass limit [59] using our program packages [60] and compare it with the proper ε expansion following from the hypergeometric representation (141). In the latter case, using the relation

$${}_pF_{p-1} \left(\begin{Bmatrix} \{a_i\} \\ \{b_j\} \end{Bmatrix} \middle| z \right) = 1 + z \frac{\prod_{i=1}^p a_i}{\prod_{j=1}^{p-1} b_j} {}_pF_{p-1} \left(\begin{Bmatrix} 1, \{1+a_i\} \\ 2, \{1+b_j\} \end{Bmatrix} \middle| z \right), \quad (142)$$

all hypergeometric functions are reduced to one of the two “basic” ones,

$$\begin{aligned} {}_4F_3 \left(\begin{matrix} k_1+1+a_1\varepsilon, k_2+1+a_2\varepsilon, r_1+\frac{1}{2}+c_1\varepsilon, r_2+\frac{1}{2}+c_2\varepsilon \\ k_3+2+d\varepsilon, r_3+1+\frac{3}{4}+b_1\varepsilon, r_4+1+\frac{1}{4}+b_2\varepsilon \end{matrix} \middle| z \right) \\ {}_4F_3 \left(\begin{matrix} k_1+1+a_1\varepsilon, k_2+1+a_2\varepsilon, k_3+1+a_3\varepsilon, r_1+\frac{1}{2}+c_1\varepsilon \\ r_2+\frac{1}{2}+c_2\varepsilon, r_3+1+\frac{3}{4}+b_1\varepsilon, r_4+1+\frac{1}{4}+b_2\varepsilon \end{matrix} \middle| z \right), \end{aligned} \quad (143)$$

where $\{k_a\}$ are non-negative integers and $\{r_k\}$ are integers. Their ε expansions can be easily constructed with the help of Eq. (54a) and read

$$\begin{aligned} & {}_4F_3 \left(\begin{matrix} k_1+1+a_1\varepsilon, k_2+1+a_2\varepsilon, r_1+\frac{1}{2}+c_1\varepsilon, r_2+\frac{1}{2}+c_2\varepsilon \\ k_3+2+d\varepsilon, r_3+1+\frac{3}{4}+b_1\varepsilon, r_4+1+\frac{1}{4}+b_2\varepsilon \end{matrix} \middle| z \right) \\ &= \frac{1}{z} \frac{\Gamma(k_3+2)\Gamma(r_3+1+\frac{3}{4})\Gamma(r_4+1+\frac{1}{4})}{\Gamma(k_1+1)\Gamma(k_2+1)\Gamma(r_1+\frac{1}{2})\Gamma(r_2+\frac{1}{2})} \\ &\quad \times \sum_{j=1}^{\infty} z^j \frac{\Gamma(k_1+j)\Gamma(k_2+j)\Gamma(r_1-\frac{1}{2}+j)\Gamma(r_2-\frac{1}{2}+j)}{\Gamma(k_3+1+j)\Gamma(j)\Gamma(r_3+\frac{3}{4}+j)\Gamma(r_4+\frac{1}{4}+j)} \exp \left[\sum_{m=1}^{\infty} \frac{(-\varepsilon)^m}{m} \right. \\ &\quad \times \left(d^m S_m^{[1+k_3,1]}(j-1) - a_1^m S_m^{[k_1,1]}(j-1) - a_2^m S_m^{[k_2,1]}(j-1) \right. \\ &\quad \left. \left. + b_1^m S_m^{[4r_3+3,4]}(j-1) + b_2^m S_m^{[4r_4+1,4]}(j-1) - c_1^m S_m^{[2r_1-1,2]}(j-1) - c_2^m S_m^{[2r_2-1,2]}(j-1) \right) \right], \\ & {}_4F_3 \left(\begin{matrix} k_1+1+a_1\varepsilon, k_2+1+a_2\varepsilon, k_3+1+a_3\varepsilon, r_1+\frac{1}{2}+c_1\varepsilon \\ r_2+\frac{1}{2}+c_2\varepsilon, r_3+1+\frac{3}{4}+b_1\varepsilon, r_4+1+\frac{1}{4}+b_2\varepsilon \end{matrix} \middle| z \right) \\ &= \frac{1}{z} \frac{\Gamma(r_2+\frac{1}{2})\Gamma(r_3+2-\frac{1}{4})\Gamma(r_4+2-\frac{3}{4})}{\Gamma(k_1+1)\Gamma(k_2+1)\Gamma(k_3+1)\Gamma(r_1+\frac{1}{2})} \\ &\quad \times \sum_{j=1}^{\infty} z^j \frac{\Gamma(k_1+j)\Gamma(k_2+j)\Gamma(k_3+j)\Gamma(r_1-\frac{1}{2}+j)}{\Gamma(j)\Gamma(r_2-\frac{1}{2}+j)\Gamma(r_3+\frac{3}{4}+j)\Gamma(r_4+\frac{1}{4}+j)} \exp \left[\sum_{m=1}^{\infty} \frac{(-\varepsilon)^m}{m} \right. \\ &\quad \times \left(-a_1^m S_m^{[k_1,1]}(j-1) - a_2^m S_m^{[k_2,1]}(j-1) - a_3^m S_m^{[k_3,1]}(j-1) \right. \\ &\quad \left. \left. + b_1^m S_m^{[4r_3+3,4]}(j-1) + b_2^m S_m^{[4r_4+1,4]}(j-1) - c_1^m S_m^{[2r_1-1,2]}(j-1) + c_2^m S_m^{[2r_2-1,2]}(j-1) \right) \right], \end{aligned} \quad (144)$$

where $S_c^{[a,b]}(j)$ is defined by Eq. (58). Both kinds of expansions, the large-mass and hypergeometric one, yield the same results, which also agree with Eqs. (16)–(18) of Ref. [54].

6 Discussion and Conclusion

The proof of **Theorems I** includes two steps: (i) the algebraic reduction of Gauss hypergeometric functions of the type in **Theorem I** to basic functions and (ii) the iterative

algorithms for calculating the analytical coefficients of the ε expansions of the latter. Step (i) is well known [44,45], and, in step (ii), the algorithm is constructed for rational values of the parameters [see Eqs. (28), (39), (43) and (46)]. This allows us to calculate the coefficients directly, without reference to multiple sums. It is interesting to note that the Laurent expansions of the Gauss hypergeometric functions with one rational upper parameter are expressible in terms of multiple polylogarithms times powers of a logarithm, as shown in Section 2.1.3. We presented in Eq. (53) an algebraic relation between Gauss hypergeometric functions which allows us to find linear relations between special values of multiple polylogarithms.

We constructed an iterative solution for multiple (inverse) rational sums defined by Eqs. (65) and (100). It was shown that, by appropriate change of variables, defined by Eqs. (18) and (40), the multiple (inverse) rational sums may be converted into multiple polylogarithms (see **Theorem A** and **Theorem B**). Symbolically, this may be expressed

as

$$\sum_{j=1}^{\infty} z^j \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_{a_1}(j-1) S_{a_2}(j-1) \cdots S_{a_k}(j-1) \Big|_{z=z(\xi)} \\ = \xi^p \sum_{\substack{\vec{J}, \vec{s} \\ \sum_{k=1}^r s_k = 1+a_1+\cdots+a_p}} c_{\vec{J}, \vec{s}} \text{Li}_{\vec{s}}\left(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} \xi\right), \quad (145)$$

$1 \leq \{j_m\} \leq q$

$$\sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma(j)\Gamma\left(1-\frac{p}{q}\right)}{\Gamma\left(1+j-\frac{p}{q}\right)} S_{a_1}(j-1) S_{a_2}(j-1) \cdots S_{a_k}(j-1) \Big|_{z=z(\xi)} \\ = \sum_{\substack{\vec{J}, \vec{s} \\ \sum_{k=1}^r s_k = 1+c+a_1+\cdots+a_p}} \tilde{c}_{\vec{J}, \vec{s}} \text{Li}_{\vec{s}}\left(\lambda_q^{j_1-j_2}, \lambda_q^{j_2-j_3}, \dots, \lambda_q^{j_{r-1}-j_r}, \lambda_q^{j_r} \xi\right) \quad (c \geq 1), \quad (146)$$

$1 \leq \{j_m\} \leq q$

$$\sum_{j=1}^{\infty} z^j \frac{\Gamma\left(j+\frac{p}{q}\right)}{\Gamma(j+1)\Gamma\left(1+\frac{p}{q}\right)} S_{a_1}(j-1) S_{a_2}(j-1) \cdots S_{a_k}(j-1) \Big|_{z=z(\tau)} \\ = \sum_{\vec{J}, \vec{s}, k} \left(c_{\vec{J}, \vec{s}, k} + d_{\vec{J}, \vec{s}, k} \tau^{-p} \right) \ln^k \tau \left[\text{Li}_{\vec{s}}\left(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r} \tau\right) - \text{Li}_{\vec{s}}\left(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r}\right) \right], \quad (147)$$

$$\sum_{j=1}^{\infty} \frac{z^j}{j^c} \frac{\Gamma\left(j+\frac{p}{q}\right)}{\Gamma(j+1)\Gamma\left(1+\frac{p}{q}\right)} S_{a_1}(j-1) S_{a_2}(j-1) \cdots S_{a_k}(j-1) \Big|_{z=z(\tau)} \\ = \sum_{\vec{J}, \vec{s}, k} \tilde{d}_{\vec{J}, \vec{s}, k} \ln^k \tau \left[\text{Li}_{\vec{s}}\left(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r} \tau\right) - \text{Li}_{\vec{s}}\left(\lambda_q^{j_1-j_2}, \dots, \lambda_q^{j_r}\right) \right] \quad (c \geq 1), \quad (148)$$

where $\{c_{\vec{J}, \vec{s}}, \tilde{c}_{\vec{J}, \vec{s}}, d_{\vec{J}, \vec{s}}, \tilde{d}_{\vec{J}, \vec{s}}\} \in \mathbb{C}$ are numerical coefficients, the weight of the l.h.s. equals the weight of the r.h.s., and

$$S_a(j-1) = \sum_{i=1}^{j-1} \frac{1}{i^a},$$

is a harmonic series.

Unfortunately, one of the unsolved problems is the completeness of the representation in Eqs. (146) and (148). In other words, is it possible to express all multiple polylogarithms in terms of multiple (inverse) harmonic sums? If not, what kind of sums must be added

to obtain a complete basis? Another problem beyond our present considerations is to find the algebraic relations between the sums.

Using the results of **Theorem A** and **Theorem B**, we proved **Theorem C** about the all-order ε expansion of a special class of hypergeometric functions. The proof includes two steps: (i) the algebraic reduction of generalized hypergeometric functions of the type specified in **Theorem C** to basic functions and (ii) the algorithms for calculating the analytical coefficients of the ε expansions of the basic hypergeometric functions. The implementation of step (i), the reduction algorithm, is based on general considerations made in Refs. [52,53]. In step (ii), the algorithm is based on the series representation of the basis hypergeometric functions defined by Eq. (132). The coefficients of the ε expansions are expressible in terms of multiple (inverse) rational sums, to which **Theorem A** and **Theorem B** apply.

Finally, we demonstrated, in Section 5, that Feynman diagrams produce hypergeometric functions with quarter values of parameters.

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A Hyperlogarithms and multiple polylogarithms

For completeness, we present a definition of multiple polylogarithms and some relations that are useful for our considerations. We are guided by the analyses presented in Refs. [9,10,61,62].

The starting point of our consideration is the integral

$$\begin{aligned} I(a_k, a_{k-1}, \dots, a_1; z) &= \int_0^z \frac{dt_k}{t_k - a_k} \int_0^{t_k} \frac{dt_{k-1}}{t_{k-1} - a_{k-1}} \cdots \int_0^{t_2} \frac{dt_1}{t_1 - a_1} \\ &= \int_0^z \frac{dt}{t - a_k} I(a_{k-1}, \dots, a_1; t), \end{aligned} \quad (149)$$

where we assume that all $a_k \neq 0$. In early considerations by Kummer, Poincare, and Lappo-Danilevky [7,8], this integral was called hyperlogarithm. It was treated as an analytical function in the single variable z , the upper limit of integration. Goncharov [9] analyzed it as multivalued analytical function of a_1, \dots, a_k, z . One of the properties of hyperlogarithms is the scaling invariance,

$$I(a_1, \dots, a_k; z) = I\left(\frac{a_1}{z}, \dots, \frac{a_k}{z}; 1\right). \quad (150)$$

A special case of this integral is the following one:

$$\begin{aligned}
& G_{m_k, m_{k-1}, \dots, m_1}(a_k, \dots, a_1; z) \\
& \equiv I(\underbrace{0, \dots, 0}_{m_{k-1} \text{ times}}, a_k, \underbrace{0, \dots, 0}_{m_{k-1}-1 \text{ times}}, a_{k-1}, \dots, \underbrace{0, \dots, 0}_{m_1-1 \text{ times}}, a_1; z) \\
& = (-1)^k \sum_{j_1=1}^{\infty} \cdots \sum_{j_k=1}^{\infty} \frac{1}{j_1^{m_1}} \left(\frac{z}{a_1} \right)^{j_1} \frac{1}{(j_1+j_2)^{m_2}} \left(\frac{z}{a_2} \right)^{j_2} \cdots \frac{1}{(j_1+j_2+\cdots+j_k)^{m_k}} \left(\frac{z}{a_k} \right)^{j_k},
\end{aligned} \tag{151}$$

where all $a_k \neq 0$. The last sum can be rewritten as

$$\begin{aligned}
& \sum_{j_1=1}^{\infty} \cdots \sum_{j_k=1}^{\infty} \frac{1}{j_1^{m_1}} \left(\frac{z}{a_1} \right)^{j_1} \frac{1}{(j_1+j_2)^{m_2}} \left(\frac{z}{a_2} \right)^{j_2} \\
& \quad \cdots \frac{1}{(j_1+j_2+\cdots+j_{k-1})^{m_{k-1}}} \left(\frac{z}{a_{k-1}} \right)^{j_{k-1}} \frac{1}{(j_1+j_2+\cdots+j_k)^{m_k}} \left(\frac{z}{a_k} \right)^{j_k} \\
& = \sum_{j_1=1}^{\infty} \cdots \sum_{j_k=1}^{\infty} \frac{1}{j_1^{m_1}} \left(\frac{a_2}{a_1} \right)^{j_1} \frac{1}{(j_1+j_2)^{m_2}} \left(\frac{a_3}{a_2} \right)^{j_1+j_2} \\
& \quad \cdots \frac{1}{(j_1+\cdots+j_{k-1})^{m_{k-1}}} \left(\frac{a_k}{a_{k-1}} \right)^{j_1+j_2+\cdots+j_{k-1}} \frac{1}{(j_1+\cdots+j_k)^{m_k}} \left(\frac{z}{a_k} \right)^{j_1+j_2+\cdots+j_k} \\
& = \sum_{n_k > n_{k-1} > \cdots > n_1 > 0}^{\infty} \frac{1}{n_1^{m_1}} \left(\frac{a_2}{a_1} \right)^{n_1} \frac{1}{n_2^{m_2}} \left(\frac{a_3}{a_2} \right)^{n_2} \cdots \frac{1}{n_k^{m_k}} \left(\frac{z}{a_k} \right)^{n_k}.
\end{aligned} \tag{152}$$

By definition, the multiple polylogarithm is [9]

$$\text{Li}_{k_1, k_2, \dots, k_n}(x_1, x_2, \dots, x_n) = \sum_{m_n > m_{n-1} > \cdots > m_1 > 0}^{\infty} \frac{x_1^{m_1} x_2^{m_2} \cdots x_n^{m_n}}{m_1^{k_1} m_2^{k_2} \cdots m_n^{k_n}}, \tag{153}$$

with weight $k = k_1 + k_2 + \cdots + k_n$ and depth n . From relations (151), (152), and (153), we have

$$G_{m_n, m_{n-1}, \dots, m_2, m_1}(x_n, x_{n-1}, \dots, x_2, x_1; z) = (-1)^n \text{Li}_{m_1, m_2, \dots, m_n} \left(\frac{x_2}{x_1}, \frac{x_3}{x_2}, \dots, \frac{z}{x_n} \right). \tag{154}$$

The inverse relation is

$$\text{Li}_{k_1, k_2, \dots, k_n}(y_1, y_2, \dots, y_n) = (-1)^n G_{k_n, k_{n-1}, \dots, k_2, k_1} \left(\frac{1}{y_n}, \frac{1}{y_n y_{n-1}}, \dots, \frac{1}{y_1 \cdots y_n}; 1 \right). \tag{155}$$

In particular, we have

$$\begin{aligned}
G_1(a; z) &= \int_0^z \frac{dt}{t-a} = - \sum_{j=1}^{\infty} \frac{z^j}{ja^j} = \ln \left(1 - \frac{z}{a} \right) = -\text{Li}_1 \left(\frac{z}{a} \right) , \\
G_k(a; z) &= \int_0^z \frac{dt_k}{t_k} \int_0^{t_k} \frac{dt_{k-1}}{t_{k-1}} \cdots \int_0^{t_2} \frac{dt_1}{t_1-a} = - \sum_{j=1}^{\infty} \frac{z^j}{j^k a^j} = -\text{Li}_k \left(\frac{z}{a} \right) , \\
G_{1,1}(a_2, a_1; z) &= \int_0^z \frac{dt_1}{t_1-a_2} \int_0^{t_1} \frac{dt_2}{t_2-a_1} \\
&= \sum_{j_1=1}^{\infty} \sum_{j_2=1}^{\infty} \frac{1}{j_1} \left(\frac{z}{a_1} \right)^{j_1} \frac{1}{(j_1+j_2)} \left(\frac{z}{a_2} \right)^{j_2} = \text{Li}_{1,1} \left(\frac{a_2}{a_1}, \frac{z}{a_2} \right) . \tag{156}
\end{aligned}$$

The multiple polylogarithms form two Hopf algebras, the so-called shuffle and stuffle ones. The first one is related to the integral representation, the second one to the series.

Integral (149) is an iterated Chen integral [63] w.r.t. the differential one-forms

$$\omega_0 = \frac{dy}{y}, \quad \omega_a = \frac{dy}{y-a}, \tag{157}$$

where a is any number, so that

$$G_{m_k, m_{k-1}, \dots, m_1}(a_k, \dots, a_1; z) = \int_0^z \omega_0^{m_k-1} \omega_{a_k} \omega_0^{m_{k-1}-1} \omega_{a_{k-1}} \cdots \omega_0^{m_1} \omega_{a_1}. \tag{158}$$

A special consideration is necessary when the last few arguments $a_{k-j}, a_{k-j-1}, \dots, a_k$ in the integral $I(a_1, a_k; z)$ in Eq. (149) are equal to zero, which is the so-called trailing-zero case. It is possible to factorise such a kind of contribution into a product of a power of a logarithm and an integral of the type described in Eq. (149). An appropriate procedure was described for generalized polylogarithms of the square root of unity, the Remiddi-Vermaseren functions, in Ref. [3] and extended on the case of hyperlogarithms in Ref. [62]. These may be written in the form

$$I(\vec{A}, \vec{0}; z) = \sum_{p, \vec{A}} c_{p, \vec{A}} \ln^p z I_{k_1, k_2, \dots, k_{n-p}}(\vec{B}; z), \tag{159}$$

where the coefficients $c_{p, \vec{A}}$ are rational numbers and the components of vector \vec{B} are shuffle products of the components of the original vectors \vec{A} and $\vec{0}$. In Eq. (159), the weight of the l.h.s. is equal to the weight of the r.h.s.

B Iterative solution of first-order differential equation

A system of homogeneous linear differential equations,

$$\frac{d}{dt} \vec{u}(t) = A(t, \vec{u}(t)),$$

where A is an $n \times n$ matrix and \vec{u} is an n -dimensional vector, can be formally written via Picard's method of approximation as

$$\begin{aligned}\vec{u}_1 &= \vec{u}_0 + \int_{u_0}^t A(t, \vec{u}_0) dt , \\ \vec{u}_2 &= \vec{u}_0 + \int_{u_0}^t A(t, \vec{u}_1(t)) dt , \\ &\dots \\ \vec{u}_n &= \vec{u}_0 + \int_{u_0}^t A(t, \vec{u}_{n-1}(t)) dt ,\end{aligned}\tag{160}$$

where $\vec{u}_0 = \vec{u}(t_0)$ is an initial condition. It can be proven [8,64] that, in the region where this integral exists, the following properties are satisfied: (i) as n increases indefinitely, the sequence of functions \vec{u}_n tends to a limit which is a continuous function of t ; (ii) this limiting function satisfies the differential equation; (iii) the solution thus defined assumes the value \vec{u}_0 when $t = t_0$ and is the only continuous solution which does so.

Let us introduce the set of functions,

$$F_p(t) = \int_{t_0}^t d\tau A(\tau) F_{p-1}(\tau) ,\tag{161}$$

and write the relations (160) as

$$\vec{u}(t) = F_0(t) u_0 + \dots + F_p(t) u_0 + \dots ,\tag{162}$$

where F_0 is the identical transformation, $F_0 = I$. For $A(t) = \sum_j \frac{U_j}{t - \alpha_j}$, the iterative solution coincides with hyperlogarithms of configuration α_j .

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