# Classification of complete projective special real surfaces 

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February 18, 2013


#### Abstract

We determine all complete projective special real surfaces. By the supergravity r-map, they give rise to complete projective special Kähler manifolds of dimension 6 , which are distinguished by the image of their scalar curvature function. By the supergravity c-map, the latter manifolds define in turn complete quaternionic Kähler manifolds of dimension 16.


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## 6 Classification of complete projective very special Kähler manifolds of complex dimension 3

## Introduction

Projective special real manifolds first occurred as the scalar manifolds of certain supergravity theories in five space-time dimensions [GST, DV1], see Definition 1 below. Their geometry is encoded in a homogeneous cubic polynomial. A typical example occurring in string theory is the geometry defined by the cubic form on $H^{1,1}(X, \mathbb{R})$ for a Kähler manifold $X$ of complex dimension 3. It was shown in CHM, using constructions from supergravity, that any complete projective special real manifold of dimension $n$ defines a complete projective special Kähler manifold of (real) dimension $2 n+2$ and a complete quaternionic Kähler manifold of dimension $4 n+8$. For that reason it is interesting to find examples of complete projective special real manifolds. Let us also mention that the completeness (or incompleteness) of the scalar manifold in the underlying supergravity theories is related to the global behaviour of solutions to the equations of motion. This is due to the fact that the scalar fields of the theory cannot approach infinity along a trajectory of finite length if the manifold is complete.

In this paper we classify all complete projective special real surfaces:

Theorem 1 There exist precisely five discrete examples and a one-parameter family of complete projective special real surfaces, up to isomorphism:
a) $\left\{(x, y, z) \in \mathbb{R}^{3} \mid x y z=1, x>0, y>0\right\}$,
b) $\left\{(x, y, z) \in \mathbb{R}^{3} \mid x\left(x y-z^{2}\right)=1, x>0\right\}$,
c) $\left\{(x, y, z) \in \mathbb{R}^{3} \mid x\left(y z+x^{2}\right)=1, x<0, y>0\right\}$,
d) $\left\{(x, y, z) \in \mathbb{R}^{3} \mid z\left(x^{2}+y^{2}-z^{2}\right)=1, z<0\right\}$,
e) $\left\{(x, y, z) \in \mathbb{R}^{3} \mid x\left(y^{2}-z^{2}\right)+y^{3}=1, y<0, x>0\right\}$,
f) $\left\{(x, y, z) \in \mathbb{R}^{3} \mid y^{2} z-4 x^{3}+3 x z^{2}+b z^{3}=1, z<0,2 x>z\right\}$, where $b \in(-1,1) \subset \mathbb{R}$.

In Sections 1 团 we prove Theorem 1 essentially by first determining all homogeneous cubic polynomials $h$ on $\mathbb{R}^{3}$ such that the surface $\{h=1\} \subset \mathbb{R}^{3}$ has a strictly locally convex
component $\mathcal{H}$ of hyperbolic type. It turns out that, up to linear transformations, the resulting surfaces $\mathcal{H}$ of hyperbolic type are precisely those listed in Theorem 1 . Then we prove in all cases that $\mathcal{H}$ is complete with respect to the Riemannian metric $g_{\mathcal{H}}$ induced by the Hessian of $-h$. At present we do not know, in dimensions $n \geq 3$, whether a projective special real manifold $\mathcal{H} \subset \mathbb{R}^{n+1}$ which is closed as a subset of $\mathbb{R}^{n+1}$ is necessarily complete with respect to the metric $g_{\mathcal{H}}$, see open problem on page 12. The converse statement, however, can be easily proven in all dimensions.

In Section 5 we provide general formulas for the curvature of the Kähler manifolds obtained from the generalized r-map defined in [CHM]. This is applied in Section 6 to the projective special Kähler manifolds of complex dimension 3 obtained from the projective special real surfaces of Theorem 1 . Computing the scalar curvature we prove, in particular, that the complete projective special real manifolds c)-f) of Theorem 1 as well as the corresponding complete projective special Kähler manifolds are not locally homogeneous as Riemannian manifolds. The family of projective special Kähler manifolds associated with the Weierstraß polynomials $h_{b}=y^{2} z-4 x^{3}+3 x z^{2}+b z^{3}, b \in(-1,1)$, seems to be the first example of a continuous family of complete projective special Kähler manifolds.

Let us finally mention that applying the supergravity c-map to our examples one obtains complete quaternionic Kähler manifolds of dimension 16, which have negative scalar curvature and cohomogeneity less than or equal to 2 . More precisely, there exists a group of isometries which has cohomogeneity $k$, where $k$ is the cohomogeneity of the initial projective special real manifold under the full group of linear automorphisms, that is $k=0$ in the cases a) and b), $k=1$ in the case c) and d) and $k=2$ in the cases e) and f$)$. We expect that the same is true for the full isometry group of the quaternionic Kähler manifold.

Acknowledgments This work is part of a research project within the RTG 1670 "Mathematics inspired by String Theory", funded by the Deutsche Forschungsgemeinschaft (DFG).

## 1 Statement of the classification problem

Let $h$ be a homogeneous cubic polynomial function on $\mathbb{R}^{n+1}$ and $U \subset \mathbb{R}^{n+1}$ a domain invariant under multiplication by positive numbers such that $\left.h\right|_{U}>0$. Then

$$
\mathcal{H}:=\{x \in U \mid h(x)=1\} \subset U
$$

is a smooth hypersurface and $-\partial^{2} h$ induces a symmetric tensor field $g_{\mathcal{H}}$ on $\mathcal{H}$.

Definition 1 If $g_{\mathcal{H}}$ is positive definite then the hypersurface $\mathcal{H} \subset \mathbb{R}^{n+1}$ is called a projective special real manifold. Two projective special real manifolds $\mathcal{H}, \mathcal{H}^{\prime} \subset \mathbb{R}^{n+1}$ are called isomorphic if there exists $\varphi \in \mathrm{GL}(n+1)$ mapping $\mathcal{H}$ to $\mathcal{H}^{\prime}$.

## Remark 1

1) In the above situation $\left.\varphi\right|_{\mathcal{H}}: \mathcal{H} \rightarrow \mathcal{H}^{\prime}$ is an isometry.
2) For any projective special real manifold $\mathcal{H} \subset \mathbb{R}^{n+1}$ the tensor field $-\partial^{2} h$ is a Lorentzian metric on $U=\mathbb{R}^{>0} \cdot \mathcal{H} \subset \mathbb{R}^{n+1}$. In particular, $(-1)^{n} \operatorname{det} \partial^{2} h>0$ on $U$.

The classification of complete projective special real surfaces up to isomorphism can be separated into two problems. First we have to determine all homogeneous cubic polynomials $h$ on $\mathbb{R}^{3}$, up to linear transformations, which are hyperbolic, that is admit a point $p \in \mathbb{R}^{3}$ such that $h(p)>0$ and $\partial^{2} h$ is negative definite on the kernel of $d h_{p}$. We can assume that $h(p)=1$. Then there exists a maximal connected neighborhood $\mathcal{H}$ of $p$ in the level set $\{h=1\}$ such that $\mathcal{H}$ is a projective special real surface. The second problem is then to check whether $\left(\mathcal{H}, g_{\mathcal{H}}\right)$ is a complete Riemannian manifold.

## 2 Classification of cubic polynomials

In this section we provide the needed classification of homogeneous real cubic polynomials $h$ in three variables up to linear transformations. We will say that two polynomials are equivalent if they are related by a linear transformation. This problem is equivalent to the classification of cubic curves in the real projective plane. The study of real plane cubic curves goes back to Newton [N]. For the classification of complex plane cubic curves up to projective transformations see the textbooks $[\mathrm{BK}, \mathrm{H}$.

Let us first consider the case when $h$ is reducible, that is a product of homogeneous polynomials of degree 1 or 2 .

Proposition 1 Any reducible homogeneous cubic polynomial on $\mathbb{R}^{3}$ is equivalent to one of the following:
(i) $x^{3}$,
(ii) $x^{2} y$,
(iii) $x y(x+y)$,
(iv) $x y z$,

$$
\begin{aligned}
& \text { (v) } x\left(x^{2}+y^{2}\right), \\
& \text { (vi) } z\left(x^{2}+y^{2}\right) \\
& \text { (vii) } x\left(x^{2}+y^{2}+z^{2}\right), \\
& \text { (viii) } z\left(x^{2}+y^{2}-z^{2}\right), \\
& \text { (ix) } x\left(x^{2}+y^{2}-z^{2}\right), \\
& \text { (x) }(y+z)\left(x^{2}+y^{2}-z^{2}\right) \text {. }
\end{aligned}
$$

The proof is a simple exercise. Notice that the first 4 cases are products of linear factors and are the same as in the complex case. The remaining 6 polynomials contain an irreducible quadratic polynomial as a factor. Over $\mathbb{C}$ there are only 2 such polynomials.

Next we consider the case of singular curves $C=\{h=0\} \subset \mathbb{R} P^{2}$.
Proposition 2 Any irreducible homogeneous cubic polynomial $h$ on $\mathbb{R}^{3}$ such that the curve $C=\{h=0\} \subset \mathbb{R} P^{2}$ has a singularity is equivalent to one of the following:
(xi) $x\left(y^{2}+z^{2}\right)+y^{3}$,
(xii) $x\left(y^{2}-z^{2}\right)+y^{3}$,
(xiii) $x z^{2}+y^{3}$.

Proof: We can assume that $h$ and $d h$ vanish at $P=(1,0,0)$. Then we decompose $h=x q+r$, where $q=q(y, z)$, and $r=r(x, y, z) \neq 0$ does not contain any monomial summands linear in $x$. Now the conditions $h(P)=0$ and $\partial_{y} h(P)=\partial_{z} h(P)=0$ easily imply that $r=r(y, z)$. By a linear transformation we can obviously assume that $q \in$ $\left\{y^{2}+z^{2}, y^{2}-z^{2}, z^{2}\right\}$. In the last two cases, one can use the same linear transformation as in the complex case to bring $h$ to the form (xii) and (xiii), respectively, cf. [H]. Therefore it suffices to consider the case $q=y^{2}+z^{2}$. The vector space $S \cong S^{3}\left(\mathbb{R}^{2}\right)^{*}$ of homogeneous cubic polynomials in the variables $(y, z)$ is decomposed as a sum of two irreducible $\mathrm{O}(2)$ modules:

$$
S^{3}\left(\mathbb{R}^{2}\right)^{*}=\left(\mathbb{R}^{2}\right)^{*} q \oplus \operatorname{span}\left\{y^{3}-3 y z^{2}, z^{3}-3 y^{2} z\right\}
$$

Using a homothety in the ( $y, z$ )-plane we can thus assume that $r \equiv y^{3}-3 y z^{2}$ modulo $\left(\mathbb{R}^{2}\right)^{*} q$. Furthermore, by a linear transformation preserving $y$ and $z$ we can freely change the $\left(\mathbb{R}^{2}\right)^{*} q$-component of $r$. For instance, we can take it to be $3 y q$, which implies $r=4 y^{3}$. Now it suffices to rescale $x$ and ( $y, z$ ) to bring $h$ to the form (xi).

Finally, the classification of smooth irreducible real cubic curves is provided by the Weierstraß normal form.

Proposition 3 Let $h$ be an irreducible homogeneous cubic polynomial on $\mathbb{R}^{3}$ such that the curve $C=\{h=0\} \subset \mathbb{R} P^{2}$ is smooth. Then $h$ is equivalent to a Weierstraß cubic polynomial

$$
y^{2} z-4 x^{3}+a x z^{2}+b z^{3}
$$

of nonzero discriminant $a^{3}-27 b^{2}$, for some $a, b \in \mathbb{R}$.

Proof: By Bezout's theorem, we know that $C$ has 9 complex inflection points [BK, H]. Since, the imaginary inflection points occur in pairs one of them has to be real. Therefore the same proof as in the complex case applies $[\mathrm{H}]$.

Remark 2 Note that some of the Weierstraß cubic polynomials given in Proposition 3 are linearly equivalent. From the classification of smooth cubics over $\mathbb{C}$, we know that two Weierstraß cubics are inequivalent if they have different j-invariants (see $\mathrm{BK}, \mathrm{H}$ )

$$
j(a, b):=\frac{a^{3}}{a^{3}-27 b^{2}} .
$$

## 3 Classification of hyperbolic polynomials

In this section we study the hyperbolicity of the polynomials given in Propositions 1 and 2. The study of Weierstraß polynomials with nonzero discriminant is postponed to Subsection 4.1.

Proposition 4 Let $h$ be a hyperbolic homogeneous cubic polynomial on $\mathbb{R}^{3}$. Then either $h$ is equivalent to a Weierstraß cubic polynomial with nonzero discriminant or to one of the following:

1) $x y z$,
2) $z\left(x^{2}+y^{2}-z^{2}\right)$,
3) $x\left(x^{2}+y^{2}-z^{2}\right)$,
4) $(y+z)\left(x^{2}+y^{2}-z^{2}\right)$,
5) $x\left(y^{2}+z^{2}\right)+y^{3}$,
6) $x\left(y^{2}-z^{2}\right)+y^{3}$,
7) $x z^{2}+y^{3}$.

Proof: In the following we will denote by $g$ the symmetric tensor field on the surface $\{h=1\}$, which is induced by $-\partial^{2} h$. We have to decide whether $-\partial^{2} h(p)$ is Lorentzian for some $p \in\{h=1\}$ or, equivalently, whether $g_{p}$ is positive definite for some $p \in\{h=1\}$.

The polynomials (i-iii) and (v) in Proposition 1 do not depend on $z$. Hence, their Hessian is everywhere degenerate. We claim that also (vi) and (vii) are not hyperbolic, which leaves us with the cases 1)-7). In the case (vi), $\operatorname{det} \partial^{2} h=-8 h$ is negative on $\{h=1\}$. Therefore, $h$ is not hyperbolic. In the case (vii), $\operatorname{det} \partial^{2} h=8\left(4 x^{3}-h\right)$, which is positive precisely on those points of $\{h=1\}$ for which $x>\frac{1}{\sqrt[3]{4}}$. Next we observe that $\operatorname{det}\left(\begin{array}{ll}h_{y y} & h_{y z} \\ h_{z y} & h_{z z}\end{array}\right)=4 x^{2}$ and $h_{z z}=2 x$ are positive for $x>\frac{1}{\sqrt[3]{4}}$, where the subscripts denote partial derivatives. This shows that $\partial^{2} h$ is positive definite on the set $\left\{\operatorname{det} \partial^{2} h>\right.$ $0\} \cap\{h>0\}$. In particular, $h$ is not hyperbolic. Now we prove that the remaining polynomials are all hyperbolic. The polynomials 1), 3) and 4) give rise to the complete projective special real surfaces a)-c) in Theorem 1, which were already discussed in CHM. In fact, $x\left(x^{2}+y^{2}-z^{2}\right)$ is equivalent to $x y z+x^{3}$ and $(y+z)\left(x^{2}+y^{2}-z^{2}\right)$ to $x\left(x y-z^{2}\right)$. In case 2), $\operatorname{det} \partial^{2} h=-8\left(4 z^{3}+h\right)$, which is positive precisely on those points of $\{h=1\}$ for which $z<-\frac{1}{\sqrt[3]{4}}$. Since $\partial_{x}^{2} h=2 z$, we see that the subset of $\{h=1\}$ on which $g$ is Riemannian is nonempty and coincides with the subset on which $\operatorname{det} \partial^{2} h>0$. This subset is precisely the surface d) in Theorem 11. In fact, $z<0$ and $h=1$ imply $z \leq-1<-\frac{1}{\sqrt[3]{4}}$. In case 5), the surface $\{h=1\}$ is a graph

$$
x=\frac{1-y^{3}}{y^{2}+z^{2}}
$$

over the domain $\mathbb{R}^{2} \backslash\{0\}$ in the ( $y, z$ )-plane. The (nonempty) subset on which $g$ is Riemannian is

$$
\left\{(y, z) \in \mathbb{R}^{2} \mid y\left(y^{2}-3 z^{2}\right)-1>0\right\} .
$$

This follows from $\operatorname{det} \partial^{2} h=8\left(y\left(y^{2}-3 z^{2}\right)-h\right)$, since $\partial_{x}^{2} h=0$.
In case 6), the surface $\{h=1\}$ is a union of the graph

$$
\left\{x=\frac{1-y^{3}}{y^{2}-z^{2}}, y^{2}-z^{2} \neq 0\right\}
$$

and the two vertical lines $\{y=|z|=1\}$. Since $\operatorname{det} \partial^{2} h=8\left(h-y\left(y^{2}+3 z^{2}\right)\right)$ and $\partial_{x}^{2} h=0$, we see that the (nonempty) subset of $\{h=1\}$ on which $-\partial^{2} h$ induces a Riemannian metric on the surface is precisely

$$
\left\{y\left(y^{2}+3 z^{2}\right)<1, x=\frac{1-y^{3}}{y^{2}-z^{2}}, y^{2}-z^{2} \neq 0\right\}
$$

In case 7 ), $\{h=1\}$ is a graph

$$
y=\sqrt[3]{1-x z^{2}}
$$

over the ( $x, z$ )-plane and $g$ is Riemannian precisely on the (nonempty) subset

$$
x z^{2}>1
$$

This follows from $\operatorname{det} \partial^{2} h=-24 y z^{2}$, since $\partial_{x}^{2} h=0$.

## 4 Classification of complete surfaces

In this section we study the completeness of the maximal connected projective special real surfaces associated with the hyperbolic cubic polynomials $h$ described in Proposition 4. These are precisely the connected components of the hypersurface

$$
\mathcal{H}(h):=\left\{x \in \mathbb{R}^{3} \mid h(x)=1 \quad \text { and } \quad g_{x}>0\right\},
$$

where we recall that $g_{x}$ is the restriction of the symmetric bilinear form $-\partial^{2} h(x)$ to the plane ker $d h(x)$.

In the next theorem we determine all the complete and incomplete components of $\mathcal{H}(h)$ for the polynomials 1)-7) of Proposition 4, up to equivalence. The five cases which admit a complete component are listed first. They correspond to the surfaces a)-e) in Theorem 1. The case of Weierstraß polynomials with nonzero discriminant will be analysed in the next subsection. It will lead to the family of surfaces f) in Theorem 1 .

## Theorem 2

1) For $h=x y z, \mathcal{H}(h)=\{h=1\}$ has four isomorphic components, each of which is complete.
2) For $h=x\left(x y-z^{2}\right), \mathcal{H}(h)=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, x>0\right\}$ is connected and complete.
3) For $h=x\left(y z+x^{2}\right)$, $\mathcal{H}(h)=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, x<\frac{1}{\sqrt[3]{4}}\right\}$ has four components; a pair of isomorphic complete components and a pair of isomorphic incomplete components.
4) For $h=z\left(x^{2}+y^{2}-z^{2}\right), \mathcal{H}(h)=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, z<0\right\}$ is connected and complete.
5) For $h=x\left(y^{2}-z^{2}\right)+y^{3}$,

$$
\mathcal{H}(h)=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, y^{2}-z^{2} \neq 0, y\left(y^{2}+3 z^{2}\right)<1\right\}
$$

has four components; a complete component, a pair of isomorphic incomplete components and a further incomplete component.
6) For $h=x\left(y^{2}+z^{2}\right)+y^{3}$, $\mathcal{H}(h)=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, y\left(y^{2}-3 z^{2}\right)>1\right\}$ has three components; a pair of isomorphic incomplete components and a further incomplete component.
7) For $h=x z^{2}+y^{3}, \mathcal{H}(h)=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, y<0\right\}$ has two components. They are isomorphic and incomplete.

Proof: 1) The group $\mathbb{Z}_{2}^{2}$ acts by $(x, y, z) \mapsto\left(\epsilon_{1} x, \epsilon_{2} y, \epsilon_{1} \epsilon_{2} z\right), \epsilon_{1}, \epsilon_{2} \in\{ \pm 1\}$, on the level set $\{h=1\}$ permuting its four components. Therefore, the statement follows from the fact [HM that the tensor field $g$ is positive definite and complete on the component $\left\{(x, y, z) \in \mathbb{R}^{3} \mid x y z=1, x>0, y>0\right\}$.
2) The description of $\mathcal{H}(h)$ follows from $\operatorname{det} \partial^{2} h=8 x^{3}$ and $\partial_{y}^{2} h=0$, the completeness from CHM .
3) The description of $\mathcal{H}(h)$ follows from $\operatorname{det} \partial^{2} h=2\left(h-4 x^{3}\right)$ and $\partial_{y}^{2} h=0$. Notice that $\mathcal{H}(h)$ is a graph over the union of the following four domains in the $(x, y)$-plane: $\{x<0, y>0\},\{x<0, y<0\},\left\{0<x<\frac{1}{\sqrt[3]{4}}, y>0\right\},\left\{0<x<\frac{1}{\sqrt[3]{4}}, y<0\right\}$. The corresponding components of $\mathcal{H}(h)$ are related by the involution $(x, y, z) \mapsto(x,-y,-z)$. So up to isomorphism, it suffices to consider the two components

$$
\begin{array}{r}
\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, x<0, y>0\right\} \\
\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1,0<x<\frac{1}{\sqrt[3]{4}}, y>0\right\}
\end{array}
$$

The first one is complete by [CHM] and the second one is incomplete. This follows from the fact that the second component has nonempty boundary. The boundary is given by the curve

$$
\left\{\left.\left(\frac{1}{4^{1 / 3}}, y, \frac{3}{4^{2 / 3} y}\right) \right\rvert\, y>0\right\}
$$

4) The description of $\mathcal{H}=\mathcal{H}(h)$ was obtained in the proof of Proposition 4. In order to prove the completeness let us first remark that $\mathcal{H}(h)$ is a surface of revolution. More precisely, it is the graph of the function

$$
(x, y) \mapsto z=\varphi(\rho)
$$

where $\rho=r^{2}=x^{2}+y^{2}$ and

$$
\varphi:[0, \infty) \rightarrow(-\infty,-1]
$$

is the inverse of the strictly decreasing function

$$
f:(-\infty,-1] \rightarrow[0, \infty), \quad z \mapsto \rho=f(z)=\frac{1}{z}+z^{2}
$$

Let us first calculate the metric $g=-\left.\partial^{2} h\right|_{\mathcal{H}}$ in the coordinates $(x, y)$. Using that $z=\varphi(\rho)$, we obtain
$\frac{1}{2} g=-z\left(d x^{2}+d y^{2}\right)+3 z d z^{2}-2(x d x+y d y) d z=-\varphi(\rho)\left(d x^{2}+d y^{2}\right)+\varphi^{\prime}(\rho)\left(3 \varphi(\rho) \varphi^{\prime}(\rho)-1\right) d \rho^{2}$.
Rewriting $d x^{2}+d y^{2}=d r^{2}+r^{2} d s^{2}=\frac{1}{4 \rho} d \rho^{2}+\rho d s^{2}$ in polar coordinates $(r, s)$ in the $(x, y)$-plane we arrive at

$$
\begin{equation*}
\left.g\right|_{\{\rho>0\}}=2 f_{1}(\rho) d \rho^{2}+2 f_{2}(\rho) d s^{2}, \tag{4.1}
\end{equation*}
$$

where

$$
\begin{aligned}
f_{1}(\rho) & =-\frac{1}{4 \rho} \varphi(\rho)+\varphi^{\prime}(\rho)\left(3 \varphi(\rho) \varphi^{\prime}(\rho)-1\right) \\
f_{2}(\rho) & =-\varphi(\rho) \rho
\end{aligned}
$$

The metric (4.1) is of the type considered in Section 1 of [CHM] (cf. Lemma 5 below). Therefore, for all $a>0$, the completeness of $\mathcal{H}$ is equivalent to

$$
\begin{equation*}
\int_{a}^{\infty} \sqrt{f_{1}(\rho)} d \rho=\infty \tag{4.2}
\end{equation*}
$$

A straightforward calculation shows the following asymptotics when $\rho \rightarrow \infty$ :

$$
f_{1}(\rho)=\frac{3}{4 \rho^{2}}+O\left(\rho^{-7 / 2}\right)
$$

which implies (4.2).
5) The description of $\mathcal{H}(h)$ was obtained in the proof of Proposition 4. The surface is a graph over the union of the following four domains in the $(y, z)$-plane:

$$
\{y<0,|z|<|y|\},\{0<y<1,|z|<\min (y, f(y))\},\left\{\epsilon z>0,|y|<|z|, y<f^{-1}(|z|)\right\},
$$

where $\epsilon= \pm 1, f:(0,1) \xrightarrow{\sim}(0, \infty)$ is the strictly decreasing function $f(y)=\frac{1}{\sqrt{3}}\left(\frac{1}{y}-y^{2}\right)^{1 / 2}$ and $f^{-1}:(0, \infty) \xrightarrow{\sim}(0,1)$ denotes its inverse. The involution $(x, y, z) \mapsto(x, y,-z)$ acts on $\mathcal{H}(h)$ preserving the first two components and interchanging the last two. The last three components are incomplete as they have a nonempty boundary. The boundary of the second component is

$$
\left\{(x, y, z) \in \mathbb{R}^{3}\left|y_{0}<y \leq 1,|z|=f(y), x=\frac{1-y^{3}}{y^{2}-z^{2}}\right\}\right.
$$

where $y_{0}$ is the unique fixed point of $f$. The boundary of the third one $(\epsilon=1)$ is

$$
\left\{(x, y, z) \in \mathbb{R}^{3} \mid 0<y<y_{0}, z=f(y), x=\frac{1-y^{3}}{y^{2}-z^{2}}\right\}
$$

Now we show that the first component, namely

$$
\mathcal{H}:=\left\{(x, y, z) \in \mathbb{R}^{3}\left|y<0,|z|<|y|, x=\frac{1-y^{3}}{y^{2}-z^{2}}\right\}\right.
$$

is complete. The metric $g$ is given by

$$
\frac{1}{2} g=-(x+3 y) d y^{2}+x d z^{2}-2 d x(y d y-z d z)
$$

where $(y, z)$ is restricted to the domain $\{y<0,|z|<|y|\}$ and $x=\frac{1-y^{3}}{y^{2}-z^{2}}$. Using the function $s=y^{2}-z^{2}>0$, we rewrite this as

$$
\frac{1}{2} g=-3 y d y^{2}-x\left(d y^{2}-d z^{2}\right)-d x d s
$$

Eliminating $x=\frac{1-y^{3}}{s}$ and

$$
d x=-\frac{3 y^{2} d y}{s}-\frac{\left(1-y^{3}\right) d s}{s^{2}}
$$

we get

$$
\frac{1}{2} g=-3 y d y^{2}-\left(1-y^{3}\right) \frac{d y^{2}-d z^{2}}{s}+3 y^{2} d y d \sigma+\left(1-y^{3}\right) d \sigma^{2}
$$

where $\sigma=\ln s$. Using the coordinates

$$
t_{ \pm}:=\ln (|y| \pm z),
$$

such that

$$
\sigma=t_{+}+t_{-}
$$

this is

$$
\frac{1}{2} g=-3 y d y^{2}-\left(1-y^{3}\right) d t_{+} d t_{-}+3 y^{2} d y\left(d t_{+}+d t_{-}\right)+\left(1-y^{3}\right)\left(d t_{+}+d t_{-}\right)^{2}
$$

Notice that the coordinates $\left(t_{+}, t_{-}\right)$define a diffeomorphism $\mathcal{H} \cong \mathbb{R}^{2}$. Eliminating

$$
y=-\frac{e^{t_{+}}+e^{t_{-}}}{2}
$$

we get

$$
\begin{aligned}
\frac{1}{2} g & =\left(1+\frac{1}{8}\left(e^{3 t_{+}}+e^{3 t_{-}}\right)\right)\left(d t_{+}^{2}+d t_{-}^{2}\right)+\left(1-\frac{1}{4}\left(e^{3 t_{+}}+e^{3 t_{-}}\right)\right) d t_{+} d t_{-} \\
& \left.=d t_{+}^{2}+d t_{-}^{2}+d t_{+} d t_{-}+\frac{1}{8}\left(e^{3 t_{+}}+e^{3 t_{-}}\right)\right)\left(d t_{+}-d t_{-}\right)^{2} \\
& \geq d t_{+}^{2}+d t_{-}^{2}+d t_{+} d t_{-} \geq \frac{1}{2}\left(d t_{+}^{2}+d t_{-}^{2}\right)
\end{aligned}
$$

So $g$ is bounded from below by the complete metric $d t_{+}^{2}+d t_{-}^{2}$ and, hence, is itself complete. 6) The description of $\mathcal{H}(h)$ follows from $\operatorname{det} \partial^{2} h=8\left(y\left(y^{2}-3 z^{2}\right)-h\right)$ and $\partial_{x}^{2} h=0 . \mathcal{H}(h)$ is
a graph $x=\frac{1-y^{3}}{y^{2}+z^{2}}$ over the union of the following three domains in the $(y, z)$-plane: $\{y<$ $\left.0,3 z^{2}>y^{2}-\frac{1}{y}, z>0\right\},\left\{y<0,3 z^{2}>y^{2}-\frac{1}{y}, z<0\right\},\left\{y>0,3 z^{2}<y^{2}-\frac{1}{y}\right\}$. The first two correspond to components of $\mathcal{H}(h)$ that are related by the involution $(x, y, z) \mapsto(x, y,-z)$. $(y, z)=(-1, \sqrt{2 / 3})$ and $(y, z)=(1,0)$ are points in the boundary of the first and third domain respectively. Since $|x|=\left|\frac{1-y^{3}}{y^{2}+z^{2}}\right|<\infty$ for $(y, z) \neq(0,0)$, the corresponding components of $\mathcal{H}(h)$ have nonempty boundary. Hence, all three components of $\mathcal{H}(h)$ are incomplete.
7) The description of $\mathcal{H}(h)$ follows from $\operatorname{det} \partial^{2} h=-24 y z^{2}$ and $\partial_{x}^{2} h=0$. $\mathcal{H}(h)$ is a graph $y=\sqrt[3]{1-x z^{2}}$ over the union of the following two domains in the $(x, z)$-plane: $\left\{x z^{2}>1, z>0\right\},\left\{x z^{2}>1, z<0\right\}$. The corresponding components of $\mathcal{H}(h)$ are related by the involution $(x, y, z) \mapsto(x, y,-z) .(x, y, z)=(1,0,1)$ is a point in the boundary of the first component. Hence both components of $\mathcal{H}(h)$ are incomplete.

Proof: (of Theorem 11) In Section 2, we classified all homogeneous cubic polynomials, up to linear equivalence. They fall into three classes: reducible polynomials, irreducible polynomials $h$ such that $\{h=0\} \subset \mathbb{R} P^{2}$ is a singular curve and irreducible polynomials such that the corresponding cubic curve in $\mathbb{R} P^{2}$ is smooth. For the first two classes, all hyperbolic polynomials, i.e. all polynomials that define a projective special real surface are classified in Proposition 4. Theorem 2 then classifies all complete projective special real surfaces defined by the polynomials given in Proposition 4. This gives the surfaces a)-e). The polynomials in the third class are all equivalent to Weierstraß polynomials of nonzero discriminant (Proposition 3). They are studied in the next subsection. According to Corollary 2, the surfaces in the one-parameter family f) are, up to equivalence, the only closed projective special real surfaces defined by Weierstraß polynomials of nonzero discriminant. Proposition 8 in combination with Lemma 4 shows that all surfaces in the family f) are complete.

Remark 3 More precisely, we have classified all projective special real surfaces that are closed in $\mathbb{R}^{3}$ and we have shown that all closed projective special real surfaces are complete.

Together with the classification of all closed and of all complete projective special real curves in (CHM, we obtain the following corollary:

Corollary $1 \quad A$ projective special real manifold $\mathcal{H} \subset \mathbb{R}^{n+1}$ of dimension $n \leq 2$ is complete if and only if $\mathcal{H}$ is a closed subset of $\mathbb{R}^{n+1}$.

Open problem: Does the statement of Corollary $\mathbb{1}$ hold in all dimensions?

### 4.1 Complete surfaces defined by Weierstraß polynomials with nonzero discriminant

In this subsection, we will study Weierstraß polynomials

$$
h^{(a, b)}:=y^{2} z-4 x^{3}+a x z^{2}+b z^{3}
$$

with $a^{3}-27 b^{2} \neq 0$ and show that for positive discriminant, they define a one-parameter family of complete projective special real surfaces and that for negative discriminant, all connected components of $\left\{x \in \mathbb{R} \mid h(x)=1, g_{x}>0\right\}$ are incomplete.

First, we study the connected components of $\{h=1\}$. In the case of positive discriminant, we can restrict ourselves to Weierstraß cubics with $a=3$, according to the following lemma.

Lemma 1 Let $h^{(a, b)}=y^{2} z-4 x^{3}+a x z^{2}+b z^{3}$ be a Weierstraß cubic polynomial with positive discriminant $a^{3}-27 b^{2}>0$. Then $h^{(a, b)}$ is linearly equivalent to $h^{(3, \widetilde{b})}$ with $-1<$ $\widetilde{b}<1$.

Proof: $a^{3}-27 b^{2}>0$ implies $a>0$. Defining $\widetilde{x}:=x, \widetilde{y}:=\left(\frac{3}{a}\right)^{\frac{1}{4}} y, \widetilde{z}:=\sqrt{\frac{a}{3}} z$ and $\widetilde{b}:=\left(\frac{3}{a}\right)^{\frac{3}{2}} b$, we obtain $h^{(a, b)}(x, y, z)=\tilde{y}^{2} \tilde{z}-4 \tilde{x}^{3}+3 \tilde{x} \tilde{z}^{2}+\tilde{b} \tilde{z}^{3}=h^{(3, \tilde{b})}(\widetilde{x}, \widetilde{y}, \widetilde{z})$ and $a^{3}-27 b^{2}=$ $a^{3}\left(1-\widetilde{b}^{2}\right)>0$ if and only if $-1<\widetilde{b}<1$.

Proposition 5 Let $h=y^{2} z-4 x^{3}+a x z^{2}+b z^{3}$ with $a, b \in \mathbb{R}$ such that the discriminant $a^{3}-27 b^{2}$ is nonzero. Then $\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1\right\}$ has
a) one connected component for $a^{3}-27 b^{2}<0$ and
b) two connected components for $a^{3}-27 b^{2}>0$. For $a=3$ (and hence $-1<b<1$ ), one of them is given by $\mathcal{H}^{(3, b)}:=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, z<0,2 x>z\right\}$.

Proof: Consider the diffeomorphism

$$
\Phi:\{h \neq 0\} \cap\{z=1\} \rightarrow\{h=1\} \cap\{z \neq 0\}, \quad(x, y, 1) \mapsto \frac{1}{\sqrt[3]{h(x, y, 1)}}(x, y, 1)
$$

with inverse $\Phi^{-1}(\widetilde{x}, \widetilde{y}, \widetilde{z})=\left(\frac{\widetilde{x}}{\widetilde{z}}, \frac{\widetilde{y}}{\widetilde{z}}, 1\right)$. The restriction of $\Phi$ gives diffeomorphisms

$$
\begin{aligned}
& V_{+}:=\{h>0\} \cap\{z=1\} \stackrel{\approx}{\approx}\{h=1\} \cap\{z>0\}=: \mathcal{H}_{+}, \\
& V_{-}:=\{h<0\} \cap\{z=1\} \stackrel{\approx}{\longrightarrow}\{h=1\} \cap\{z<0\}=: \mathcal{H}_{-} .
\end{aligned}
$$

The discriminant $a^{3}-27 b^{2}$ determines the number of real roots of

$$
f(x):=y^{2}-h(x, y, 1)=4 x^{3}-a x-b .
$$

a) Case $a^{3}-27 b^{2}<0$ : For negative discriminant, $f(x)=4 x^{3}-a x-b$ has exactly one real root that we denote by $x_{1}$. Then $V_{+}=\left\{(x, y, 1) \mid x \in \mathbb{R}, y^{2}>f(x)\right\}$ and $V_{-}=$ $\left\{(x, y, 1) \mid x>x_{1}, y^{2}<f(x)\right\}$ are connected. Hence, $\mathcal{H}_{+}=\Phi\left(V_{+}\right)$and $\mathcal{H}_{-}=\Phi\left(V_{-}\right)$ are connected as well. With $\mathcal{H}_{0}:=\{h=1\} \cap\{z=0\}=\left\{\left.\left(-\frac{1}{\sqrt[3]{4}}, y, 0\right) \right\rvert\, y \in \mathbb{R}\right\}$, we have $\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1\right\}=\mathcal{H}_{+} \cup \mathcal{H}_{0} \cup \mathcal{H}_{-}$. For $x<x_{1}$, we have

$$
\mathcal{H}_{+} \ni \Phi(x, 0,1)=\frac{1}{\sqrt[3]{-4 x^{3}+a x+b}}(x, 0,1) \xrightarrow{x \rightarrow-\infty}\left(-\frac{1}{\sqrt[3]{4}}, 0,0\right) \in \mathcal{H}_{0}
$$

and for $x>x_{1}$,

$$
\mathcal{H}_{-} \ni \Phi(x, 0,1)=\frac{1}{\sqrt[3]{-4 x^{3}+a x+b}}(x, 0,1) \xrightarrow{x \rightarrow+\infty}\left(-\frac{1}{\sqrt[3]{4}}, 0,0\right) \in \mathcal{H}_{0} .
$$

Thus, $\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1\right\}$ is connected.
b) Case $a^{3}-27 b^{2}>0$ : Without loss of generality, we set $a=3$ (see Lemma (1). Then $-1<b<1$. For positive discriminant, $f(x)=4 x^{3}-3 x-b$ has three real roots that we denote by $x_{1}, x_{2}, x_{3}$ such that $x_{2}<x_{3}<x_{1}$. Hence, $f(x)>0$ for $x \in\left(x_{2}, x_{3}\right) \cup\left(x_{1}, \infty\right)$. As before, $V_{+}=\left\{(x, y, 1) \mid x \in \mathbb{R}, y^{2}>f(x)\right\}$ is connected and diffeomorphic to $\mathcal{H}_{+} . V_{-}$has two connected components given by

$$
V_{-b}:=\left\{(x, y, 1) \mid x_{2}<x<x_{3}, y^{2}<f(x)\right\} \text { and } V_{-u}:=\left\{(x, y, 1) \mid x>x_{1}, y^{2}<f(x)\right\} .
$$

$$
\mathcal{H}_{-b}:=\Phi\left(V_{-b}\right) \approx V_{-b} \text { and } \mathcal{H}_{-u}:=\Phi\left(V_{-u}\right) \approx V_{-u} \text { are connected and with } \mathcal{H}_{0}:=
$$ $\{h=1\} \cap\{z=0\}=\left\{\left.\left(-\frac{1}{\sqrt[3]{4}}, y, 0\right) \right\rvert\, y \in \mathbb{R}\right\}$, we have $\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1\right\}=$ $\mathcal{H}_{+} \cup \mathcal{H}_{0} \cup \mathcal{H}_{-b} \cup \mathcal{H}_{-u}$. By the same reasoning as in the proof of $a$ ), we see that $\mathcal{H}_{+} \cup \mathcal{H}_{0} \cup \mathcal{H}_{-u}$ is connected.

Notice that the minimum of $f(x)$ is located at $x=\frac{1}{2}$, so $x_{3}<\frac{1}{2}<x_{1}$. Hence, we have $\mathcal{H}_{-b}=\Phi\left(V_{-b}\right) \subset\{z<0\} \cap\left\{\frac{x}{z}<\frac{1}{2}\right\}$ and $\mathcal{H}_{-u}=\Phi\left(V_{-u}\right) \subset\{z<0\} \cap\left\{\frac{x}{z}>\frac{1}{2}\right\}$. From $\overline{\{z<0\} \cap\{2 x>z\}} \cap \mathcal{H}_{0}=\emptyset$, it follows that $\overline{\mathcal{H}_{-b}} \cap\left(\mathcal{H}_{+} \cup \mathcal{H}_{0} \cup \mathcal{H}_{-u}\right)=\emptyset$. Thus, $\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1\right\}$ has two connected components, namely $\mathcal{H}_{+} \cup \mathcal{H}_{0} \cup \mathcal{H}_{-u}$ and $\mathcal{H}^{(3, b)}:=\mathcal{H}_{-b} \subset\{z<0\} \cap\{2 x>z\}$.

Now, we show that $h$ is hyperbolic for each point in the closed surface $\mathcal{H}^{(3, b)}=$ $\left\{(x, y, z) \in \mathbb{R}^{3} \mid h^{(3, b)}(x, y, z)=1, z<0,2 x>z\right\} \subset \mathbb{R}^{3}$ defined in Proposition 5 b$)$.

Proposition 6 Let $h=y^{2} z-4 x^{3}+3 x z^{2}+b z^{3}$ with $-1<b<1$ and let $\mathcal{H}^{(3, b)}=$ $\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, z<0,2 x>z\right\}$. Then $-\partial^{2} h(p)$ has Lorentzian signature for all $p \in \mathcal{H}^{(3, b)}$.

Proof: Let $x_{2}<x_{3}<x_{1}$ be the three distinct solutions of $4 x^{3}-3 x-b=0$ and let $d:=\operatorname{det} \partial^{2} h=-24\left(12 x z(x+b z)+3 z^{3}-4 x y^{2}\right)$. Let $(x, y, 1) \in V_{-b}:=\left\{(x, y, 1) \mid x_{2}<x<\right.$ $\left.x_{3}, y^{2}<4 x^{3}-3 x-b\right\}$. We show that $d(x, y, 1)<0$ :

Case $x=0:-\frac{d(0, y, 1)}{24}=3>0$.
Case $x<0:-\frac{d(x, y, 1)}{24}=12 x(x+b)+3-4 x y^{2}=12\left(x+\frac{b}{2}\right)^{2}+3\left(1-b^{2}\right)-4 x y^{2}>0$.
Case $x>0$ : We use $y^{2}<4 x^{3}-3 x-b$ :

$$
\begin{aligned}
-\frac{d(x, y, 1)}{24} & =12 x(x+b)+3-4 x y^{2}>12 x(x+b)+3-4 x\left(4 x^{3}-3 x-b\right) \\
& =-16 x^{4}+24 x^{2}+16 b x+3=: g(x)
\end{aligned}
$$

$g^{\prime}(x)=-16\left(4 x^{3}-3 x-b\right)$, so $g(x)$ has local maxima at $x_{2}<-\frac{1}{2}$ and $x_{1}>\frac{1}{2}$ and a local minimum at $x_{3}$. For $-1<b<1$, the quartic polynomial $g(x)$ has only two real root. ${ }^{1}$, which must lie in $\left(-\infty, x_{2}\right)$ and $\left(x_{1}, \infty\right)$. So $g\left(x_{3}\right)>0$ and it follows that $g(x)>0$ for $0<x<x_{3}$.
(Note that, depending on the value of $b$, some of these cases might be empty.)
We have $\mathcal{H}^{(3, b)}=\left\{\left.\frac{1}{\sqrt[3]{h(x, y, 1)}}(x, y, 1) \right\rvert\,(x, y, 1) \in V_{-b}\right\}$, where $\left.h\right|_{V_{-b}}<0$ (see the proof of Proposition 5,b). Since $d$ is homogeneous of degree three, $\left.d\right|_{V_{-b}}<0$ implies $\left.d\right|_{\mathcal{H}}>0$. Now $\left.\partial^{2} h\right|_{\mathcal{H}}$ can have signature $(+,+,+)$ or $(+,-,-)$. Since $\partial^{2} h\left(\partial_{y}, \partial_{y}\right)=2 z<0$, the signature of $\left.\partial^{2} h\right|_{\mathcal{H}}$ is $(+,-,-)$.

Lemma 2 For $h^{(a, b)}=y^{2} z-4 x^{3}+a x z^{2}+b z^{3},-\partial^{2} h^{(a, b)}(x, y, z)$ is Lorentzian iff

$$
(x, y, z) \in \mathcal{U}_{\text {Lor. }}:=\left\{\operatorname{det} \partial^{2} h>0, x>0\right\} \cup\left\{\operatorname{det} \partial^{2} h>0, z<0\right\} .
$$

Proof: For $h=y^{2} z-4 x^{3}+a x z^{2}+b z^{3}, \partial^{2} h$ is positive definite iff $h_{x x}=-24 x>0$, $\operatorname{det}\left(\begin{array}{ll}h_{x x} & h_{x y} \\ h_{y x} & h_{y y}\end{array}\right)=-48 x z>0$ and $\operatorname{det} \partial^{2} h=-8\left(12 x z(a x+3 b z)+a^{2} z^{3}-12 x y^{2}\right)>0$, i.e.

$$
\left\{(x, y, z) \in \mathbb{R}^{3} \mid \partial^{2} h(x, y, z)>0\right\}=\left\{(x, y, z) \in \mathbb{R}^{3} \mid x<0, z>0, \operatorname{det} \partial^{2} h>0\right\}=: \mathcal{U}_{p o s .}
$$

Hence, $-\partial^{2} h(x, y, z)$ is Lorentzian iff $(x, y, z) \in\left\{(x, y, z) \in \mathbb{R}^{3} \mid \operatorname{det} \partial^{2} h>0\right\} \backslash U_{\text {pos. }}=\left\{\operatorname{det} \partial^{2} h>0, x \geq 0\right\} \cup\left\{\operatorname{det} \partial^{2} h>0, z \leq 0\right\}$.

We show that $\left\{\operatorname{det} \partial^{2} h>0, x=0, z \geq 0\right\} \cup\left\{\operatorname{det} \partial^{2} h>0, x \leq 0, z=0\right\}=\emptyset:$

$$
\begin{aligned}
& x=0, z \geq 0 \Rightarrow \operatorname{det} \partial^{2} h=-8 a^{2} z^{3} \leq 0 \\
& x \leq 0, z=0 \Rightarrow \operatorname{det} \partial^{2} h=96 x y^{2} \leq 0
\end{aligned}
$$

Using the above lemma, we show that except for $\mathcal{H}^{(3, b)}$, all connected components of $\left\{x \in \mathbb{R} \mid h^{(3, b)}(x)=1, g_{x}>0\right\}$ have nonempty boundary in $\mathbb{R}^{3}$.

[^0]
## Proposition 7 Let

a) $\mathcal{S}:=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1\right\}$ for $h=y^{2} z-4 x^{3}+a x z^{2}+b z^{3}$ with negative discriminant or
b) $\mathcal{S}:=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1\right\} \backslash \mathcal{H}^{(3, b)}$ for $h=y^{2} z-4 x^{3}+3 x z^{2}+b z^{3}$ with $-1<b<1$, where $\mathcal{H}^{(3, b)}=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, z<0,2 x>z\right\}$.

Then $\mathcal{S} \cap\left\{(x, y, z) \in \mathbb{R}^{3} \mid-\partial^{2} h(x, y, z)\right.$ Lorentzian $\}$ has no connected component that is closed in $\mathcal{S}$.

Proof: Let $\widetilde{\mathcal{H}}$ be a connected component of $\mathcal{S} \cap \mathcal{U}_{\text {Lor. }}$ (see lemma (2). $\quad\left(-\frac{1}{\sqrt[3]{4}}, 0,0\right) \in$ $\mathcal{S} \cap\left\{\operatorname{det} \partial^{2} h=0\right\}$ implies $\widetilde{\mathcal{H}} \neq \mathcal{S} . \mathcal{U}_{\text {Lor. }}=\left\{\operatorname{det} \partial^{2} h>0, x>0\right\} \cup\left\{\operatorname{det} \partial^{2} h>0, z<0\right\}$ is open in $\mathbb{R}^{3}$, so $\mathcal{S} \cap \mathcal{U}_{\text {Lor. }}$ and hence $\widetilde{\mathcal{H}}$ are open in $\mathcal{S}$. According to proposition 5 , $\mathcal{S}$ is connected. Since $\widetilde{\mathcal{H}} \subset \mathcal{S}$ is open, nonempty and $\neq \mathcal{S}$, it cannot be closed in $\mathcal{S}$.

In summary, we have proven the following

Corollary 2 Up to linear equivalence, the only closed (in $\mathbb{R}^{3}$ ) projective special real surfaces defined by Weierstraß cubic polynomials with nonzero discriminant are given by

$$
\mathcal{H}^{(3, b)}=\left\{(x, y, z) \in \mathbb{R}^{3} \mid y^{2} z-4 x^{3}+3 x z^{2}+b z^{3}=1, z<0,2 x>z\right\}
$$

with $-1<b<1$.

To prove the completeness of the projective special real metric defined on the closed component $\mathcal{H}^{(3, b)}$ given in Corollary 2, we will use the following three lemmata.

Lemma 3 For each $b \in(-1,1)$ there exists exactly one $R \in \mathbb{R}$, such that $h^{(3, b)}=$ $y^{2} z-4 x^{3}+3 x z^{2}+b z^{3}$ is equivalent to

$$
h(x, y, z):=y^{2} z-x^{3}+x z^{2}+R x^{2} z .
$$

Proof: It is straightforward to see that $h^{(3, b)}$ is equivalent to $h_{1}(x, y, z):=y^{2} z-x^{3}+$ $x z^{2}+\frac{2 b}{3^{\frac{3}{2}}} z^{3}$. To eliminate the $z^{3}$-part we make the ansatz $x=\widetilde{x}+c z$. We obtain

$$
h_{1}(\widetilde{x}+c z, y, z)=y^{2} z-\widetilde{x}^{3}+\left(1-3 c^{2}\right) \widetilde{x} z^{2}-3 c \widetilde{x}^{2} z+\left(-c^{3}+c+\frac{2 b}{3^{\frac{3}{2}}}\right) z^{3} .
$$

We need to analyse the solvability of $\left(-c^{3}+c+\frac{2 b}{3^{\frac{3}{2}}}\right)=0$. Therefore, we define $f(c):=$ $c^{3}-c$ and calculate its first derivative $f^{\prime}(c)=3 c^{2}-1 . f^{\prime}(c)$ vanishes if and only if $c=-\frac{1}{3^{\frac{1}{2}}}$
or $c=\frac{1}{3^{\frac{1}{2}}}$, and $f\left(-\frac{1}{3^{\frac{1}{2}}}\right)=\frac{2}{3^{\frac{3}{2}}}, \quad f\left(\frac{1}{3^{\frac{1}{2}}}\right)=-\frac{2}{3^{\frac{3}{2}}}$. Thus, for each $b \in(-1,1)$ there is exactly one $c_{b} \in\left(-\frac{1}{3^{\frac{1}{2}}}, \frac{1}{3^{\frac{1}{2}}}\right)$, such that $f\left(c_{b}\right)=\frac{2 b}{3^{\frac{3}{2}}}$. Choosing $c$ that way, we arrive at

$$
h_{1}(x, y, z)=y^{2} z-\widetilde{x}^{3}+\left(1-3 c^{2}\right) \widetilde{x} z^{2}-3 c \widetilde{x}^{2} z
$$

It follows from $|c|<\frac{1}{3^{\frac{1}{2}}}$ that $\left(1-3 c^{2}\right)>0$, regardless of the choice of the parameter $b \in(-1,1)$, and, hence, the transformation $z=\left(1-3 c^{2}\right)^{-\frac{1}{2}} \widetilde{z}$ does not switch signs. After the additional transformation $y=\left(1-3 c^{2}\right)^{\frac{1}{4}} \widetilde{y}$, $h_{1}$ reads

$$
h_{1}(x, y, z)=\widetilde{y}^{2} \widetilde{z}-\widetilde{x}^{3}+\widetilde{x} \widetilde{z}^{2}+\frac{-3 c}{\left(1-3 c^{2}\right)^{\frac{1}{2}}} \widetilde{x}^{2} \widetilde{z}
$$

One can easily verify that $R:\left(-\frac{1}{3^{\frac{1}{2}}}, \frac{1}{3^{\frac{1}{2}}}\right) \rightarrow \mathbb{R}, c \mapsto \frac{-3 c}{\left(1-3 c^{2}\right)^{\frac{1}{2}}}$ is a bijection.
In the following we will omit the tildes so that $x, y, z$ denote our new coordinates.

Lemma 4 The closed surface $\mathcal{H}^{(3, b)}=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h^{(3, b)}=1, z<0,2 x>z\right\}$ is linearly equivalent to

$$
\mathcal{H}:=\left\{(x, y, z) \in \mathbb{R}^{3} \mid h(x, y, z)=1, x>0, z<0\right\},
$$

where $h=y^{2} z-x^{3}+x z^{2}+R x^{2} z$ as in the above lemma.

Proof: After transforming $h^{(3, b)}$ into $h(x, y, z)=y^{2} z-x^{3}+x z^{2}+R x^{2} z$, the corresponding inequalities for the coordinates introduced in the proof of Lemma 3 read

$$
z<0, \quad x>\frac{1}{\sqrt{3}} \sqrt{\frac{1-\sqrt{3} c}{1+\sqrt{3} c}} z
$$

where $c$ is the parameter determined in the proof of Lemma 3, which satisfies $0 \leq$ $|c|<3^{-\frac{1}{2}}$. We have to show that $x>0$. Since $\mathcal{H}^{(3, b)}$ is connected, $\widetilde{\mathcal{H}}:=\{(x, y, z) \in$ $\left.\mathbb{R}^{3} \mid h(x, y, z)=1, z<0, x>\frac{1}{\sqrt{3}} \sqrt{\frac{1-\sqrt{3} c}{1+\sqrt{3} c}} z\right\}$ is connected as well. Hence, it suffices to show that $\widetilde{\mathcal{H}} \cap\{x=0\}=\emptyset$. To do so, we write $\mathcal{H}$ as a graph.

$$
\begin{align*}
& h(x, y, z)=1 \\
& \Leftrightarrow y^{2} z-x^{3}+x z^{2}+R x^{2} z=1 \\
& \Leftrightarrow z^{2}+\left(\frac{y^{2}+R x^{2}}{x}\right) z-\left(x^{2}+\frac{1}{x}\right)=0 \\
& \Leftrightarrow z(x, y):=z=-\frac{1}{2 x}\left(y^{2}+R x^{2}+\sqrt{\left(y^{2}+R x^{2}\right)^{2}+4 x^{4}+4 x}\right) . \tag{4.3}
\end{align*}
$$

The last equivalence holds since $z<0$.

Considering the limit $x \rightarrow 0$, we see that in the case $y \neq 0, \lim _{x \rightarrow 0, x>0} z(x, y)=-\infty$. In the case $y=0$, it is easy to verify that

$$
|z(x, 0)| \geq \frac{1}{2 x}\left(\sqrt{R^{2} x^{4}+4 x}-|R| x^{2}\right)=\frac{1}{2} \sqrt{R^{2} x^{2}+\frac{4}{x}}-\frac{1}{2}|R| x \geq 0 .
$$

Therefore, we have

$$
\lim _{x \rightarrow 0, x>0}|z(x, 0)|=\lim _{x \rightarrow 0, x>0} \sqrt{\frac{1}{x}}=\infty .
$$

Since $(\overline{\mathcal{H}} \backslash\{z=0\}) \cap\{x=0\}=\widetilde{\mathcal{H}} \cap\{x=0\}$, the above calculation shows that $\widetilde{\mathcal{H}} \cap\{x=0\}=\emptyset$. Hence, $\widetilde{\mathcal{H}}$ can be written as the disjoint union of $\mathcal{H}$ and $\{h(x, y, z)=$ $\left.1 \mid z<0,0>x>\frac{1}{\sqrt{3}} \sqrt{\frac{1-\sqrt{3} c}{1+\sqrt{3} c}} z\right\}$. This shows that $\mathcal{H}$ is a connected component of $\tilde{\mathcal{H}}$. Since $\widetilde{\mathcal{H}}$ is connected, the equality $\mathcal{H}=\widetilde{\mathcal{H}}$ holds true.

Lemma 5 Let $\left(M, g_{1}\right)$ be a complete Riemannian manifold and let $g_{2, p}$ be a family of complete Riemannian metrics on $\mathbb{R}$, depending smoothly on $p \in M$ such that $g_{2, p}=$ $G(p) d s^{2}$. Then $\left(M \times \mathbb{R}, g_{1}+g_{2, p}\right)$ is also a complete Riemannian manifold.

Proof: This is a special case of Theorem 2 in CHM.

Proposition 8 The surface $\mathcal{H}$ defined in Lemma 4 endowed with the metric $g_{\mathcal{H}}:=$ $-\left.\partial^{2} h\right|_{T \mathcal{H} \times T \mathcal{H}}$ is a complete Riemannian manifold for all $R \in \mathbb{R}$.

Proof: Computing the Hessian of $h$, we obtain

$$
-\partial^{2} h=(6 x-2 R z) d x^{2}-2 z d y d y-2 x d z d z-4(z+R x) d x d z-4 y d y d z
$$

It was shown in the proof of Lemma 2 that $\mathcal{H}$ admits the following parametrization:

$$
F: \mathbb{R}^{>0} \times \mathbb{R} \rightarrow \mathcal{H} \subset \mathbb{R}^{3},(x, y) \mapsto(x, y, z(x, y))
$$

where $z(x, y)$ is the function defined in equation (4.3). With the abbreviation $A:=$ $\left(y^{2}+R x^{2}\right)^{2}+4 x^{4}+4 x, g_{\mathcal{H}}$ reads

$$
\begin{aligned}
g_{\mathcal{H}} & =x^{-3}\left(A^{\frac{1}{2}}(y d x-x d y)^{2}+A^{-1}\left(( y d x - x d y ) ^ { 2 } \left(12 x^{4} y^{2}+6 x y^{2}+3 R^{2} x^{4} y^{2}+3 R x^{2} y^{4}\right.\right.\right. \\
& \left.+R^{3} x^{6}+4 R x^{6}+y^{6}\right)+6 x^{2}\left(\left(1+R^{2} x^{3}+4 x^{3}\right) d x^{2}+x y^{2} d y^{2}\right)+2 R x^{3}\left(y^{2} d x^{2}+x^{2} d y^{2}\right. \\
& \left.\left.\left.+(y d x+x d y)^{2}\right)\right)\right) .
\end{aligned}
$$

Now we change the coordinates via

$$
T: \mathbb{R}^{>0} \times \mathbb{R} \rightarrow \mathbb{R}^{>0} \times \mathbb{R},(s, t) \mapsto(s, s t)
$$

such that, in particular, $T^{*}(y d x-x d y)=-s^{2} d t$. In these coordinates, $g_{\mathcal{H}}$ has the following form:

$$
\begin{aligned}
g_{\mathcal{H}} & =(s A)^{-1}\left(\left(24 s^{3}+6+6 s^{3}\left(t^{2}+R\right)^{2}\right) d s^{2}\right. \\
& +12 s^{4} t\left(t^{2}+R\right) d s d t \\
& +\left(4 s^{8} R+s^{8} R^{3}+4 R s^{5}+12 s^{8} t^{2}+s^{8} t^{6}+12 s^{5} t^{2}+3 R^{2} s^{8} t^{2}+3 R s^{8} t^{4}\right. \\
& \left.\left.+\left(s^{6} R^{2}+2 s^{6} t^{2} R+s^{6} t^{4}+4 s^{6}+4 s^{3}\right) \sqrt{s^{4}\left(t^{2}+R\right)^{2}+4 s^{4}+4 s}\right) d t^{2}\right)
\end{aligned}
$$

where $A=s^{4}\left(t^{2}+R\right)^{2}+4 s^{4}+4 s$ is the same function as above in the new coordinates $s$ and $t$. To show that $g_{\mathcal{H}}$ is complete, we start with rewriting it and make some estimates:

$$
\begin{aligned}
g_{\mathcal{H}} & =(s A)^{-1}\left(\left(24 s^{3}+6+\frac{3}{2} s^{3}\left(t^{2}+R\right)^{2}\right) d s^{2}\right. \\
& +\left(4 s^{8} R+s^{8} R^{3}+4 R s^{5}+12 s^{8} t^{2}+s^{8} t^{6}+4 s^{5} t^{2}+3 R^{2} s^{8} t^{2}+3 R s^{8} t^{4}\right. \\
& \left.+\left(s^{6} R^{2}+2 s^{6} t^{2} R+s^{6} t^{4}+4 s^{6}+4 s^{3}\right) \sqrt{s^{4}\left(t^{2}+R\right)^{2}+4 s^{4}+4 s}\right) d t^{2} \\
& +\underbrace{\left.\frac{9}{2} s^{3}\left(t^{2}+R\right)^{2} d s^{2}+12 s^{4} t\left(t^{2}+R\right) d s d t+8 s^{5} t^{2} d t^{2}\right)}_{\left(\frac{3}{\sqrt{2}} s^{\frac{3}{2}}\left(t^{2}+R\right) d s+\sqrt{8} s^{\frac{5}{2}} t d t\right)^{2} \geq 0} \\
& \geq(s A)^{-1}\left(\left(4 s^{3}+4+s^{3}\left(t^{2}+R\right)^{2}\right) d s^{2}\right. \\
& +\left(4 s^{8} R+s^{8} R^{3}+4 R s^{5}+4 s^{8} t^{2}+s^{8} t^{6}+4 s^{5} t^{2}+3 R^{2} s^{8} t^{2}+3 R s^{8} t^{4}\right. \\
& \left.\left.+\left(s^{6} R^{2}+2 s^{6} t^{2} R+s^{6} t^{4}+4 s^{6}+4 s^{3}\right) \sqrt{s^{4}\left(t^{2}+R\right)^{2}+4 s^{4}+4 s}\right) d t^{2}\right) \\
& =\frac{1}{s^{2}} d s^{2}+(s A)^{-1} s^{2} A\left(s^{2} R+s^{2} t^{2}+\sqrt{s^{4}\left(t^{2}+R\right)^{2}+4 s^{4}+4 s}\right) d t^{2} \\
& \geq \frac{1}{s^{2}} d s^{2}+s\left(s^{2} R+s^{2} t^{2}+\sqrt{s^{4}\left(t^{2}+R\right)^{2}+s^{4}}\right) d t^{2} \\
& =\frac{1}{s^{2}} d s^{2}+s^{3}\left(t^{2}+R^{2}+\sqrt{\left(t^{2}+R\right)^{2}+1}\right) d t^{2} .
\end{aligned}
$$

Solving the ODE

$$
\begin{equation*}
\mu^{\prime}=\sqrt{t^{2}+R+\sqrt{\left(t^{2}+R\right)^{2}+1}} \tag{4.4}
\end{equation*}
$$

we obtain a (strictly increasing) diffeomorphism $\mu: \mathbb{R} \rightarrow \mathbb{R}, t \mapsto \mu(t)$, such that $d \mu^{2}=$ $\left(t^{2}+R+\sqrt{\left(t^{2}+R\right)^{2}+1}\right) d t^{2}$. In fact, the right-hand side of (4.4) is bounded from below by a positive constant. Now we can conclude the proof using Lemma 5, which shows that the metric $\frac{1}{s^{2}} d s^{2}+s^{3}\left(t^{2}+R^{2}+\sqrt{\left(t^{2}+R\right)^{2}+1}\right) d t^{2}=d \sigma^{2}+e^{3 \sigma} d \mu^{2}$ is complete, where $\sigma=\ln s$.

## 5 Curvature formulas for the generalized supergravity r-map

We generalize the definition of projective special real manifolds in section 1 to hypersurfaces $\mathcal{H} \subset \mathbb{R}^{n+1}$ defined as the level set of an arbitrary homogeneous function $h$ and then define the generalized supergravity r-map, which assigns to each such $n$-dimensional real manifold a Kähler manifold of dimension $2 m:=2 n+2$ (see [CHM]). Then we calculate the Riemann, Ricci and scalar curvature of manifolds in the image of the generalized supergravity r-map and express them in terms of $h$ and its derivatives.

Let $U \subset \mathbb{R}^{n+1}$ be an $\mathbb{R}^{>0}$-invariant domain and let $h: U \rightarrow \mathbb{R}^{>0}$ be a smooth function which is homogeneous of degree $\mathscr{}^{2} D \in \mathbb{R}^{>0} \backslash\{1\}$. Then $\mathcal{H}:=\{x \in U \mid h(x)=1\} \subset U$ is a smooth hypersurface and we will assume that $-\partial^{2} h$ induces a Riemannian metric $g_{\mathcal{H}}=-\left.\partial^{2} h\right|_{T \mathcal{H} \times T \mathcal{H}}$ on $\mathcal{H}$.

We consider $M:=\mathbb{R}^{n+1}+i U \subset \mathbb{C}^{n+1}$, endowed with the standard complex structure and the standard holomorphic coordinates $z^{1}, \ldots, z^{n+1}$ induced from $\mathbb{C}^{n+1}$. We define $x^{\mu}:=\operatorname{Im} z^{\mu}$ and $y^{\mu}:=\operatorname{Re} z^{\mu}$, i.e. $z=\left(z^{\mu}\right)_{\mu=1, \ldots, n+1}=y+i x$ with $x=\left(x^{\mu}\right) \in U$ and $y=\left(y^{\mu}\right) \in \mathbb{R}^{n+1}$. We define a positive definite Kähler metrid ${ }^{3} g_{M}$ on $M$ with Kähler potential $K(z, \bar{z})=-\log h(x)$ :

$$
\begin{equation*}
g_{M}=2 g_{\mu \bar{\nu}} d z^{\mu} d \bar{z}^{\nu}, g_{\mu \bar{\nu}}:=\frac{\partial^{2} K}{\partial z^{\mu} \partial \bar{z}^{\nu}}=-\frac{h_{\mu \nu}(x)}{4 h(x)}+\frac{h_{\mu}(x) h_{\nu}(x)}{4 h^{2}(x)} . \tag{5.1}
\end{equation*}
$$

Here, we use the notation $h_{\mu}(x):=\frac{\partial h(x)}{\partial x^{\mu}}, h_{\mu \nu}(x):=\frac{\partial^{2} h(x)}{\partial x^{\mu} \partial x^{\nu}}, \ldots$.

Definition 2 We call the correspondence $\left(\mathcal{H}, g_{\mathcal{H}}\right) \mapsto\left(M, g_{M}\right)$ the generalized supergravity r-map. The restriction to polynomial functions $h$ of degree $D=3$ is called the supergravity r-map. Manifolds in the image of the supergravity r-map are called projective very special Kähler.

Note that the Kähler manifolds in the image of the generalized supergravity r-map in general only fall into the class of projective special Kähler manifolds (see e.g. [CHM]) if $h$ is a polynomial of degree $D=3$.

Using the fact that $h$ is a homogeneous function of degree $D$, i.e. $\sum_{\mu} h_{\mu}(x) x^{\mu}=$ $D \cdot h(x), \sum_{\nu} h_{\mu \nu}(x) x^{\nu}=(D-1) \cdot h_{\mu}(x), \ldots$, one can check that the coefficients of the

[^1]inverse metric $g_{M}^{-1}$ are given by 4
\[

$$
\begin{equation*}
g^{\bar{\nu} \lambda}=-4 h(x) h^{\nu \lambda}(x)+\frac{4}{D-1} x^{\nu} x^{\lambda} \tag{5.2}
\end{equation*}
$$

\]

where $h^{\mu \nu}$ denote the coefficients of the matrix $\left(h_{\mu \nu}\right)^{-1}$.

Theorem 3 Let $M$ be a 2m-dimensional manifold in the image of the generalized supergravity r-map described by a homogeneous function $h$ of degree $D \in \mathbb{R}^{>0} \backslash\{1\}$. Then the Riemann, Ricci and scalar curvature 5 in the holomorphic coordinates $\left(z^{\mu}\right)=\left(y^{\mu}+i x^{\mu}\right)$ defined above are given by

$$
\begin{gather*}
R_{\sigma \mu \bar{\nu}}^{\rho}=-\frac{1}{4 h^{2}}\left[-h^{2} h_{\sigma \mu \nu}^{\rho}+\frac{1}{D-1} x^{\rho}\left(h h_{\sigma \mu \nu}-h_{\mu \sigma} h_{\nu}\right)+h_{\mu} h_{\nu} \delta_{\sigma}^{\rho}+h_{\sigma} h_{\nu} \delta_{\mu}^{\rho}\right. \\
\left.-h\left(h_{\sigma \nu} \delta_{\mu}^{\rho}+h_{\mu \nu} \delta_{\sigma}^{\rho}-\frac{1}{D-1} h_{\mu \sigma} \delta_{\nu}^{\rho}\right)-h^{2} h^{\rho}{ }_{\nu \beta} h_{\sigma \mu}^{\beta}\right]  \tag{5.3}\\
R i c_{\mu \bar{\nu}}=-m g_{\mu \bar{\nu}}+\frac{1}{4} h_{\mu}^{\alpha \beta} h_{\alpha \beta \nu}+\frac{1}{4} h_{\rho \mu \nu}^{\rho}  \tag{5.4}\\
\text { scal }=-m^{2}+\frac{D-2}{D-1} m+h h_{\alpha \beta \gamma} h^{\alpha \beta \gamma}+h h^{\mu \nu}{ }_{\mu \nu} \tag{5.5}
\end{gather*}
$$

where the argument of $h$ and its derivatives is always $x$ and where we use the Lorentzian metric $-\partial^{2} h$ to raise and lower indices. Sums over repeated indices are implied via the Einstein summation convention.

Proof: For Kähler manifolds, the only non-vanishing Christoffel symbols are (see e.g. M, section 12.2 , or $[\mathrm{KN}]$ )

$$
d z^{\rho}\left(\nabla_{\partial_{z^{\sigma}}} \partial_{z^{\mu}}\right)=: \Gamma_{\sigma \mu}^{\rho}=g^{\rho \bar{\kappa}} \partial_{z^{\sigma}} g_{\mu \bar{\kappa}}
$$

and its complex conjugate. For the Riemann tensor $R(X, Y):=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-$ $\nabla_{[X, Y]} Z$ in holomorphic coordinates, we have (see e.g. [M], section 12.2, or [KN])

$$
d z^{\rho}\left(R\left(\partial_{z^{\mu}}, \partial_{z^{\bar{\nu}}}\right) \partial_{z^{\sigma}}\right)=: R_{\sigma \mu \bar{\nu}}^{\rho}=-\partial_{\bar{z}^{\nu}} \Gamma_{\sigma \mu}^{\rho}
$$

The other non-vanishing components $R^{\bar{\rho}}{ }_{\bar{\sigma} \mu \bar{\nu}}, R^{\rho}{ }_{\sigma \bar{\mu} \nu}$ and $R^{\bar{\rho}}{ }_{\bar{\sigma} \mu \nu}$ of the curvature tensor can be obtained from this via symmetry and complex conjugation.

[^2]Since the metric only depends on the imaginary part of $z=y+i x \in M$, we have

$$
\begin{aligned}
\partial_{z^{\sigma}} g_{\mu \bar{\kappa}} & =-\frac{i}{2} \partial_{x^{\sigma}}\left(-\frac{h_{\mu \kappa}}{4 h}+\frac{h_{\mu} h_{\kappa}}{4 h^{2}}\right) \\
& =-\frac{i}{2} \frac{1}{4 h^{3}}\left(-h^{2} h_{\mu \kappa \sigma}+h h_{\sigma} h_{\mu \kappa}+h h_{\kappa} h_{\mu \sigma}+h h_{\mu} h_{\kappa \sigma}-2 h_{\mu} h_{\kappa} h_{\sigma}\right),
\end{aligned}
$$

where the argument of $h$ and its derivatives is always $x$. This gives

$$
\begin{aligned}
\Gamma_{\sigma \mu}^{\rho}= & g^{\rho \kappa} \partial_{z^{\sigma}} g_{\mu \bar{\kappa}}=-\frac{i}{2}\left(-4 h h^{\rho \kappa}+\frac{4}{D-1} x^{\rho} x^{\kappa}\right) \\
& \cdot \frac{1}{4 h^{3}}\left(-h^{2} h_{\mu \kappa \sigma}+h h_{\sigma} h_{\mu \kappa}+h h_{\kappa} h_{\mu \sigma}+h h_{\mu} h_{\kappa \sigma}-2 h_{\mu} h_{\kappa} h_{\sigma}\right) \\
= & -\frac{i}{2 h^{3}}\left(h^{3} h^{\rho \kappa} h_{\kappa \mu \sigma}-h^{2} h_{\sigma} \delta_{\mu}^{\rho}-\frac{1}{D-1} h^{2} x^{\rho} h_{\mu \sigma}-h^{2} h_{\mu} \delta_{\sigma}^{\rho}+\frac{1}{D-1} 2 h x^{\rho} h_{\mu} h_{\sigma}\right. \\
& \left.-\frac{D-2}{D-1} h^{2} x^{\rho} h_{\mu \sigma}+h x^{\rho} h_{\sigma} h_{\mu}+\frac{D}{D-1} h^{2} x^{\rho} h_{\mu \sigma}+h x^{\rho} h_{\mu} h_{\sigma}-\frac{D}{D-1} 2 h x^{\rho} h_{\mu} h_{\sigma}\right) \\
= & -\frac{i}{2 h}\left(h h^{\rho \kappa} h_{\kappa \mu \sigma}-h_{\sigma} \delta_{\mu}^{\rho}-h_{\mu} \delta_{\sigma}^{\rho}+\frac{1}{D-1} x^{\rho} h_{\mu \sigma}\right),
\end{aligned}
$$

where for the third equality, we used $h^{\rho \kappa} h_{\kappa}=\frac{1}{D-1} x^{\rho}$. The curvature tensor is then found to be

$$
\begin{align*}
R_{\sigma \mu \bar{\nu}}^{\rho}=- & \frac{i}{2} \partial_{x^{\nu}} \Gamma_{\sigma \mu}^{\rho}=-\frac{1}{4 h}\left[-\frac{h_{\nu}}{h}\left(h h^{\rho \kappa} h_{\kappa \mu \sigma}-h_{\sigma} \delta_{\mu}^{\rho}-h_{\mu} \delta_{\sigma}^{\rho}+\frac{1}{D-1} x^{\rho} h_{\mu \sigma}\right)\right. \\
& +h_{\nu} h^{\rho \kappa} h_{\kappa \mu \sigma}-h h^{\rho \alpha} h_{\nu \alpha \beta} h^{\beta \kappa} h_{\kappa \mu \sigma}+h h^{\rho \kappa} h_{\kappa \mu \sigma \nu} \\
& \left.-h_{\sigma \nu} \delta_{\mu}^{\rho}-h_{\mu \nu} \delta_{\sigma}^{\rho}+\frac{1}{D-1} h_{\mu \sigma} \delta_{\nu}^{\rho}+\frac{1}{D-1} x^{\rho} h_{\mu \sigma \nu}\right] \\
=- & \frac{1}{4 h^{2}}\left[h^{2} h^{\rho \kappa} h_{\kappa \mu \sigma \nu}+\frac{1}{D-1} x^{\rho}\left(h h_{\mu \sigma \nu}-h_{\mu \sigma} h_{\nu}\right)+h_{\mu} h_{\nu} \delta_{\sigma}^{\rho}+h_{\sigma} h_{\nu} \delta_{\mu}^{\rho}\right. \\
& \left.-h\left(h_{\sigma \nu} \delta_{\mu}^{\rho}+h_{\mu \nu} \delta_{\sigma}^{\rho}-\frac{1}{D-1} h_{\mu \sigma} \delta_{\nu}^{\rho}\right)-h^{2} h^{\rho \alpha} h_{\nu \alpha \beta} h^{\beta \kappa} h_{\kappa \mu \sigma}\right], \tag{5.6}
\end{align*}
$$

where for the second equality, we used the formula $\frac{d}{d t} A^{-1}=-A^{-1} \frac{d A}{d t} A^{-1}$ for an invertible matrix $A$ that smoothly depends on a parameter $t$. Now, we contract the indices $\rho$ and $\mu$
in equation (5.6) to obtain the Ricci tensor:

$$
\begin{aligned}
\operatorname{Ric}_{\mu \bar{\nu}}= & R^{\rho}{ }_{\mu \rho \bar{\nu}}=-\frac{1}{4 h^{2}}\left[h^{2} h^{\rho \kappa} h_{\kappa \rho \mu \nu}+\frac{1}{D-1} x^{\rho}\left(h h_{\rho \mu \nu}-h_{\rho \mu} h_{\nu}\right)+h_{\rho} h_{\nu} \delta_{\mu}^{\rho}+h_{\mu} h_{\nu} \delta_{\rho}^{\rho}\right. \\
& \left.-h\left(h_{\mu \nu} \delta_{\rho}^{\rho}+h_{\rho \nu} \delta_{\mu}^{\rho}-\frac{1}{D-1} h_{\rho \mu} \delta_{\nu}^{\rho}\right)-h^{2} h^{\rho \alpha} h_{\nu \alpha \beta} h^{\beta \kappa} h_{\kappa \rho \mu}\right] \\
=- & \frac{1}{4 h^{2}}\left[h^{2} h^{\rho \kappa} h_{\kappa \rho \mu \nu}+\frac{1}{D-1}\left((D-2) h h_{\mu \nu}-(D-1) h_{\mu} h_{\nu}\right)+h_{\mu} h_{\nu}+m h_{\mu} h_{\nu}\right. \\
& \left.-h\left(m h_{\mu \nu}+h_{\mu \nu}-\frac{1}{D-1} h_{\mu \nu}\right)-h^{2} h^{\rho \alpha} h_{\nu \alpha \beta} h^{\beta \kappa} h_{\kappa \rho \mu}\right] \\
=- & m g_{\mu \bar{\nu}}+\frac{1}{4} h^{\rho \alpha} h_{\nu \alpha \beta} h^{\beta \kappa} h_{\kappa \rho \mu}-\frac{1}{4} h^{\rho \kappa} h_{\kappa \rho \mu \nu} .
\end{aligned}
$$

The scalar curvature for manifolds in the image of the generalized local r-map reads

$$
\begin{aligned}
s c a l & =g^{\mu \bar{\nu}} \operatorname{Ric}_{\mu \bar{\nu}}=\left(-4 h h^{\mu \nu}+\frac{4}{D-1} x^{\mu} x^{\nu}\right)\left(-m g_{\mu \bar{\nu}}+\frac{1}{4} h^{\rho \alpha} h_{\nu \alpha \beta} h^{\beta \kappa} h_{\kappa \rho \mu}-\frac{1}{4} h^{\rho \kappa} h_{\kappa \rho \mu \nu}\right) \\
& =-m^{2}-h h^{\rho \alpha} h_{\nu \alpha \beta} h^{\beta \kappa} h^{\mu \nu} h_{\kappa \rho \mu}+\frac{(D-2)^{2}}{D-1} \delta_{\beta}^{\rho} \delta_{\rho}^{\beta}+h h^{\rho \kappa} h_{\kappa \rho \mu \nu} h^{\mu \nu}-\frac{(D-3)(D-2)}{D-1} \delta_{\rho}^{\rho} \\
& =-m^{2}+\frac{D-2}{D-1} m-h h^{\rho \alpha} h_{\nu \alpha \beta} h^{\beta \kappa} h^{\mu \nu} h_{\kappa \rho \mu}+h h^{\rho \kappa} h_{\kappa \rho \mu \nu} h^{\mu \nu} .
\end{aligned}
$$

Remark 4 Note that in the derivation of these formulas, we did not use the fact that $D$ is positive, i.e. the theorem also holds for metrics of the form (5.1) with $h$ being a homogeneous function of degree $D<0$.

The curvature for projective very special Kähler manifolds, i.e. for manifolds in the image of the generalized supergravity r-map that are defined by a homogeneous cubic polynomial $h$ can be easily obtained from Theorem 3 by setting $D=3$ and dropping terms with quadruple derivatives of $h$.

For an arbitrary homogeneous function $h$, we also give the following alternative expression for Ric and scal:

Corollary 3 Let $M$ be a 2m-dimensional manifold in the image of the generalized supergravity r-map described by a homogeneous function $h$ of degree $D \in \mathbb{R}^{>0} \backslash\{1\}$. Then the Ricci tensor and the scalar curvature are given by

$$
\begin{equation*}
\operatorname{Ric}_{\mu \bar{\nu}}=-\partial_{z^{\mu}} \partial_{\bar{z}^{\nu}} \log \frac{d}{h^{m}}, \tag{5.7}
\end{equation*}
$$

$$
\begin{equation*}
\text { scal }=-m^{2}+\frac{D-2}{D-1} m-\frac{h}{d} d^{\mu}{ }_{\mu}+\frac{h}{d^{2}} d^{\mu} d_{\mu}, \tag{5.8}
\end{equation*}
$$

where $d(x):=\operatorname{det}\left(\partial^{2} h(x)\right)$.

Proof: Using $\frac{d}{d t}(\operatorname{det} A)=\operatorname{det} A \cdot \operatorname{tr}\left(A^{-1} \frac{d A}{d t}\right)$, we get

$$
\begin{aligned}
-\partial_{z^{\mu}} \partial_{\bar{z}^{\nu}} \log \frac{d}{h^{m}} & =m \cdot \partial_{z^{\mu}} \partial_{\bar{z}^{\nu}} \log h-\frac{1}{4} \frac{\partial^{2}}{\partial x^{\mu} \partial x^{\nu}} \log d=-m g_{\mu \bar{\nu}}-\frac{1}{4} \frac{\partial}{\partial x^{\mu}} \frac{d_{\nu}}{d} \\
& =-m g_{\mu \bar{\nu}}-\frac{1}{4} \frac{\partial}{\partial x^{\mu}}\left(h^{\alpha \beta} h_{\nu \alpha \beta}\right) \\
& =-m g_{\mu \bar{\nu}}+\frac{1}{4} h^{\alpha \rho} h_{\mu \rho \sigma} h^{\sigma \beta} h_{\nu \alpha \beta}-\frac{1}{4} h^{\alpha \beta} h_{\mu \nu \alpha \beta} \\
& \stackrel{(5.4)}{=} R i c_{\mu \bar{\nu}} .
\end{aligned}
$$

Since $h_{\mu \nu}$ are homogeneous of degree $D-2, d=\operatorname{det}\left(h_{\mu \nu}\right)$ is homogeneous of degree $m(D-2)$. Using this property and (5.2), we find

$$
\begin{aligned}
\text { scal }= & g^{\mu \bar{\nu}} \operatorname{Ric}_{\mu \bar{\nu}}= \\
& -m^{2}+\frac{h}{d} h^{\mu \nu} d_{\mu \nu}-\frac{h}{d^{2}} h^{\mu \nu} d_{\mu} d_{\nu} \\
& \quad-\frac{1}{D-1} m(D-2)(m(D-2)-1)+\frac{1}{D-1}(m(D-2))^{2} \\
= & -m^{2}+\frac{D-2}{D-1} m+\frac{h}{d} h^{\mu \nu} d_{\mu \nu}-\frac{h}{d^{2}} h^{\mu \nu} d_{\mu} d_{\nu}
\end{aligned}
$$

## 6 Classification of complete projective very special Kähler manifolds of complex dimension 3

In [CHM], it was shown that the supergravity r-map maps complete $n$-dimensional projective special real manifolds to complete projective special Kähler manifolds of complex dimension $m:=n+1$. Since there is a totally geodesic embedding of a projective special real manifold into the corresponding very special Kähler manifold, the image of an incomplete manifold under the r-map is incomplete. From the classification of all complete projective special real surfaces in Theorem [1, we thus immediately get the following corollary:

Corollary 4 The supergravity r-map assigns to each projective special real surface given in Theorem 1 a complete projective special Kähler 3-manifold and up to isometry, any complete projective special Kähler 3-manifold in the image of the r-map is obtained from one of the surfaces in Theorem 1 .

To classify all complete projective very special Kähler manifolds up to isometry, we want to show that the supergravity r-map maps the list of complete surfaces in Theorem 1 to a list of pairwise non-isometric manifolds.

Using the formula for the scalar curvature of manifolds in the image of the supergravity r-map given in Corollary 3, we obtain the following result:

Proposition 9 The five complete projective special Kähler manifolds in the image of the supergravity r-map obtained from the examples a)-e) in Theorem 1 are pairwise nonisometric.

Proof: Applied to the case of projective very special Kähler 3-manifolds, the formula for the scalar curvature given in Corollary 3 reads

$$
\begin{equation*}
\text { scal }=-\frac{15}{2}+\frac{h}{d} h^{\mu \nu} d_{\mu \nu}-\frac{h}{d^{2}} h^{\mu \nu} d_{\mu} d_{\nu} . \tag{6.1}
\end{equation*}
$$

We use it to determine the image of scal : $M \rightarrow \mathbb{R}$ for the five projective special Kähler manifolds in the image of the supergravity r-map obtained from the examples a)-e) in Theorem 1. $\operatorname{scal}(M)$ is pairwise different for the examples a)-e) and hence they are non-isometric.
a) Example a), the so-called STU model, is defined by

$$
h: U \rightarrow \mathbb{R},(x, y, z) \mapsto x y z \quad \text { with } \quad U=\left\{(x, y, z) \in \mathbb{R}^{3} \mid x>0, y>0, z>0\right\} .
$$

The corresponding manifold in the image of the r-map is the symmetric space $(S U(1,1) / U(1))^{3}$. Consequently, its scalar curvature is constant:

$$
d:=\operatorname{det} h_{\mu \nu}=2 h \quad \stackrel{(5.7)}{\Rightarrow} \quad \operatorname{Ric}_{\mu \bar{\nu}}=-2 g_{\mu \bar{\nu}} \quad \Rightarrow \quad \text { scal }=-6,
$$

i.e. the image of the scalar curvature is $\operatorname{scal}(M)=\{-6\}$.
b) This example is described by

$$
h: U \rightarrow \mathbb{R},(x, y, z) \mapsto x\left(x y-z^{2}\right) \quad \text { with } \quad U=\left\{(x, y, z) \in \mathbb{R}^{3} \mid x>0, y>\frac{z^{2}}{x}\right\}
$$

While the corresponding projective special real manifold is the symmetric space $S O(2,1) / S O(2)$, the corresponding projective special Kähler manifold obtained from the r-map is homogeneous but non-symmetric [DV1].
We have $\left(h^{\mu \nu}\right)=\frac{1}{2 x^{3}}\left(\begin{array}{ccc}0 & x^{2} & 0 \\ x^{2} & -z^{2}-x y & -x z \\ 0 & -x z & -x^{2}\end{array}\right)$ and with $d:=\operatorname{det}\left(h_{\mu \nu}\right)=8 x^{3}$, one finds $h^{\mu \nu} d_{\mu \nu}=0, h^{\mu \nu} d_{\mu} d_{\nu}=0$. (6.1) then gives $\operatorname{scal}(M)=\{-7.5\}$.
c) The so-called quantum STU model is defined by $h: U \rightarrow \mathbb{R},(x, y, z) \mapsto x y z+x^{3} \quad$ with $\quad U=\left\{(x, y, z) \in \mathbb{R}^{3} \mid x<0, z<0, y>-\frac{x^{2}}{z}\right\}$.

With $d=2 h-8 x^{3}$ and $h^{\mu \nu}=\frac{1}{d}\left(\begin{array}{ccc}-x^{2} & x y & x z \\ x y & -y^{2} & y z-6 x^{2} \\ x z & y z-6 x^{2} & -z^{2}\end{array}\right)$, we calculate

$$
h^{\mu \nu} d_{\mu \nu}=12 \cdot \frac{h}{d}, \quad h^{\mu \nu} d_{\mu} d_{\nu}=\frac{12}{d} \cdot\left[\left(x y z-5 x^{3}\right)^{2}-52 x^{6}\right] .
$$

The scalar curvature can be written as

$$
s c a l=-\frac{15}{2}+3 h \cdot\left(\frac{1}{d}+48 x^{3} \cdot \frac{h}{d^{3}}\right) .
$$

Using $d=2 h-8 x^{3}$, we can show that scal $>-\frac{15}{2}$ :

$$
\text { scal }>-\frac{15}{2} \stackrel{(h, d>0)}{\Leftrightarrow} d^{2}+48 x^{3} h>0 \Leftrightarrow\left(2 h+4 x^{3}\right)^{2}+48 x^{6}>0
$$

We also check that scal $<-6$ :

$$
\begin{aligned}
\text { scal }<-6 & \Leftrightarrow 3 h\left(\frac{1}{d}+48 x^{3} \frac{h}{d^{3}}\right)<\frac{3}{2} \\
& \stackrel{(d>0)}{\Leftrightarrow} 2 h\left(1+48 x^{3} \frac{h}{d^{2}}\right)<d=2 h-8 x^{3} \\
& \Leftrightarrow 2 \cdot 48 x^{3} h^{2}<-8 x^{3} d^{2}
\end{aligned} \stackrel{(x<0)}{\Leftrightarrow} 12 h^{2}+d^{2}>0 .
$$

To show that the bounds $-\frac{15}{2}<$ scal $<-6$ are optimal, we determine the behaviour of scal at the boundary $\partial U=\left\{y=-\frac{x^{2}}{z}, x<0, z<0\right\} \cup\{x=0, y \geq 0, z \leq 0\}$ : For $\partial U \cap\{x<0\}$, we have $\left.h\right|_{\partial U \cap\{x<0\}}=0,\left.d\right|_{\partial U \cap\{x<0\}}=-8 x^{3} \neq 0$ and hence

$$
\text { scal } \underset{x=x_{0}<0}{\stackrel{h \rightarrow 0}{\longrightarrow}}-\frac{15}{2} \text {. }
$$

For $\{x=0, y>0, z<0\} \subset \partial U \cap\{x=0\}$, we have

$$
\text { scal } \underset{y=y_{0}>0, z=z_{0}<0}{\stackrel{x \rightarrow 0}{2}} \frac{-15}{2}+\frac{3}{2}=-6 .
$$

Since $U$ is connected and scal is continuous, we have proven that

$$
\operatorname{scal}(M)=\left(-\frac{15}{2},-6\right)=(-7.5,-6)
$$

d) This example is described by
$h: U \rightarrow \mathbb{R},(x, y, z) \mapsto z\left(x^{2}+y^{2}-z^{2}\right)$ with $U=\left\{(x, y, z) \in \mathbb{R}^{3} \mid z<0, x^{2}+y^{2}<z^{2}\right\}$.

Using $d=-8\left(h+4 z^{3}\right)$ and $h^{\mu \nu}=\frac{-4}{d}\left(\begin{array}{ccc}y^{2}+3 z^{2} & -x y & x z \\ -x y & x^{2}+3 z^{2} & y z \\ x z & y z & -z^{2}\end{array}\right)$, we calculate

$$
h^{\mu \nu} d_{\mu \nu}=192 \cdot \frac{h}{d}, \quad h^{\mu \nu} d_{\mu} d_{\nu}=12 d+4 \cdot 96 z^{3}+4 \cdot 96^{2} z^{6} \frac{1}{d} .
$$

The scalar curvature can be written as

$$
\text { scal }=-\frac{15}{2}-12 h \cdot\left(\frac{1}{d}-16 \cdot 48 z^{3} \cdot \frac{h}{d^{3}}\right) .
$$

We show that scal $<-\frac{15}{2}$ :

$$
\mathrm{scal}<-\frac{15}{2} \stackrel{(h, d>0)}{\Leftrightarrow} d^{2}-16 \cdot 48 z^{3} h>0 \quad \Leftrightarrow \quad\left(h-2 z^{3}\right)^{2}+12 z^{6}>0 .
$$

This bound is assumed at the boundary of $U$ :

$$
\lim _{p \rightarrow p_{0}} \operatorname{scal}_{p}=-\frac{15}{2} \quad \forall p_{0} \in \partial U \backslash\{0\} .
$$

At $(x, y, z)=(0,0,-1) \in U$, we have $\operatorname{scal}(0,0,-1)=-8-\frac{2}{3}$. To show that $-8-\frac{2}{3}$ is a lower bound for the scalar curvature, we show $-\frac{12 h}{d} \geq-\frac{1}{2}$ and $12 \cdot 16 \cdot 48 \frac{z^{3} h}{d^{3}} \geq-\frac{2}{3}$ :

$$
\begin{aligned}
&-\frac{12 h}{d} \geq-\frac{1}{2} \stackrel{(d>0)}{\Leftrightarrow} 0 \geq-d+24 h \quad \Leftrightarrow \quad 0 \geq h+z^{3} \quad \stackrel{(z<0)}{\Leftrightarrow} 0 \leq x^{2}+y^{2}, \\
& 12 \cdot 16 \cdot 48 \frac{z^{3} h}{d^{3}} \geq-\frac{2}{3} \Leftrightarrow 27 z^{3} h^{2} \geq\left(h+4 z^{3}\right)^{3} \\
& \Leftrightarrow 27 z^{5}\left(x^{2}+y^{2}-z^{2}\right)^{2} \geq z^{3}\left(x^{2}+y^{2}+3 z^{2}\right)^{3} \\
& \Leftrightarrow 0 \leq\left(x^{2}+y^{2}\right)^{3}-18\left(x^{2}+y^{2}\right)^{2} z^{2}+81\left(x^{2}+y^{2}\right) z^{4} \\
& \Leftrightarrow 0 \leq\left(x^{2}+y^{2}\right)\left(x^{2}+y^{2}-9 z^{2}\right)^{2} .
\end{aligned}
$$

We have thus proven that

$$
\operatorname{scal}(M)=\left[-8-\frac{2}{3},-\frac{15}{2}\right)=[-8 . \overline{6},-7.5)
$$

e) This example is described by
$h: U \rightarrow \mathbb{R},(x, y, z) \mapsto x\left(y^{2}-z^{2}\right)+y^{3}$ with $U=\left\{(x, y, z) \in \mathbb{R}^{3} \mid y<0, x>0, h>0\right\}$.
One has $d=8\left(x\left(y^{2}-z^{2}\right)-3 y z^{2}\right)$ and $h^{\mu \nu}=\frac{4}{d}\left(\begin{array}{ccc}-x(x+3 y) & x y & (x+3 y) z \\ x y & -z^{2} & -y z \\ (x+3 y) z & -y z & -y^{2}\end{array}\right)$.
Then $h^{\mu \nu} d_{\mu \nu}=192 \frac{h}{d}$ and
$h^{\mu \nu} d_{\mu} d_{\nu}=4 \cdot \frac{64}{d}\left[3 x^{2} y^{4}-6 x^{2} y^{2} z^{2}+3 x^{2} z^{4}-3 x y^{5}-24 x y^{3} z^{2}+27 x y z^{4}-72 y^{4} z^{2}-9 z^{6}\right]$.

The scalar curvature can be witten as

$$
\begin{aligned}
\text { scal }=- & \frac{15}{2}+192 \cdot \frac{h^{2}}{d^{2}}-12 \cdot 64 \cdot \frac{h}{d^{3}}\left[x(x-y) y^{4}\right. \\
& \left.-2 y^{2} z^{2}\left((x+2 y)^{2}+8 y^{2}\right)+x(x+9 y) z^{4}-3 z^{6}\right] .
\end{aligned}
$$

Since scal only contains even powers of $z$, we have $\left.\frac{\partial s c a l}{\partial z}\right|_{z=0}=0$. We restrict ourselves to the hypersurface $M \cap\{z=0\} \subset M$ and determine $\operatorname{scal}(M \cap\{z=0\})$.

$$
\operatorname{scal}(x, y, 0)=-6+\frac{12 x y+9 y^{2}}{2 x^{2}}
$$

has critical points only for $y=-\frac{2}{3} x$, where it assumes the value -8 :

$$
\partial_{y} \operatorname{scal}(x, y, 0)=\frac{6 x+9 y}{x^{2}}, \quad \partial_{x} \operatorname{scal}(x, y, 0)=-y \frac{6 x+9 y}{x^{3}} ; \quad \operatorname{scal}\left(x,-\frac{2}{3} x, 0\right)=-8 .
$$

Since scal is homogeneous of degree zero, it suffices to consider the image of

$$
(-1,0) \rightarrow \mathbb{R}, \quad y \mapsto \operatorname{scal}(1, y, 0)
$$

At the boundaries $y=-1$ and $y=0$ of $U \cap\{x=1, z=0\}$, we have

$$
\lim _{y \rightarrow-1} \operatorname{scal}(1, y, 0)=-7.5 \quad \text { and } \quad \lim _{y \rightarrow 0} \operatorname{scal}(1, y, 0)=-6
$$

This shows that $\operatorname{scal}(M \cap\{z=0\})=[-8,-6)$. In particular, we have

$$
[-8,-6) \subset \operatorname{scal}(M)
$$

Remark 5 Note that the results obtained in the proof of the above proposition show that the complete projective special Kähler manifolds obtained from examples $c$ ), $d$ ) and $e)$ in Theorem 1 via the supergravity r-map have non-constant scalar curvature and, hence, are not locally homogeneous.

Using the formula for the scalar curvature in Corollary 3, one can similarly show that all manifolds in the one-parameter family of complete projective special Kähler manifolds obtained from Weierstraß cubic polynomials (see example $f$ ) in Theorem (1) are not locally homogeneous. This one-parameter family is particularly interesting, since using the supergravity c-map, which maps complete projective special Kähler manifolds to complete quaternionic Kähler manifolds [CHM, it gives an explicit expression for a one-parameter family of complete quaternionic Kähler metrics.

Remark 6 For the one-parameter family of complete projective very special Kähler manifolds defined by Weierstraß polynomials (see Example f) in Theorem (1), we obtain the following results using numerical methods:

$$
\operatorname{scal}(M)= \begin{cases}{\left[s_{\min }(b), s_{\max }(b)\right]} & \text { for }-1<b<0 \\ {\left[s_{\min }(b),-7.5\right)} & \text { for } 0 \leq b<1,\end{cases}
$$

where $s_{\max }:(-1,0) \xrightarrow{\sim}(-7.5,-6)$ and $s_{\text {min }}:(-1,1) \xrightarrow{\sim}(-8 . \overline{6},-8)$ are strictly decreasing. This shows that all manifolds in the image of the supergravity r-map obtained from the examples in Theorem 1 are non-isometric and hence it finishes the classification of all complete projective very special Kähler 3-manifolds.

Remark 7 There exist precisely two complete projective special real curves, up to linear equivalence CHM: $\mathcal{H}_{\text {hom. }}:=\left\{(x, y) \in \mathbb{R}^{2} \mid x^{2} y=1, x>0\right\}$ and $\mathcal{H}_{\text {inh. }}:=\{(x, y) \in$ $\left.\mathbb{R}^{2} \mid x\left(x^{2}-y^{2}\right)=1, x>0\right\}$, where $\mathcal{H}_{\text {hom }}$. admits a transitive group of linear transformations, while $\mathcal{H}_{\text {inh. }}$ is inhomogeneous.

One can show using the curvature formulas in Theorem 3 that the projective special Kähler manifold $M_{\text {hom. }}$ obtained from $\mathcal{H}_{\text {hom }}$. via the supergravity r-map is a product of two complex hyperbolic lines with different curvature, which is well-known from the physics literature (see e.g. [DV2]). On the other hand, the projective special Kähler manifold $M_{\text {inh. }}$ corresponding to $\mathcal{H}_{\text {inh. }}$. has non-constant scalar curvature and hence, it is not locally homogeneous.

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[^0]:    ${ }^{1}$ This can be shown using the relation between the roots of a quartic polynomial and the roots of its cubic resolvent (see e.g. [I], section 10.5). The cubic resolvent $s(z)=z^{3}-3 z^{2}+3 z-b^{2}=(z-1)^{3}+3-b^{2}$ of $g(x)$ has only one real root. This implies that $g(x)$ has two real roots.

[^1]:    ${ }^{2}$ Note that one can extend this definition to $D<0$. For $D<0$, we then get a different signature for $g_{M}$ compared to the conventions in CHM.
    ${ }^{3}$ Note that $g_{M}$ differs from the metric in CHM by a conventional factor: $g_{M}^{[C H M]}=\frac{3}{2 D} g_{M}$.

[^2]:    ${ }^{4}$ This has been found by specializing the formula for the inverse of projective special Kähler metrics in [C-G] to projective very special Kähler metrics $(D=3)$ and then generalizing this to metrics of the form (5.1) defined by arbitrary homogeneous functions $h$.
    ${ }^{5}$ We define the scalar curvature scal for Kähler manifolds to be one half of the trace of Ric, i.e. scal $:=$ $g^{\mu \bar{\nu}}$ Ric $_{\mu \bar{\nu}}$. Compared to the standard definition $s c a l_{\mathbb{R}}:=\operatorname{tr}$ Ric of the scalar curvature in differential geometric literature, we thus have $s c a l_{\mathbb{R}}=2 s c a l$.

